ABB drives

User's manual Start-up and maintenance PC tool Drive composer

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File Edit View Help!				A7	AAA	
C ACS880	OC IEM Network Start Stop Coast stop Reference :				<u>~ ~ ~</u>	ABB i R
	ACS880 Filter Not at default Index Name Value Index	Refresh log Drive ACS880 {0}.{0} ACS880 {0}.{0} ACS880 {0}.{0}	Icon Time Fault ▲ 13.01.2013 22:49:41.979 AFEB ▲ 13.01.2013 22:49:31.165 AFEB ▲ 13.01.2013 22:49:31.165 AFEB ▲ 13.01.2013 22:49:31.165 AFEB ▲ 13.01.2013 22:49:31.165 AFEB ● 13.01.2013 22:49:31.165 AFEB ● 13.01.2013 22:49:31.165 AFEB ● 13.01.2013 22:49:31.165 OFEB ● 13.01.2013 22:49:15:570 AFEB ● ACS880 ACS880	Run enable missing Run enable missing		
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List of related manuals

Drive firmware manuals and guides	Code (English)
ACS880 primary control program firmware manual	3AUA0000085967
ACS580-01 user's manual	3AUA0000076333
Option manuals and guides	
FENA-01/-11/-21 Ethernet adapter module user's manual	3AUA0000093568
FSO-11 safety functions module user's manual	3AUA0000097054
FSO-12 safety functions module user's manual	3AXD50000015612
FPBA-01 PROFIBUS DP adapter module user's manual	3AFE68573271
Tool manuals	
Drive composer start-up and maintenance PC tool user's manual	3AUA0000094606
Ethernet tool network for ACS880 drives application guide	3AUA0000125635

All manuals are available in PDF format on the Internet. See section *Document library on the Internet* on the inside of the back cover.

User's manual

Start-up and maintenance PC tool Drive composer

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3AUA0000094606 F EN EFFECTIVE: 2014-06-04

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Introduction to the manual

Contents of this chapter

This chapter contains information on the applicability, compatibility, target audience and the purpose of the manual. It also describes the contents of the manual.

Applicability

This manual applies to the Drive composer PC tool available in two different versions:

- Drive composer entry, DCET-01
- Drive composer pro, DCPT-01 (code: 3AUA0000108087).

Drive composer entry can be downloaded for free by navigating to <u>www.abb.com/drives</u> and selecting *Drive PC Tools*. Drive composer pro includes all features and is available through ABB sales channels. Both versions require registration.

Note: The features available only with Drive composer pro are indicated with (pro).

Compatibility

Drive composer is fully compatible with ACS580 and ACS880 drive families. Availability of some functions are dependent on capabilities of the drive and possibly added modules. There is a limited support (parameter editing and monitoring) for ACS800. It requires DriveWindow 2 installation on the same PC.

Target audience

The reader is expected to be an automation engineering professional or an electrician and familiar with drive products and the concepts regarding their commissioning and operation, including the parameter system of ABB drives. Also a basic knowledge of Microsoft Windows operating system is needed.

Purpose of the manual

This manual describes the Drive composer PC tool and instructs how to use it in the commissioning and maintenance of the ABB drives.

Contents

The manual consists of the following chapters:

- *Introduction to the manual* provides information on the applicability, compatibility, target audience and the purpose of the manual.
- Overview of Drive composer briefly lists the main features of the Drive composer software and instructs how and where it can be run, and how to get help and additional information.
- *Installation and uninstallation of Drive composer* describes how to install and uninstall the Drive composer software.
- *Connections* describes how to make a connection with a drive through USB or Ethernet.
- *Main user interface components* describes the main user interface components of the Drive composer PC tool, including the menus.
- Parameter window describes how to use the parameter window.
- Monitor window describes how to use the monitor window.
- Workspace handling describes the workspace functionality.
- Event logger describes how to use the event logger.
- *Diagnostics* describes how to troubleshoot a drive with the **Support package** button of Drive composer and the data logger included in the drive.
- Control diagrams (pro) describes how to use the control diagrams.
- *FSO configuration* contains the configuration procedure of the FSO-11 and FSO-12 safety functions with Drive composer pro and provides an example of how to configure the optional FSO-11 and FSO-12 safety functions module.
- Other functions (pro) describes functions that are common to many views, windows and functions that are not associated with any view or window.

Terms and abbreviations used in this manual

Term or abbreviation	Explanation
Alarm limit of monitoring	You can set a low or high alarm limit for monitoring. Color(s) of the signal(s) change(s) on the monitoring graph area if the limit is reached.
Assistant	Provides predefined steps for setting the parameters of the drive. For example, the basic start-up assistant.
Assistant control panel	Control panel with an USB connector enabling a PC tool connection for common architecture drives. Assistant control panel is a generic name for ACS-AP-I and ACS-AP-S panels.
Autoscaling	Y-axis scaling is set automatically when this button is enabled. User-defined y- axis limits are then disabled. Note: Zooming is not possible in the Autoscaling mode.
Backup	Backup of the drive. Includes all parameters, application program, user sets. ACS880 memory unit consists of FW and all the files that belongs to backup. Primary method to replace a broken drive control board is to use the memory unit from the old one. Note: Backup does not include the firmware of the drive.
Basic control panel	Control panel with limited basic functionality used with common architecture drives.
Bit mask of monitoring	You can filter bits of the Status word and monitor them individually.
Common architecture drives	For example, ACS880 and ACS580.
Compare parameters	You can compare parameters between drives or between a drive and a file to find out differences.
Control diagrams	Graphical presentation of the drive reference chain or other function. Shows online values of a parameter, switch positions and signals. Parameters can be modified online. Functionality is not available for all drives.
Copy/Download parameters	Visible parameters of a parameter window or custom parameter window are copied/downloaded to a drive.
Cursor tool	Monitor window has a double cursor tool and the positions of cursors can be freely set in the monitor window. y2—y1 and x2—x1 differences are calculated.
Custom parameter window	You can create windows and drag drop (copy) parameters to these windows. You can also change parameter values in the window and save the changes for using in offline mode. The Filename extension for custom parameters is *.dccustparams.
Data file viewer	In the Demo/Offline mode, the monitor window can be used as a data file viewer when saved monitored data (*.dcmon) or data logger data is analyzed.
Data logger	Signals are buffered inside a drive with a fast sample interval. Can be triggered and uploaded to the monitor window to be analyzed.
Demo/Offline	You can set/view saved parameter files offline. Demo mode can be used for monitoring and testing functionality of parameters.
DriveAP	Adaptive Programming of a drive. Functionality of a drive can be modified by adding some IEC 61131 -based blocks. Adaptive Programming can be done also with an Assistant control panel.
	Note: Adaptive Programming is not available with all drives.
Event logger	Can consist of faults, alarms and events. Only faults stop the drive. Latest faults and alarms are also seen in parameter interface group 4, Warnings and Faults.

12 Introduction to the manual

Term or abbreviation	Explanation
FENA-11	Ethernet adapter module for ABB drives.
LOC/REM	LOC denotes local control of the drive, either with an Assistant control panel or the Drive composer PC tool. REM means that the drive is remotely controlled by the fieldbus master PLC or by I/O connections.
Lock/Unlock parameter	Parameter can be locked by a drive. You can only view the parameter values, but cannot modify them.
Macro script	User-written sequence of macro statements for reading and writing parameters/signals. Filename extension for macro scripts is *.p.
Monitoring	You can set parameters or signals to the monitor window. Values are collected with the sampling interval and drawn to a window.
NLS support	National Language Support, the user interface (UI) of Drive composer can be easily modified by editing language files found in the LANG folder of the Drive composer PC tool.
Online/Offline	Online = PC tool is connected with the drive. Offline = PC tool is not connected with the drive. In the Offline mode it is possible to open parameter files, save monitored data etc.
OPC server	OPC DA server interface for Drive composer pro that allows other programs, such as Control Builder Pro (Advanced drive programming), to communicate with the drive.
Refresh the parameter	Parameter values are updated when a group is opened. You can set parameters to the Auto-update mode or refresh the value manually. Signals are always updated automatically. Signals are bolded in the parameter list.
Report	You can use report templates for energy savings, commissioning and maintenance. Templates can be modified.
Restore	You can restore the drive. You can select the parameters to be restored during the restore operation. For example, motor identification run results can be restored or deleted during the restore operation. Can be used for cloning drives.
Save parameters	Visible parameters of a parameter window or custom parameter window are saved to a file. Filename extension for saved parameters is *.dcparamsbak. Note: Some values are not editable in the Offline mode.
Support diagnostics package	You can collect all data from a drive for troubleshooting purposes by clicking a button in Drive composer or on an Assistant control panel.
Workspace	Workspace consists of the user interface status, such as parameters shown in the custom parameter window(s) and their status. You can save the current workspace status to a file and restore it later. Custom parameter windows with their contents and the monitor window contents (signals selected, scalings, colors) are saved to a workspace. You can set one default workspace. Filename extension for the workspace is *.dcxml.



Overview of Drive composer

Contents of this chapter

This chapter briefly lists the main features of the Drive composer software and instructs how and where it can be run, and how to get help and additional information.

Drive composer

Drive composer is a 32-bit Windows application for commissioning and maintaining ABB common architecture drives.

The full version is called Drive composer pro and the limited version is called Drive composer entry.

Both versions include a demo that allows testing user interface functionality, edit parameter files offline (pro) or open and analyze saved monitored files without connecting to a physical drive.

14 Overview of Drive composer

Highlights

With Drive composer, it is possible to:

- control a drive: start, stop, direction, speed/torque/frequency reference
- monitor the operation and status of a drive
- view and adjust drive parameters
- monitor signals in numerical and graphical (trending) format
- work simultaneously with multiple drives like master and follower drives (pro)
- display control diagrams of a drive for parameter setting and diagnostic purposes (pro)
- create user-specific workspaces by customizing parameter windows
- configure the optional FSO-11 and FSO-12 safety functions module (pro)
- handle workspaces
- create and execute macro scripts (pro)
- use Ethernet-based fieldbus adapter modules for PC tool communication (one-wire solution, Profinet, Ethernet IP) (pro) or a drive-embedded Ethernet port
- use the USB port of an Assistant control panel for an USB connection
- use an OPC-based commissioning and maintenance tool (pro).

Features

Feature	Drive composer entry	Drive composer pro
Parameters can be modified	Yes	Yes
Parameters can be searched	Yes	Yes
Parameters changed by the user (or automatically updated) have an orange background	Yes	Yes
Parameters can be saved to a file	Yes	Yes
Parameters can be copied/downloaded to a drive	Yes	Yes
Parameter windows can be customized	Yes	Yes
Parameters can be printed	No	Yes
Parameters can be edited offline	No	Yes
Parameters can be compared between parameter lists or drives	No	Yes
Data for the support service can be collected by clicking the Support package icon	Yes	Yes
As a simple monitoring method for basic purposes, signals can be monitored slowly, 2 signals per second	Yes	Yes
Monitored data can be saved to a hard drive of a PC	Yes	Yes
Monitored data can be exported to a PC by using the tab separated file	Yes	Yes
For a professional analysis of a single drive or multidrives, max 32 signals can be monitored and 8 of them can be monitored fast	No	Yes
Contents of an event logger (faults, warnings) can be viewed	Partly	Yes
Contents of the System info (drive serial number, modules, versions, SW etc.) can be viewed	Yes	Yes
Full backup/restore can be used for restoring or cloning a drive	No	Yes
Full backup/restore of multidrives can be used for restoring or cloning in a network of drives	No	Yes
PC can be used to analyze the data logged in a drive by a data logger	No	Yes
Macro scripts can be created and executed	No	Yes
Safety settings can be configured to a safety functions module (FSO)	No	Yes
Point-to-point USB can be connected through a panel port	Yes	Yes
Network drives can be connected via Ethernet or with a panelbus	No	Yes
Control diagrams of a drive can be used for parameter setting and diagnostic purposes	No	Yes
User interface is available in different languages	Yes	Yes

Hardware and software requirements

Drive composer hardware

- USB type A (PC) type mini B (panel) cable for connecting Drive composer entry/pro through the USB port of the control panel to a drive (max 3 m)
 Note: We recommend ferrite core cables.
- Ethernet cable RJ45 if the connection is made through the FENA-11 or embedded Ethernet

Computer hardware

- IBM compatible PC
- Pentium 2000 MHz or a faster processor (Dual-core or better recommended)
- 1GB RAM
- 1024 x 600 display resolution with 256 colors
- At least 150 MB free hard disk space
- CD drive
- One free USB port or Ethernet port

Software

- Operating system Windows XP, Vista, Windows 7 or Windows 8 (32- or 64-bit operating system)
- Microsoft.NET Framework 4.5.1 is required for Windows 7/Windows 8 or 4.0.3 for Windows XP.

Note: Update the latest version of Microsoft.NET Framework on your PC.



Installation and uninstallation of Drive composer

Contents of this chapter

This chapter describes how to install and uninstall the Drive composer software. Drive composer entry can be taken into use without the installer program.

Determining the current Drive composer version

To know the version of the Drive composer PC tool, select **About the product** in the **Help** menu. The **About the product** dialog box displays the Drive composer version.



Figure 1. About the product dialog box

Using Drive composer entry without the installer

Read the license agreement (License.pdf from the downloaded package of Drive composer entry).

To obtain Drive composer entry without using the installer program:

- 1. Copy the installation files to your PC.
- 2. Install the Assistant control panel PC drivers as instructed in chapter Connections.

Note: You must have administrator rights to install Assistant control panel PC drives.

 Install Microsoft.NET Framework 4.5.1 for Windows 7/Windows 8 or 4.0.3 for Windows XP on your PC.

To remove Drive composer entry from your PC, delete all files that are in the folder where you unzipped the Drive composer entry files.

Note: Before deleting all files make sure you do not have your own files. For example, saved parameter files, workplaces or saved custom parameter windows in the folder structure of Drive composer entry PC tool.

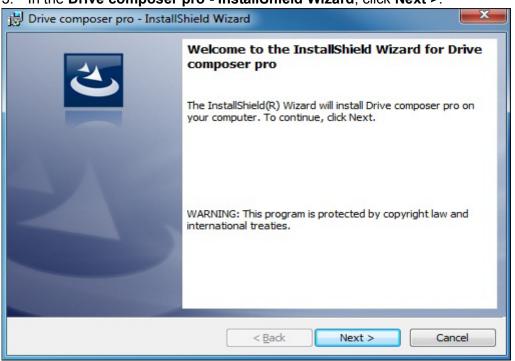
Installing Drive composer with the installer

It is recommended to uninstall all previous versions of Drive composer before installing a new version. Close all applications before starting the installation.

- 1. Run the *setup.exe* file from the folder where you unzipped the Drive composer files.
- 2. With Windows 7, right-click on the *setup.exe* file and select **Run as administrator**.



Figure 2. Run as administrator



3. In the Drive composer pro - InstallShield Wizard, click Next >.

Figure 3. Drive composer 1.5.0.1 setup wizard window

4. Choose the destination folder and click Next >.

🛃 Drive co	mposer pro - InstallShield Wizard	×
	ion Folder xt to install to this folder, or click Change to install to a different folder.	2
Ø	Install Drive composer pro to: C:\Program Files\DriveWare\Drive composer pro\	<u>C</u> hange
InstallShield -	< <u>B</u> ack Next >	Cancel

Figure 4. Destination folder window

5. Click **Install** to start the installation.

ttings, click Back. Click Cancel to

Figure 5. Installation

If Drive composer installation is complete, click **Finish**. Now the Drive composer is ready for use.

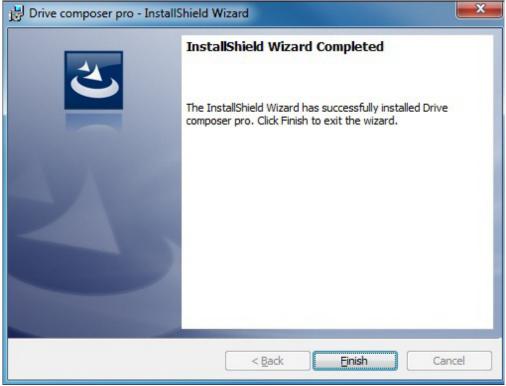


Figure 6. Installation Complete window

Uninstalling Drive composer with the installer

1. In the **Control panel** -> **Programs** -> **Program and features** window, select the installed Drive composer pro program and click **Uninstall**.

<u>File Edit View Tools Hel</u>		ch Programs and Features	
Control Panel Home View installed updates	Uninstall or change a pro		
Turn Windows features on or off	To uninstall a program, select it from the list and then click Uninstall, Change, or Repair.		
Install a program from the	Organize 🔻 Uninstall Repair	:= ▼	2
network	Name	Publisher	
	DHTML Editing Component	Microsoft Corporation	
	🔂 Drive composer pro	ABB Oy Helsinki Finland	
	ECL Viewer GIA IBM Tivoli Remote Control - Tar Intel(R) Network Connections 1 Intel® Control Center	SAP AG T-Online IBM United Kingdom Ltd. Intel Intel Corporation	
	< III.		Þ

Figure 7. Removing Drive composer

2. Click Yes to uninstall Drive composer pro application.



Figure 8. Confirming the removal of Drive composer



Connections

Contents of this chapter

This chapter describes how to make a USB connection or an Ethernet connection to an ABB drive with Drive composer.

Assistant control panel drivers

An Assistant control panel (ACS-AP-x panel) cannot be used with a PC until the drivers have been installed. If Drive composer entry is used without the installer program, the drivers must be installed separately as instructed below.

Copy the drivers to the installation folder of Drive composer entry (by default C:\Program Files\DriveWare) or to the user-changed installation path.

You can also find the drivers from the Drive composer entry.zip file that can be downloaded from <u>www.abb.com/drives</u> and selecting *Drive PC Tools*.

Note: You must have administrator rights to install the drivers.

Installing Assistant control panel drivers for a Windows XP PC

1. Connect the Assistant control panel to your PC. The following dialog box appears.

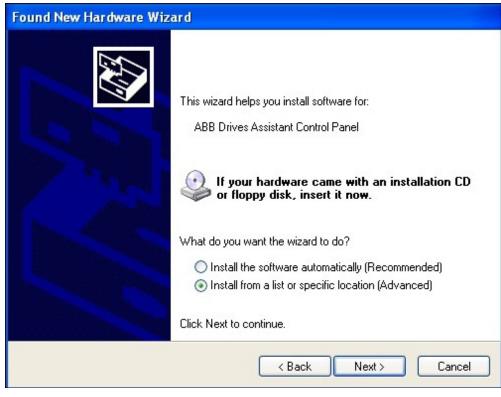
Found New Hardware Wiz	ard
	Welcome to the Found New Hardware Wizard Windows will search for current and updated software by looking on your computer, on the hardware installation CD, or on the Windows Update Web site (with your permission). Read our privacy policy
	Can Windows connect to Windows Update to search for software? Yes, this time only Yes, now and every time I connect a device No, not this time
	Click Next to continue.
	< Back Next > Cancel

Figure 9. Welcome to the Found New Hardware Wizard dialog box

2. Select No, not this time and click Next.

Found New Hardware Wizard		
	Welcome to the Found New Hardware Wizard Windows will search for current and updated software by looking on your computer, on the hardware installation CD, or on the Windows Update Web site (with your permission). Read our privacy policy	
	Can Windows connect to Windows Update to search for software? Yes, this time only Yes, now and <u>every time I connect a device</u> No, not this time	
	Click Next to continue.	
	< <u>B</u> ack <u>N</u> ext > Cancel	

Figure 10. Hardware wizard window



3. Select Install from a list or specific location (Advanced) and click Next.

Figure 11. Install from a list or specific location (Advanced)

4. Browse to locate the installed files. Normally the location is C:\Program files\DriveWare\Drive composer entry tool\Panel inf files.

Found New Hardware Wizard
Please choose your search and installation options.
Search for the best driver in these locations.
Use the check boxes below to limit or expand the default search, which includes local paths and removable media. The best driver found will be installed.
Search removable media (floppy, CD-ROM)
✓ Include this location in the search:
Browse
O Don't search. I will choose the driver to install.
Choose this option to select the device driver from a list. Windows does not guarantee that the driver you choose will be the best match for your hardware.
< <u>B</u> ack <u>N</u> ext > Cancel

Figure 12. Search and installation options selected

5. Click Next.

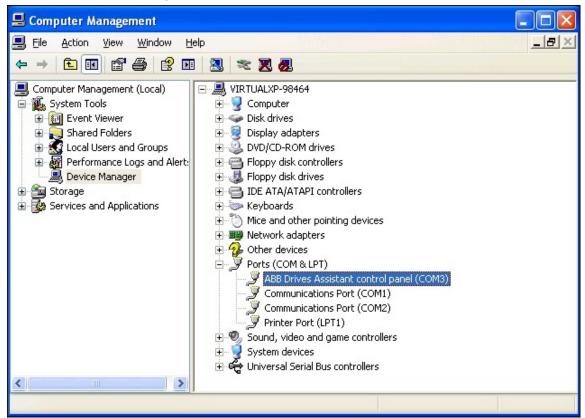
Found New Hardware Wizard	
Please wait while the wizard installs the	e software
ABB Drives Assistant control pan	el
Setting a system restore poin case your system needs to b	t and backing up old files in
Case your system needs to b	< Back Next > Cancel

Figure 13. ABB Drives Assistant control panel dialog box

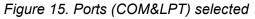
- 6. After the installation, click **Finish**.
- 7. To check the COM port number, right-click **My computer** on the desktop and select **Manage**.



Figure 14. COM port number check



8. Select Device Manager and click Ports (COM & LPT).



For example, the Assistant control panel uses COM3 on this PC.

Note: After installing the drivers, always use the same USB port when connecting the Assistant control panel with Drive composer entry. If the used USB port is changed, the COM port must be changed accordingly. Drive composer pro scans all COM ports.

Installing Assistant control panel drivers for a Windows 7 PC

1. Connect the Assistant control panel to your PC.

The first part of drivers are installed automatically and the following window appears. The Assistant control panel can be used as a USB device.

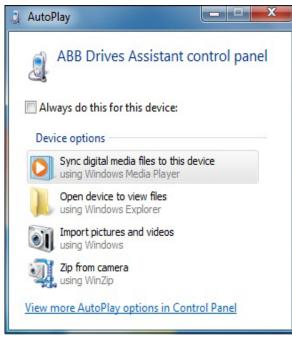


Figure 16. AutoPlay window

- 2. Install the second part of drivers manually as follows (after the installation of the second part of drivers has failed) (Drive composer entry).
- 3. In the Start menu of your computer, enter Device manager in the search field and click Device Manager.

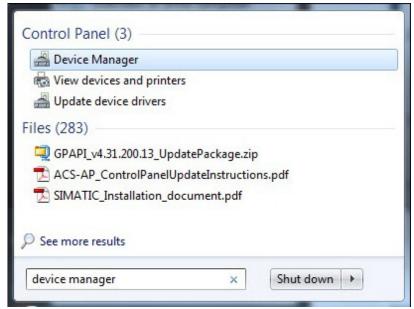


Figure 17. Device Manager

4. Expand **Ports**. Right-click **ABB Drives Assistant Control Panel** and select **Update Driver Software...**.

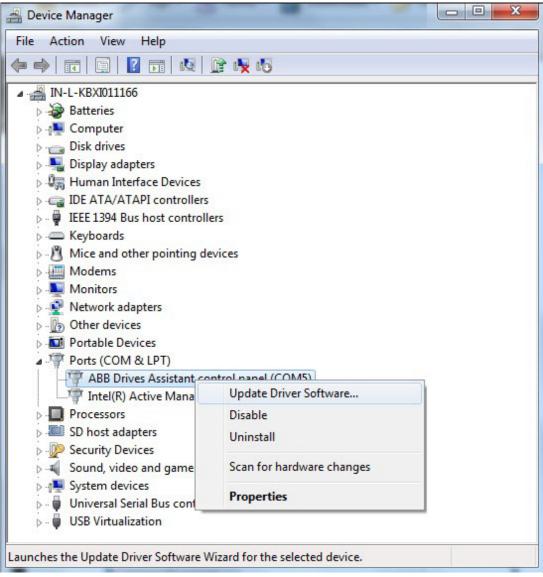


Figure 18. Update Driver Software selected

30 Connections

5. Click Browse my computer for driver software to search the driver software.

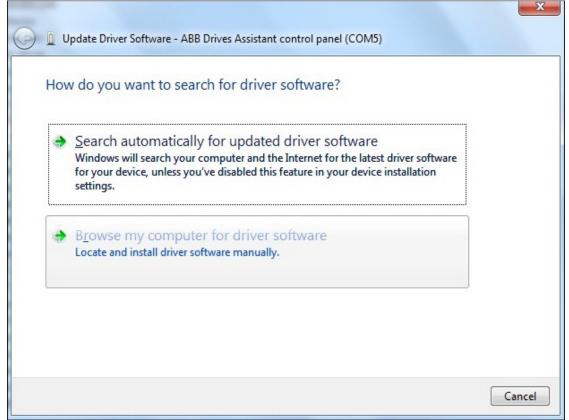


Figure 19. Search for the driver software

6. Click **Browse** to locate the drivers and click **Next**.



Figure 20. Browse for the driver software

7. In the Windows Security window, click Install to install the device software.

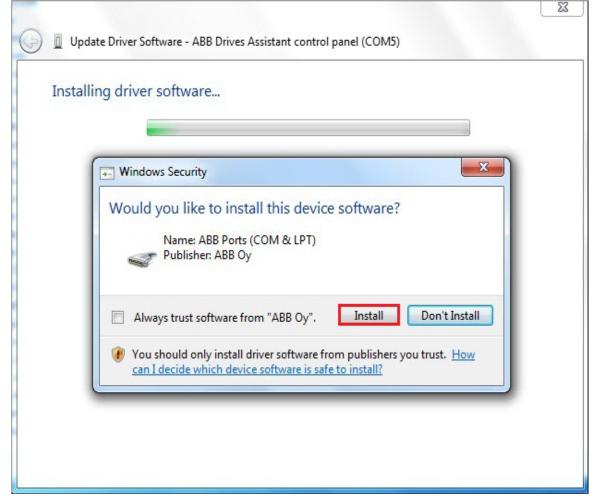


Figure 21. Windows Security message

After installation is complete, click Close.



Figure 22. Driver software successfully installed

32 Connections

The Driver software for the device is installed.

🚔 Device Manager	×
<u>File Action View H</u> elp	
⊿ 🛁 IN-L-KBXI011166	*
> 🍃 Batteries	
⊳ - 🖳 Computer	
🗅 🧫 Disk drives	
Display adapters	
Human Interface Devices	
D IDE ATA/ATAPI controllers	
🔈 – 🚆 IEEE 1394 Bus host controllers	
Keyboards	=
Mice and other pointing devices	
Modems	
Monitors	
Network adapters	
📲 11b/g/n Wireless LAN Mini-PCI Express Adapter II	
Cisco Systems VPN Adapter	
Intel(R) 82577LM Gigabit Network Connection	
Other devices	
Portable Devices	
Ports (COM & LPT)	
ABB Drives Assistant control panel (COM5)	
Intel(R) Active Management Technology - SOL (COM3)	
Processors	*

Figure 23. COM port number

Note: Install the drivers onto the USB port where you want to use the Assistant control panel again.

Connecting to a drive with an Assistant control panel for the first time

To establish a connection between Drive composer and drive, connect a USB type A (PC) type mini B (panel) cable to the USB port of the computer and the USB port of the Assistant control panel (ACS-AP-x panel). The maximum length of the USB cable should be 3 m. If the drive is used without an Assistant control panel or with a Basic control panel, use separate USB/485 adapter to establish connection between Drive composer and drive.

1. Connect your PC to the Assistant control panel with a USB cable.

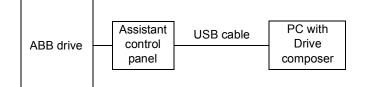


Figure 24. USB connection between Assistant control panel and PC

The following text appears on the Assistant control panel screen: "USB connected". **Note:** The Assistant control panel cannot be used when it is connected to a PC.

- 2. Launch Drive composer by double-clicking Drive composer entry/pro.exe.
- 3. Click **Connect** if you want to connect to the drive or click **Demo** if you want to choose the Offline mode.

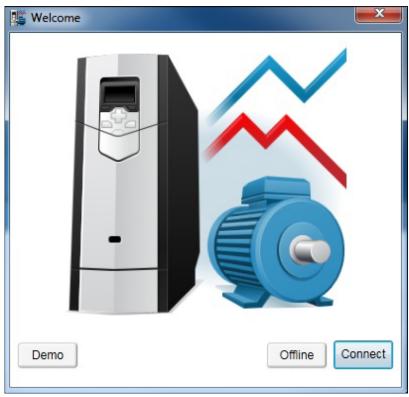


Figure 25. Connect/Demo button

Note: The status LED starts flickering in the Assistant control panel indicating that there is data transfer between drive and PC and the LED keeps blinking as long as there is a PC tool connected to the drive. The welcome dialog box is shown on the screen indicating that the application is being initialized.

34 Connections

Note: First time connection, parameter texts are loaded from the drive and this might take few minutes depending on the drive type.

Drive composer loads parameters and the following window displays.

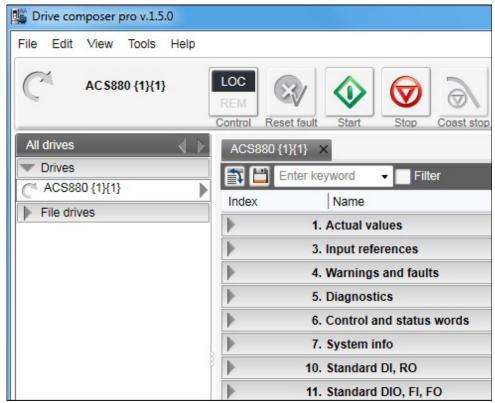


Figure 26. Parameters loaded

You have now an online connection to the drive. If you have a single drive and a point-to-point connection, move to chapter *Parameter window*.

 If you failed to make an online connection to the drive, go to View -> Settings to check your COM settings and click View -> Refresh (Ctrl + R) to reconnect Drive composer to the drive.

Changing the language settings

1. To change the language settings of the Drive composer UI, go to **View -> Settings**.

🎼 Drive compo	oser entry v.1.0.7.1 RC1	F. Samera
File Edit V	iew Help!	
C	 Normal text font size Large text font size The largest text font size 	Ctrl+F7 Ctrl+F8 Ctrl+F9
Demo x80	Tabs Floating windows Tile horizontally Tile vertically Cascade	Alt+T Alt+F Alt+H Alt+∨ Alt+C
	Refresh	Ctrl+R
	Settings	

Figure 27. View-Settings

2. In the **Settings** window, choose the required language for the Drive composer UI.

Drive composer default	language:	In english
Drive default language:		
Serial port:		
Save workspace on	exit	
Disable local contro	í.	

Figure 28. Language settings

- **Drive composer default language** to choose the default language of the menu or button text in Drive composer.
- Drive default language to choose the default language for parameters.

36 Connections

By changing language settings you can always use the same language when you connect Drive composer to the drive.

3. After changing the language settings click **View** -> **Refresh (Ctrl + R)** or restart the Drive composer application.

Note: Some elements might require application restart to update the selected language.

Connecting to a drive via an Ethernet network

Ethernet network connection

There are ABB drives which have control boards with an embedded Ethernet port and ABB drives in which the Ethernet connection is made with the FENA-11 Ethernet adapter module. For the installation of the adapter module, see *FENA-01/-11 Ethernet adapter module user's manual* (3AUA0000093568 [English]).

Note: The PC/Ethernet Switch firewall must be configured to allow a connection for Drive composer pro (port http 80 and UDP) or the firewall must be disabled.

Creating an Ethernet network connection with Drive composer (pro)

- 1. Connect the FENA-11 to a drive.
- 2. Create a point-to-point connection from Assistant control panel or Drive composer to each drive.
- If you use one adapter module with a drive, enable the FENA-11 by setting parameter 50.01 FBA A enable to Enable and parameter 50.21 FBA A Timelevel sel to Fast (or Slow for Tool network only).
- 4. If you use two fieldbus adapters with the drive and the FENA-11 has been installed as FBA B, enable the FENA-11 by setting parameters 50.31 FBA B enable to Enable and 50.51 FBA B Timelevel sel to Fast (or Slow for Tool network only).
- 5. Set a static IP address for each drive. See *FENA-01/-11 Ethernet adapter module user's manual* (3AUA0000093568 [English]).

T	51. FBA A settings					
1	FBA type	Ethernet	NoUnit			None
2	Protocol/Profile	MB/TCP ABB C	NoUnit			MB/TCP ABB C
3	Commrate	Auto	NoUnit			Auto
4	IP configuration	Static IP	NoUnit			Static IP
5	IP address 1	192	NoUnit	0	255	0
6	IP address 2	168	NoUnit	0	255	0
7	IP address 3	0	NoUnit	0	255	0
8	IP address 4	11	NoUnit	0	255	0
9	Subnet CIDR	24	NoUnit	0	32	0

Figure 29. IP settings of the drive with Drive composer

6. Refresh the settings with parameter 51.27 FBA par refresh.

Note: Refreshing the Node setting will lose the communication to the drive. To re-establish the connection with the drive, select **View** -> **Refresh**.

7. Name each drive to facilitate the recognition of drives when creating an Ethernet network connection.

If you use Drive composer, name the drives on the System info tab by typing the name to the Drive name field and clicking **Set**.

ZCU12_1 {2}{1	} System i	System info ZCU12_1 {2}{1} ×	
Drive name:	ZCU12_1	Set	2/19/2013 10:13:48 PM
Products			

Figure 30. Naming a drive with Drive composer

38 Connections

Note: The drive name changes after the view has been refreshed. The previous names in other existing workspaces are not affected.

If you use Assistant control panel, name the drives through the Setting menu of the panel.

8. Configure the TCP/IP address of your PC. In this example the TCP/IP address is 192.168.0.1. For more information on configuring the TCP/IP address, see *Configuring the TCP/IP address with Windows XP* or *Configuring the TCP/IP address with Windows 7*.

Configuring the TCP/IP address with Windows XP

- 1. Go to Control panel -> Network and Internet Connections -> Network Connections.
- 2. In the **Network Connections** window, double-click the required connection.

SNetwork Connections			
<u>File E</u> dit <u>V</u> iew F <u>a</u> vorites	Toc	ls Adva <u>n</u> ced <u>H</u> elp	
🕞 Back 🔹 🕥 🔹 💋 🕻	F (ず 🔎 Search 🌔 Folde	ers 🛄 🕶
Address 💊 Network Connection	IS		
		Name	Туре
Network Tasks	*	Broadcom NetXtreme G	igabit Ethernet
 Create a new connection Change Windows Firewall settings 		Local Area Connection	LAN or High-Speed Internet
See Also	*		
iv Network Troubleshooter			
Other Places	*		
📴 Control Panel			
🧕 My Network Places			
🙆 My Documents			
My Computer: FIHEL-L-4000514			

Figure 31. Network Connections window

3. Click the **Properties** button. The Local Area Connection Status dialog box appears.

🕹 Local Area Con	nection Status	? 🛛
General Support		
Connection		
Status:		Connected
Duration:		00:26:23
Speed:		100.0 Mbps
Activity		
	Sent — 🚮	Beceived
Bytes:	26,204	199,011
Properties	<u>D</u> isable	

Figure 32. Local Area Connection Status dialog box

4. Select Internet Protocol (TCP/IP) and click Properties.

🕹 Local Area Connection Properties 🛛 🛛 💽 🔀
General Advanced
Connect using:
Intel 21140-Based PCI Fast Ethernet
This connection uses the following items:
Client for Microsoft Networks
🗹 👵 File and Printer Sharing for Microsoft Networks
🗹 📮 QoS Packet Scheduler
✓ There Protocol (TCP/IP)
Install Uninstall Properties
Description
Transmission Control Protocol/Internet Protocol. The default wide area network protocol that provides communication across diverse interconnected networks.
Show icon in notification area when connected Notify <u>m</u> e when this connection has limited or no connectivity
OK Cancel

Figure 33. Local Area Connection Properties dialog box

40 Connections

5. Select **Use the following IP address** and type the IP address and the subnet mask. Click **OK**.

Internet Protocol (TCP/IP) Pro	perties 🛛 🖓 🛛
General	
this capability. Otherwise, you need the appropriate IP settings.	utomatically if your network supports I to ask your network administrator for
O <u>O</u> btain an IP address automat	ically
• Use the following IP address:	
IP address:	10.0.0.1
S <u>u</u> bnet mask:	255.0.0.0
<u>D</u> efault gateway:	
O D <u>b</u> tain DNS server address at	
Ouse the following DNS server	addresses:
Preferred DNS server:	
Alternate DNS server:	
	Advanced
	OK Cancel

Figure 34. Use the following IP address option selected TCP/IP address configuration is completed.

Configuring the TCP/IP address with Windows 7



Figure 35. Win 7 Control Panel

2. Click **Change adapter settings** on the left pane. A Network connections window displays.

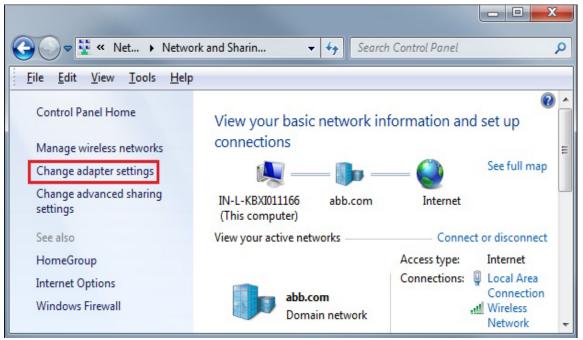


Figure 36. Network status and tasks

42 Connections

3. Double-click Local Area Connection.



Figure 37. Local Area Connection

4. Click Properties.

	tion Status	
General		
Connection		
IPv4 Connectivity	:	Internet
IPv6 Connectivity	:	No Internet access
Media State:		Enabled
Duration:		04:33:13
Speed:		100.0 Mbps
D <u>e</u> tails		
	Sent —	Received
	Sent — 4,266,957	
Activity	7	

Figure 38. Local Area Connection Status dialog box

5.	Select Internet Protocol	Version 4	(TCP/IPv4)	and click OK	٢.
----	--------------------------	-----------	------------	--------------	----

Local Area Connection Properties
Tetronolog Shanng
Connect using:
Intel(R) 82577LM Gigabit Network Connection
Configure This connection uses the following items:
✓ ➡ Virtual PC Network Filter Driver ▲ ✓ ➡ QoS Packet Scheduler ▲ ✓ ➡ File and Printer Sharing for Microsoft Networks ■ ✓ ➡ Internet Protocol Version 6 (TCP/IPv6) ■ ✓ ▲ Internet Protocol Version 4 (TCP/IPv4) ■ ✓ ▲ Link-Layer Topology Discovery Mapper I/O Driver ■ ✓ ▲ Link-Layer Topology Discovery Responder ▼
Install Uninstall Properties
Description Transmission Control Protocol/Internet Protocol. The default wide area network protocol that provides communication across diverse interconnected networks.
OK Cancel

Figure 39. Local Area Connection Properties dialog box

- 44 Connections
- 6. Select **Use the following IP address**, type the IP address and subnet mask and click **OK**.

atically if y ask your n			
	CUVOIN	auninis	suator
/			
192 . 16	в. о	. 1	
255 . 25	5.255	i. O]
	3	÷]
atically			
esses:			
•	12	÷	
	12]
	192 . 160 255 . 255 atically esses:	192 . 168 . 0 255 . 255 . 255 atically esses: 	192 . 168 . 0 . 1 255 . 255 . 255 . 0 atically esses:

Figure 40. Selecting the IP address and subnet mask

7. Connect the RJ45 cable between the FENA-11 and the PC. Alternatively, connect all drives and the PC to the same Ethernet switch.

8. Open command prompt (cmd.exe) and ping all the drives that you have configured.

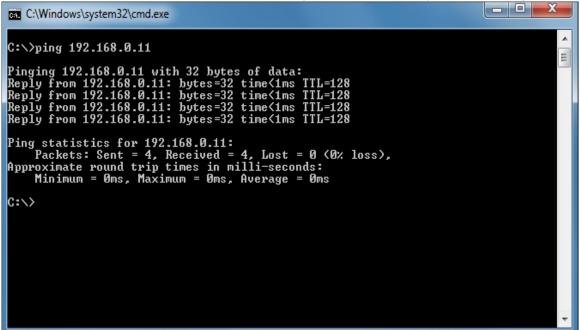


Figure 41. Pinging drives

Note: You must open http port 80 of the firewall on your PC to enable Drive composer pro to communicate with drives.

9. Open Drive composer pro.

Drive composer scans all COM ports and Ethernet ports to find drives. If problems arise, see *Ethernet tool network for ACS880 drives application guide* (3AUA0000125635 [English]).

Connecting network drives (pro)

Panel bus network connection

ABB drives with an ACS-AP-x panel can be daisy-chained through the control panel ports as a network either for a PC tool or a panel bus connection.

Note: Some ABB drives control boards (for example, ZCU-13) do not have any daisychain connectors. For those drives, a panel bus connection can be created with FDPI-02 option modules. See *FDPI-02 diagnostics and panel interface user's manual* (3AUA0000113618 [English]) for more information.



Figure 42. Creating a panel bus

Creating a panel bus with Drive composer (pro)

- 1. Create a point-to-point connection from the Assistant control panel or Drive composer to each drive.
- 2. Set an independent node ID for each drive (with parameter 49.01 Node ID number). The node ID must be between 1...32.
- 3. Refresh the settings (with parameter 49.06 Refresh settings).

Note: Refreshing the Node setting will lose the communication to the drive. To re-establish the connection with the drive, select **View** -> **Refresh**.

4. With parameter 49.05 Communication loss action, define how the drive reacts to a control panel (or PC tool) communication break by selecting **No action**.

•	49. Panel port communication					
1	Node ID number	5	NoUnit	1	32	1
3	Baud rate	230.4 kbps	NoUnit			230.4 kbps
4	Communication loss time	10.0	s	0.1	3000.0	10.0
5	Communication loss action	No action	NoUnit			Fault
6	Refresh settings	Done	NoUnit			Done

Figure 43. Panel port settings with Drive composer

5. Give a name for each drive to facilitate the recognition of drives when creating a panel bus connection.

If you use Drive composer, name the drives on the System info tab by entering the name to the Drive name field and clicking **Set**.

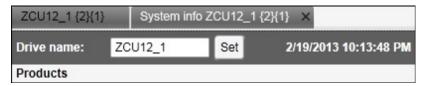


Figure 44. Naming a drive with Drive composer

Note: The drive name changes after the view has been refreshed. The previous names in other existing workspaces are not affected.

If you use Assistant control panel, name the drives through the Setting menu of the panel.

- 6. Remove all panels connected to drives.
- To daisy-chain the drives connect a standard RJ45 (straight CAT5) cable to the lefthand side connector of the Assistant control panel in the first drive (the left-hand side drive in figure *Creating a panel bus* on page 46).

Note: Heavy-industry type RJ45 male connectors do not fit into the drive side female RJ45 slot

- Connect a standard RJ45 (straight CAT5) cable from the right-hand side connector of the Assistant control panel in the first drive to the left-hand side connector of the Assistant control panel in the second drive.
- 9. Continue chaining the rest of the drives as described above.
- 10. If there is a long distance between the first and last drive in a panel bus, set the resistor to the ON position in the last node.

Connecting to the panel bus with Drive composer (pro)

- 1. Connect a USB cable between the Assistant control panel and your PC.
- 2. Double-click Drive composer pro.exe to launch Drive composer.

The status LED starts flickering on the Assistant control panel.

Note: It may take a long time before all drives are found.

Note: Drive composer does not open automatically any parameter window or other object.

3. Make sure you see all the drives in the Drive list.

Note: If you do not see all the drives, close the PC tool and try again. If you still do not see all drives, check Group 49 Panel port communication for the settings of the missing drives.

4. Select and click a drive from the Drive list.

Connection sharing (pro)

Select the option **Share connection with Control Builder Plus** to enable the simultaneous connection to the same drive from both applications.

Settings		×
Drive composer default language:	[In english 🔻
Drive default language:	[•
Save workspace on exit	(Ethernet config
Disable local control		
Share connection with Control B	uilder Plus	
	Save	Cancel

Figure 45. Connection sharing



Main user interface components

Contents of this chapter

This chapter describes the user interface (UI) components and how to use them.

Overview

The user interface consists of the following parts:

- 1. Title bar
- 2. Menu bar
- 3. Drive control panel
- 4. Drive list
- 5. Status panel (including the output view of the selected drive)
- 6. Working area for parameter windows, event logger, control diagrams, assistants etc.

The working area can be used either with tabs or floating windows. The figure below shows the user interface with floating windows.

The size of the drive list can be adjusted to the left/right. Similarly, the size of the working area can be adjusted by dragging the white separating line up/down. Most of the windows that are not maximized can be resized by dragging any corner. Scroll bars appear on the side or bottom of a window if it is possible to scroll the content.

Drive composer entry v.1.0.7.1 RC1		
Eile Edit View Help! 2	LOC REM W	6 A A A A A A A A A A A A A A A A A A A
ZCU12_1 Image: Constraint of the second se	Control Reset fault Start Stop Coast stop Reference: Step ZCU12_1 X Image: Control in the start Filter Not at default Select columns: Index Name Value Unit Image: Control in the start Not or speed used 1500.00 rpm 2 Motor speed estimated 1500.00 rpm 4 Encoder 1 speed filtered 0.00 rpm	Enable updating Min Max Default -30000.00 30000.00 0.00 -30000.00 0.00 -30000.00 0.00 -
	V - Monitor	Mask Y-scale Min Max A
8	{0}{0}Par 1.1 Motor speed used (rpm) {0}{0}Par 1.2 Motor speed estimated (rpm) ✓ Ⅲ	FFFFFFF Image: Constraint of the state of t
	(0)(0)Par 1.1 Motor speed used (rpm) 1/28/2014 2:17:39 PM x1=-23.4 y1=1500.00	(0){0}Par 1.1 Motor speed used x2=-3.4 y2=1500.00

Figure 46. Overview of the user interface

Title bar

The title bar is located at the top of the main window. It consists of the following parts:

- System menu icon
- Application name and version number (Drive composer entry/pro)
- Name of the workspace (if there is an active workspace)
- Minimize button which has the same function as Minimize in the System menu
- Maximize/Restore Down button (the name depends on the status of the maximized window) which has the same function as Maximize or Restore in the System menu
- Close button which has the same function as Close in the System menu.
 Note: When you close the application, system prompts to confirm. Click Ok to close the application.

Drive composer entry v.1.0.7.1 RC1

- -

Figure 47. Title bar

To reduce the main window to the taskbar or a sub-window to the bottom of the window area, click the **Minimize** button or go to **System menu** -> **Minimize**.

To enlarge the window to fill the available space, click the **Maximize** button or go to **System menu** –> **Maximize**.

To restore the window to the size and position it had before it was maximized, click **Restore Down** button or go to **System menu** –> **Restore**.

You can also maximize or restore the window by double-clicking the title bar.

To move a window, drag the title bar. To move a dialog box, drag its title bar. If you have maximized or minimized a window, you cannot move it by dragging the title bar.

To end your Drive composer session, click the **Close** button. Before closing down, Drive composer may:

- warn you about releasing control of the drive if the drive is controlled locally by Drive composer
- · prompt you to save the workspace with unsaved changes
- remind you to save your monitor data
- remind you of unfinished printing.

Note: If you disconnect cable from the drive *before* closing Drive composer there might be long delay in operation.

Note: To disable the function prompting you to save the workspace with unsaved changes, go to **View** -> **Settings**.

×
In english 🔻
-
COM5 -
Cancel

Figure 48. Save workspace on exit function

You can close Drive composer by

- double-clicking the System menu icon
- selecting Close in the System menu
- selecting Exit in the File menu
- pressing the shortcut key Alt+F4.

52 Main user interface components

System menu

You can open the System menu by

- left or right-clicking the System menu icon
- pressing the shortcut key Alt+space bar
- right-clicking within the non-button area of the title bar.

	Restore		
	Move		
	Size		
_	Minimize		
	Maximize		
x	Close	Alt+F4	

Figure 49. System menu

The System menu contains the following commands:

- **Restore** which has the same function as the **Maximize/Restore Down** button in the title bar when the window is maximized. The Restore command restores the window to its size and position which it had before it was maximized.
- **Move** which can be performed also by dragging the title bar. After selecting the Move command from the System menu, it is possible to move the window with the arrow keys. To stop moving the window, press Enter. To cancel the move, press Esc.
- **Size** which can be performed also by dragging any of the sides or corners of the window. After selecting the Size command, it is possible to resize the window with the arrow keys. To stop resizing the window, press Enter. To cancel resizing, press Esc.
- **Minimize** which has the same function as the **Minimize** button in the title bar. The Minimize command reduces the window to the taskbar or to the bottom of the window area.
- **Maximize** which has the same function as the **Maximize** button in the title bar when the window has not been maximized. The Maximize command enlarges the window to fill the available space.
- **Close** which has the same function as the **Close** button in the title bar. The Close command ends the Drive composer session.

Menu bar

The menu bar is located below the title bar. It contains the following drop-down main menus:

- File
- Edit
- View
- Tools (pro)
- Help.

To execute a command from a menu, click its name on the menu. You can also use the arrow keys to navigate between the menus. To execute a highlighted command, press ENTER. To close a menu, press the ESC key. You can also use the shortcut keys to execute the commands.

File menu

The File menu is always located in the menu bar.

📫 Di	rive composer pro v.1.5.0.4 R	C4
File	Edit View Tools Help	
	New	,
	Open	,
	Save workspace	Ctrl+S
	Save workspace as default	Ctrl+D
	Print	Ctrl+P
	Print real-time monitor view	
	Exit	Alt+F4

Figure 50. File menu

The File menu contains the following commands:

• **New.** opens a window where you can select a custom parameter set window. The keyboard shortcut for the custom parameter set command is Ctrl+N.

e Edit View Tools Help			
New	•	Custom parameter set	Ctrl+N
Open	,		
Save workspace	Ctrl+S		
Save workspace as default	Ctrl+D		
Print	Ctrl+P		
Print real-time monitor view			
Exit	Alt+F4		

Figure 51. Custom parameter set

• **Open..** opens a new dialog.

File	Edit View Tools Help			
	New	•		
	Open	•	Open the latest saved workspace	Ctrl+L
	Save workspace	Ctrl+S	Open workspace	Ctrl+O
	Save workspace as default	Ctrl+D	Monitor file	Ctrl+M
	Print Print real-time monitor view	Ctrl+P	Parameter file	Alt+P
	Find real-time monitor view		Custom parameter file	Alt+W
	Exit	Alt+F4		

Figure 52. Open command

- **Open the latest saved workspace** opens the latest saved workspace. The keyboard shortcut for the open latest saved workspace command is Ctrl+L.
- **Open Workspace** opens a new window where you can select the saved workspace to be opened. The keyboard shortcut for the Workspace command is Ctrl+O.
- Monitor file opens a window to open the parameter file for monitoring.
- **Parameter file** opens a new window where you can select the saved parameter file to be opened. The keyboard shortcut for the Parameter file command is Alt+P.
- **Custom parameter file** opens a new window where you can open the saved custom parameter file. The keyboard shortcut for the Custom parameter file command is Alt+W.
- **Save workspace** saves the active workspace to a file. The keyboard shortcut for the Save workspace command is Ctrl+S.
- Save workspace as default saves the active workspace to default workspace. The default workspace opens automatically when Drive composer is opened. The keyboard shortcut for the Save workspace as default command is Ctrl+D.
- **Print (pro)** menu prints the parameter screen.
- Print real-time monitor view (pro) prints the monitor screen.
- Exit ends the Drive composer session.

Edit menu

The Edit menu is always located in the menu bar.

Drive composer entry v.1.0.7.1 RC1	
File Edit View Help!	
Languages	Deutsch In english Suomeksi
Demo x80 {0}{19}	по-русски
k Event logger	在中國

Figure 53. Edit menu

The menu contains the language commands with which you can select the language for the Drive composer user interface.

Note: Restart the Drive composer to see the language changes.

View menu

The View menu is always located in the menu bar.

Drive comp	ooser entry v.1.0.7.1 RC1	
File Edit	√iew Help!	
C .	 Normal text font size Large text font size 	Ctrl+F7 Ctrl+F8
Demo x80	The largest text font size	Alt+T
👔 Parame	Floating windows Tile horizontally Tile vertically	Alt+F Alt+H Alt+V
	Cascade	Alt+C
	Refresh Settings	Ctrl+R

Figure 54. View menu

The View menu contains the following commands:

 Normal text font size for selecting the normal font size. The keyboard shortcut for Normal text font size is Ctrl+F6.

Note: The change in the font size does not affect the size of the monitor window font.

- Large text font size for selecting the larger font size. The keyboard shortcut for Large text font size is Ctrl+F7.
- **The largest text font size** for selecting the largest font size. The keyboard shortcut for the largest text font size is Ctrl+F8. The font sizes can also be changed with the following A-letter icons.



Figure 55. A-letter icons for changing the font size

• **Tabs** for changing the working area to be viewed as tabs. The keyboard shortcut for Tabs is Alt+T.

Note: The monitor window cannot be tabbed.

• Floating windows for changing the working area in a separate window. The keyboard shortcut for Floating windows is Alt+F.

Note: The monitor window cannot be a floating window.

- **Tile horizontally** for changing floating windows to be tiled horizontally. The keyboard shortcut for Tile horizontally is Alt+H.
- **Tile vertically** for changing floating windows to vertical. The keyboard shortcut for Tile vertically is Alt+V.

- **Cascade** for changing floating windows to cascade. The keyboard shortcut for Cascade is Alt+C. The cascaded windows can be resized and freely located in the working area.
- **Refresh** for creating a new connection to the drive (uploads parameter information from a single drive and creates a new connection with multidrives). The keyboard shortcut for Refresh is Ctrl+R.
- **Settings** for defining the language, serial port and for choosing whether the workspace is saved on exit and whether the local control is disabled.

Tools menu (pro)

The Tools menu is located in the menu bar. The commands of the Tools menu vary between SW versions and drives.

Drive composer pro	v.1.5.0.1 RC1	
File Edit View To	pols Help!	
Demo x	Drive Parameter Conversion Tool	Ctrl+Alt+P
	EDS Export	Ctrl+I
All drives	Compare drive data	
Drives Demo x80 {0}{	Backup network	
File drives	Application symbols	Alt+A

Figure 56. Tools menu

The menu contains the following commands:

- Drive Parameter Conversion Tool to convert the parameters.
- **EDS Export** for creating the EDS files of a connected drive. The keyboard shortcut for EDS Export is Ctrl+I.
- **Compare drive data** for comparing parameters of two drives or a parameter file and a drive or two parameter files. The keyboard shortcut for Compare drive data is Alt+C.
- **Backup network** for creating backups of all connected drives in a PC tool network. The keyboard shortcut for Backup network is Ctrl+ B.
- **Application symbols** for showing the symbols exported from Control Builder Plus application for the drive. If the drive does not have Control Builder Plus application list remains empty.

Help menu

The Help menu is always located in the menu bar.

File Edit View Tools	Help
C	Content F
Demo x80 {0}{1	Firmware manual Fi
	Make support package
All drives	Import licence file
Trives	
Demo x80 {0}{19}	About the product

Figure 57. Help menu

The Help menu contains the following commands:

- **Content** or the F1 key opens the Drive composer user manual as a PDF file.
- **Firmware manual** or the F3 key opens the firmware manual of the drive in a separate window as a PDF file. If you have selected a parameter or some other significant item when you click this command or press the F3 key, the appropriate chapter in the firmware manual is displayed.
- **Make support package** function creates a single file, that can be sent to local ABB support contact in case of any need for support.
- **Import licence file (pro)** function displays the Product activation window. Enter the activation key and click Activate.
- About the product opens a window displaying the program information, version number and copyright text.

Drive control panel

The drive control panel is located below the menu bar. It has buttons for controlling a connected drive. It also shows the status of the drive.



Figure 58. Drive control panel

The drive control panel contains the following buttons and items:

- Name and node number of the currently controlled drive and an indication if it is running. See below for status icons explanations.
- **Control** button controls the selected drive with Drive composer or releasing the control of the drive.
- **Reset fault** button sends a reset command to the drive. If the fault is no longer active, the drive clears it.
- **Start** button starts the currently controlled drive. A motor connected to the drive starts rotating according to the set reference value.
- Stop button stops the rotation of the motor connected to the currently controlled drive.
- Coast stop button.
- **Reference** value field enables entering a new reference value. When you click the Reference field, a tooltip tells you max and min limits for the reference and current reference value.
- Reference field shows the reference used in the drive. The reverse direction is set manually with the sign.
- Set button enforces the value in the reference value field to the currently controlled drive. The same command can be performed by pressing Enter.
- Active reference displays the reference value.
- **Step configuration** cycle button enables to modify Step type, Step value and Step duration with reference value. The available configuration is dependent on the connected drive.
- **Step** functionality activates the step cycle with the reference value.

Drive list panel

The drive list panel shows all connected drives and open files. Drives are indicated with a motor icon (clockwise open circle arrow).

All drives	$\triangleleft \triangleright$
🐨 USB- drives	
C ACS880_1	•
ACS880_2) b
ACS880_3	- È
ACS880_4	- b
ACS880_5) b
ACS880_6	- È
C Test Drive) b
C Test Drive	- b
ACS880_9) þ
➡ File drives	
acs880.dcparamsbak	•

Figure 59. Drive list panel in Drive composer pro

A grey circle arrow indicates a stopped drive.

All drives	< ▶
VSB- drives	
C Test Drive	•

Figure 60. Stopped drive

A green circle arrow indicates a running drive.



Figure 61. Running drive

A red circle with a white cross (x) indicates a faulty drive.



Figure 62. Faulty drive

An orange background means that a drive that has an alarm.



Figure 63. Drive with an alarm

A red broken line (-//-) means that the connection to a drive has broken.



Figure 64. Drive with a broken connection

The views for a drive – parameter window, data logger, event logger, system info, assistants (if such are available for the drive), control diagrams (if such are available for the drive) – can be seen by clicking with the primary mouse button and selecting the corresponding icons from the pop-up window.

You can open those views either as new tabs or floating windows. If an active window is associated with a drive or a file, the corresponding tree item is highlighted in the drive list.

Using the drive control panel for starting the drive

- 1. See the firmware manual of the drive for parameters you must set before starting.
- Click the **Control** button.
 The control box indicator changes to LOC.
- 3. Enter a reference value and press Enter or click the **Set** button.
- 4. Click Start.

The drive starts. The indicator box arrow changes to green.

Note: Limit settings in group 30 affect reference limits.

Working area

Parameter windows, custom parameter windows, event logger, system info, control diagrams, assistants etc. are shown in the working area. The user interface is tabbed by default. You can change the order of tabs by dragging them. You can open tabs for a single drive or for multiple drives.

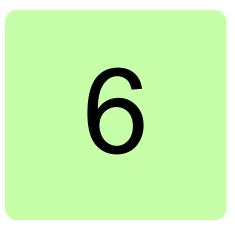
ZCU12_1	× Event logger ZCU12	_1 System info Z	CU12_1		
	Enter keyword 🛛 👻 🔲 Fi	iter 📃 Not at default	Select co	lumns:	-
Index	Name	Value		Unit	Min
-	1. Actual values				
1	Motor speed used	i	1500.00	rpm	-30000.00
2	Motor speed estir	nated	1500.00	rpm	-30000.00
4	Encoder 1 speed	filtered	0.00	rpm	-30000.00
5	Encoder 2 speed	filtered	0.00	rpm	-30000.00
6	Output frequency		50.00	Hz	-500.00

Figure 65. Tabbed user interface

The working area can be set to a floating window. For example, parameter window, event logger, system info etc. are shown as floating windows. The floating windows can be tiled vertically or horizontally or cascaded by using the commands in the **View** menu.

Drive composer entry v	.1.0.7.1 RC1								-	X
<u>F</u> ile <u>E</u> dit <u>V</u> iew <u>H</u> elp!									AAA	
C ZCU12_1	LO RE Cont		Stop Coast stop	Active refe 149 1499 Reference	erence 9.9 Se	t	الع Step		A [i]	BB R
ZCU12_1	ZCU12_1					23	Event logger ZCU12_1			23
System info	🖹 💾 Ent	er keyword 🔹 🔤 Filter	Not at default	÷			Refresh log			
Parameters	Index	Name	Value		Unit		Drive	Icon	Time	F
	•	1. Actual values				*	ZCU12_1 {0}.{0}		19.02.2013 21:34:40.432	€
	1	Motor speed used		1500.00	rpm	Ξ	ZCU12_1 {0}.{0}	3	18.02.2013 19:52:36.526	e
	2	Motor speed estimated	t	1500.00	rpm		701140 4 (0) (0) 4	-	10 00 0040 10-40-04 040	*
	4	Encoder 1 speed filter	ed	0.00	rpm					_
	5	Encoder 2 speed filter	ed	0.00	rpm		System info ZCU12_1			X
	6	Output frequency		50.00	Hz		Drive name: ZCU12	2_1	Set 2/19/201	3 1
	7	Motor current		2.12	A		Products			=
6	10	Motor torque %		0.0	%		Drive type:		ACS880	
8	11	DC voltage		568.38	v		Drive model: Serial number:			
	13	Output voltage		0	v	-	Firmware version: Description:		AINF7 v1.62.200.22	
	4	m			+		Drive name:		ZCU12_1	

Figure 66. Floating windows



Parameter window

Contents of this chapter

This chapter describes the parameter and custom parameter windows.

Parameter window

With Drive composer entry the parameter window is always opened when you make connection to a drive. With Drive composer pro the parameter window is opened by clicking on the selected drive in the drive list and selecting **Parameters**.

The parameter window view displays parameter groups, parameters and their values for the associated drive or a file. There can be several parameter windows in the working area. The headline of each parameter window shows which drive it belongs to.

	Following are the	command icons	available in the	parameter window.
--	-------------------	---------------	------------------	-------------------

Icon	Description
	Expands/collapses parameter groups. When parameter groups are expanded, all parameter values are read once from the drive.
	Saves parameters to a file. Saves visible parameters to a file. File extension is dcparams(bak).
Enter keyword Filter	Enables you to search parameter lists with a keyword. Search is activated/deactivated by clicking the Filter check box. When the Filter check box is unchecked all parameters are seen. Note: If parameter groups have not been expanded, the first search takes about 3060 seconds.
Select columns:	Allows you to select/deselect columns to be seen in a parameter window.

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Icon	Description
Enable updating	Parameters are updated only when a group is opened. With the Enable updating function it is possible to set all open and visible groups to be updated automatically. Parameters that have been set to be updated automatically have a yellow background.
	Allows you to download parameters from a file to a drive. With a custom parameter window allows downloading offline values to a drive.
Change drive	Enables you to change the window target, which is useful if you have Drive composer pro and you have to check certain parameters of another drive. Included only in custom parameter windows.
Not at default	Provides you with a list of all user-changed parameters if you click the check box. These parameters have an orange background.
Ð	Allows you to add or remove one parameter or signal or several parameters or signals to/from a custom parameter window.

ZCU12_	_1 {2}{1} ×						
T	Enter keyword Filter N	ot at default S	Select co	lumns:	- E	nable updat	ting 📄
Index	Name	Value		Unit	Min	Max	Default
-	1. Actual values						
1	Motor speed used		0.00	rpm	-30000.00	30000.00	0.00
2	Motor speed estimated		0.00	rpm	-30000.00	30000.00	0.00
4	Encoder 1 speed filtered		0.00	rpm	-30000.00	30000.00	0.00
5	Encoder 2 speed filtered		0.00	rpm	-30000.00	30000.00	0.00
6	Output frequency		0.00	Hz	-500.00	500.00	0.00
7	Motor current		0.00	Α	0.00	30000.00	0.00
10	Motor torque %		0.0	%	-1600.0	1600.0	0.0
•	3. Input references						
•	4. Warnings and faults						
•	5. Diagnostics						
•	6. Control and status words						
•	7. System info						
-	10. Standard DI, RO						
1	DI status	0b1000 0000	0000	NoUnit	0b0000	0b1111 11 [.]	0b0000
2	DI delayed status	0b1000 0000	0000	NoUnit	0b0000	0b1111 11 [.]	0b0000
3	DI force selection	C	0000d	NoUnit	0b0000	Ob1111 111	0b0000
4	DI force data	0	0000d	NoUnit	0b0000	0b1111 111	0b0000
5	DI1 ON delay		5.0	s	0.0	3000.0	0.0
6	DI1 OFF delay		0.0	s	0.0	3000.0	0.0
7	DI2 ON delay		0.0	S	0.0	3000.0	0.0
8	DI2 OFF delay		10.0	S	0.0	3000.0	0.0
9	DI3 ON delay		0.0	s	0.0	3000.0	0.0
10	DI3 OFF delay		0.0	S	0.0	3000.0	0.0

Figure 67. Parameter window

The parameter window contains different types of parameters. Some of these types are identified by colors or bold fonts as shown in the table below:

Icon/Example	Explanation
Regular	Normal parameters
1.1 Motor speed	Signals (bold, magenta)
1 DI status 0b0000	Bit names of a parameter can be seen by double-clicking on the parameter (bold). New window opens.
P2.1.1	Parameter value is set from another parameter, for example, parameter group 2, index 1, bit 1.
P2.1.2-	Parameter value is an inverted bit of another parameter, group 2, index 1, bit 2.
	User has changed the value of a parameter (shown with an
28 Al2 max 20,000	orange background).

The most common type is the regular parameter. Parameters are normally readable and writable. However, when the drive is running, some parameters may be write-protected.

Parameter names, values, units, default values and different user sets are shown in the parameter window. The number of user sets depends on the drive type.

The value of a parameter is read only once. If you want to update this value, right-click and select **Refresh the parameter**. You can set all visible parameters to update automatically by clicking the **Enable updating** button.

The values of signals cannot be modified. If signals are modified, you will get an error prompt for every signal. Signals are updated cyclically in the parameter window. Parameter signals are also updated frequently, but their values can be modified.

Navigating parameters and groups

Parameter values are updated if they are modified. A parameter value can be modified by double-clicking the parameter or by pressing Enter on a highlighted parameter. To update parameter group values, right-click the group name and select **Refresh group parameters**.

In special cases, hidden parameters and groups become available by modifying some parameter values, the **View -> Refresh** command updates the whole parameter table. An example for such a group is group 51 FBA A Settings: When the adapter module has been enabled in group 50, the parameter names can be seen by selecting **View -> Refresh**.

Note: The parameter window must be closed before refreshing and opened again after refreshing.

There are five alternative formats in which parameters are shown: default, binary, hexadecimal, integer and float format. To change the format of a parameter, right-click and select either **Use default format**, **Use binary format**, **Use hexadecimal format**, **Use integer format** or **Use float format**.

You can change the widths of the columns by dragging the vertical lines between the column headers.

66 Parameter window

Double-click the value field box to see the bit names of certain binary parameters. For example, see the below parameter 10.1 DI status.

ZCU12_1	{2}{1} ×						
T 🗎 🗉	inter keyword 🛛 🗕 Filter	Not at default Select co	olumns:	🔹 📄 Enable u	pdating		
Index	Name	Value	Unit N	vin Max	Default		
₽	7. System info		Binan	v parameter edit	or DI status {2}{1}		
-	10. Standard DI, RO						
1	DI status	0b1000 0000 0000	Old valu	ue [bin] 0b100	0 0000 0000 0000	[hex] 0x8000	[dec] 32768
2	DI delayed status	0b1000 0000 0000	New val	lue [bin] 0b100	0000000000000	0x8000	32768
3	DI force selection	0b0000					
4	DI force data	0b0000	Bit	Name	Val	lue	
5	DI1 ON delay	5.0	0	0 = DI1	0		
6	DI1 OFF delay	0.0	1 2	1 = DI2 2 = DI3	0		
7	DI2 ON delay	0.0	3	3 = DI4	0		
8	DI2 OFF delay	10.0	4	4 = DI5	0		
9	DI3 ON delay	0.0	5	5 = DI6 6	0		
10	DI3 OFF delay	0.0	7	7	0		
11			8	8	0		
	DI4 ON delay	0.0	9	9	0		
12	DI4 OFF delay	0.0	10	10 11	0		
13	DI5 ON delay	0.0	12	12	0		
14	DI5 OFF delay	0.0	13	13	0		
15	DI6 ON delay	0.0	14	14	0		
16	DI6 OFF delay	0.0	15	15 = DIIL	1		
21	RO status	0b0101	Def				0
24	RO1 source	Ready run	Refr	esn			Cancel
25	RO1 ON delay	0.0	s	0.0 300	0.0 0.	.0	

Figure 68. Bit names for a parameter

To reset a parameter, right-click it and select Reset to default.

Parameter values are read once when a group is opened. Independent parameters from different groups can be set to the Auto-update mode by right-clicking them and selecting **Add to auto-update**. The parameters that are updated automatically are seen with a yellow background as shown in the following figure.

Note: Signals are automatically updated cyclically

1	Enter keyword 🔻 🗌 Filter 🔜 N	Not at default Select co	olumns:	- E	Enable up	dating 💂	
Index	Name	Value	Unit	Min	Max	Default	
•	19. Operation mode						
1	Actual operation mode	Speed	NoUnit				Speed
11	Ext1/Ext2 selection	EXT1 -	NoUnit				EXT1
12	Ext1 control mode	Speed	NoUnit				Speed
14	Ext2 control mode	Speed	NoUnit				Speed
16	Local control mode	Speed	NoUnit				Speed
17	Local control disable	No	NoUnit				No
20	Scalar control reference unit	Rpm	NoUnit				Rpm
•	20. Start/stop/direction						
•	21. Start/stop mode						
•	22. Speed reference selection						
)÷	23. Speed reference ramp						
•	24. Speed reference condition	i					
•	25. Speed control						
•	26. Torque reference chain						
•	28. Frequency reference chair	1					

Figure 69. Parameters with a yellow background

Parameters or signals can be sent to the monitor window by right-clicking them and selecting **Send to monitor**. Parameters can be copied to a custom parameter window by right-clicking them and selecting **Copy**. In addition, you can drag and drop parameters to a custom parameter window.

Pointer parameters

One special type of a parameter is a pointer parameter. The value of a pointer parameter is read from the parameter it points to. Depending on the pointer parameter, value or bit pointer, its target can be another parameter or one of its bits. Some pointer parameters can be assigned Active (false) or Inactive (true).

In most cases, common settings are offered as a selection list. In those cases where the selection list does not offer the correct pointer, pointing can be done by selecting **Other...** from a selection list.

*	21. Start/stop mode		
1	Start mode	Automatic	NoUnit
2	Magnetization time	500	ms
3	Stop mode	Coast	NoUnit
4	Emergency stop mode	Ramp stop (Off1)	NoUnit
5	Emergency stop source	-	NoUnit
6	Zero speed limit	Other Active (
7	Zero speed delay	Inactive	
8	DC current control	d DIIL	t
9	DC hold speed	DI2 DI3	- 1
10	DC current reference	DI4	- 1
11	Post magnetization time	D15	
13	Autophasing mode	DIO1 DIO2	t

Figure 70. Constant value for a pointer parameter

Select a parameter from the list for a value pointer and then its bit from 0 to 31 for a bit pointer.

You can also enter a value manually by selecting the Edit manually check box. The value must follow form P.#.#.#, where the first # is the parameter group number, the second # is the parameter number and the third # is the bit number without leading zeros (for example P.2.1.2).

Active (false) or Inactive (true) are the constant values that can be entered manually.

	alue : Off	
lew	value : P.10.1.5 -	
	Edit manually	
	Invert Value	
	Other	•
•	10 Standard DI, RO	
1	DI status Bit: 5 = DI6 -	
2	DI delayed status	-
3	DI force selection	
4	DI force data	
5	DI1 ON delay	
6	DI 1 OFF delay	
7	DI2 ON delay	
8	DI2 OFF delay	
9	DI3 ON delay	

A bit pointer value can also be inverted by selecting the Invert value check box.

Figure 71. Inverting a bit pointer value

The inverted bit pointer value is shown with the minus sign at the end of the parameter.

W	20. Start/stop/direction			
1	Ext1 commands	In1 Start; In2 Dir	NoUnit	In1 Start; In2 Dir
2	Ext1 start trigger	Edge	NoUnit	Edge
3	Ext1 in1	P.10.1.5 -	NoUnit	DI1

Figure 72. Inverted bit pointer value with the minus sign

Setting fieldbus data in/out parameters

Process data transferred to and from the drive/PLC is set with parameter groups 52 and 53. With an ACS880 drive it is possible to select the data type for each selected parameter/signal in these group.

1. Double-click FBA data in/out parameter and select Other.

📑 🗖 E	Enter keyword 🛛 🗾 Filter	Not at default	Select columns:
Index	Name	Value	Unit
-	52. FBA A data in		
1	FBA A data in1		✓ NoUnit
2	FBAA data in2		Other Unit
3	FBA A data in3		None CW 16bit Unit
4	FBA A data in4		Ref1 16bit Ref2 16bit ^{Unit}
5	FBA A data in5		SW 16bit Unit
			Act1 16bit
6	FBA A data in6		Act2 16bit Unit
7	FBA A data in7		CW 32bit Ref1 32bit ^{Unit}
8	FBA A data in8		Ref2 32bit Unit
			SW 32bit
9	FBA A data in9		Act1 32bit Unit
10	FBAA data in10		Act2 32bit SW2 16bit Unit
11	FBA A data in 11		None NoUnit
12	FBAA data in12		None NoUnit

Figure 73. Selecting the data type

2. Select the format in which the value is handled:16-bit, 32-bit or floating point format.

Set pointer parameter			~
Old value : SW 16bit			
New value : 1.1[16]			
Edit manually			
[1	6 bit	-
Other		32	bit bit oat
1 Actual values			
1 Motor speed used			=
2 Motor speed estimated			
4 Encoder 1 speed filtered			
5 Encoder 2 speed filtered			
6 Output frequency			
7 Motor current			
10 Motor torque %			
11 DC voltage			
13 Output voltage		•	-
Ok	Can	cel	

Figure 74. Selecting the format

In the parameter window the selections are shown inside brackets: [16], [32] or [F].

•	52. FBA A data in		
1	FBAA data in1	1.1[16]	NoUnit
2	FBAA data in2	1.11[16]	NoUnit
3	FBAA data in3	1.7[16]	NoUnit
4	FBAA data in4	None	NoUnit
5	FBA A data in5	1.4[16]	NoUnit

Figure 75. Formats shown inside brackets in the parameter window

Note: The floating point or 32-bit value reserves 2 slots in the configuration. Consequently, if you try to select a value for parameter 52.04 as in the figure above, you get a Parwrite failed error message. The scalings of parameters/signals are found in *ACS880 primary control program firmware manual* (AUA0000085967 [English]).

Note: You should always check the parameter mapping from the manual of the used fieldbus protocol. Example, FENA-01/-11/-21 Ethernet adapter module user's manual (3AUA0000093568 [English]) or FPBA-01 PROFIBUS DP adapter module user's manual (3AFE68573271 [English]).

Binary parameters

Binary parameters have a special meaning for each of their bits. These parameters are modified in a special Set binary parameter dialog. The value can be modified numerically in binary, hexadecimal or decimal format.

You can modify the values in the bit by double-clicking the value field for each bit. Some bits are greyed out and disable to edit.

Another way to modify a bit is to type the bit value directly to the New value [bin] / [hex] / [dec] field.

Signal values, which are in binary format, can be viewed in a similar dialog.

矘 Binary	parameter editor DI st	atus {2}{1}		×
Old value	e (bin) 0b1000 0000	0000 0000	[hex] 0x8000	[dec] 32768
New valu	ue [bin] 0b10000000	000000	0x8000	32768
Bit	Name	Value		
0	0 = DI1	0		
1	1 = DI2	0		
2	2 = DI3	0		
3	3 = DI4	0		
4	4 = DI5	0		
5	5 = DI6	0		
6	6	0		
7	7	0		
8	8	0		
9	9	0		
10	10	0		
11	11	0		
12	12	0		
13	13	0		
14	14	0		
15	15 = DIIL	1		
Refre	esh		Ok	Cancel

Figure 76. Binary parameter editor

Search for groups and parameters

You can search the names of parameters and groups inside the parameter window. The search result is a list of all parameters matching the search text criteria. For example, all torque-related parameters can be found by entering search criteria "torque" in the Enter keyword field and clicking the Filter check box. To uncheck the Filter box, click it again.

ZCU12_1 {	{2}{1} ×					
📉 💾 to	orque 🗸 🗸 Filter 🚺 N	ot at default Select co	lumns:	- E	nable upda	ting 📘
Index	Name	Value	Unit	Min	Max	Default
•	26. Torque reference chain					
1	Torque reference to TC	0.0	%	- <mark>1600.</mark> 0	1600.0	0.0
2	Torque reference used	0.0	%	-1600.0	1600.0	0.0
8	Minimum torque ref	-300.0	%	-1000.0	0.0	-300.0
9	Maximum torque ref	300.0	%	0.0	1000.0	300.0
11	Torque ref1 source	Zero	NoUnit			Zero
12	Torque ref2 source	Zero	NoUnit			Zero
13	Torque ref1 function	Ref1	NoUnit			Ref1
14	Torque ref1/2 selection	Torque reference 1	NoUnit			Torque reference 1
16	Torque additive 1 source	Zero	NoUnit			Zero
17	Torque ref filter time	0.000	S	0.000	30.000	0.000
18	Torque ramp up time	0.000	S	0.000	60.000	0.000
19	Torque ramp down time	0.000	s	0.000	60.000	0.000
25	Torque additive 2 source	Zero	NoUnit			Zero
26	Force torque ref add 2 zero	Not selected	NoUnit			Not selected
41	Torque step	0.0	%	-300.0	300.0	0.0

Figure 77. Search example

Note: The first search takes about 30...60 seconds, because Drive composer goes through the whole parameter structure. The next searches are fast. All searches are in memory of the PC as long as Drive composer is on.

Custom parameter window

In Drive composer it is possible to customize parameter windows. This means that parameters/signals can be dragged and dropped or copied from the main parameter window or from other custom parameter windows. You can rename custom parameter windows.

For example, you can collect all the typical parameters used in a quick start-up to one window. You can create separate windows for separate functions (for example, references, limits, ACS880 I/O). Custom parameter windows open automatically when a connection to a drive is made because they are saved with the workplace. Custom parameter windows can also be opened separately.

Parameter values can be changed in custom parameter windows. Custom parameter windows can be used both in tabbed and floating windows environments.

Separate custom parameter windows can be also saved to a file by selecting **Save parameters to file**. The changed values in the Offline value column are saved as well. Therefore the contents of a custom parameter window can be used for the parameterization of another drive. You can send the saved custom parameter windows to other users and they can open them with their Drive composer to see parameters that you want them to check or download to a drive.

Note: When a custom parameter window is saved, the actual drive values of the Value column are copied to the Offline value column. During loading the values in the Offline value column are shown in comparison with the current actual values. When you open the file containing the saved custom parameter window you can copy the values of the Offline value column to another drive by clicking the **Download to device** button.



Figure 78. Download to device button

In a network of drives, you can create a custom parameter window including parameters/signals selected from different drives. To have a view where all parameters are from one drive, click the **Change drive** button and select the drive.

To see the value of a parameter/signal used in another drive, right-click the parameter/signal and select **Change drive**.

ACS880 {1}{2}	Custom 1 ×	A	CS880 {1}{2} C	ustom 1 🛛 🗙		
🛟 💾 📇 Change	drive 🗓 Enter keyword	🔻 🔲 Filte 🚭	💾 🛅 Change	drive 📳	Enter keyword 🛛 🚽 🔲 Filter	
Index	Name	Value	Index	Name	Value	
{1}{2}Par.1.1	Motor speed used		{1}{2}Par.1.1	Motor spe	eed used	0,00
{1}{2}Par.1.2	Motor speed estimated		{1}{2}Par.1.2	Motor :	Сору	7,00
{1}{2}Par.1.4	Encoder 1 speed filtered		{1}{2}Par.1.4	Encode	Paste),00
{1}{2}Par.1.5	Encoder 2 speed filtered		{1}{2}Par.1.5	Encode),00
{1}{2}Par.1.6	Output frequency		{1}{2}Par.1.6	Output	Delete parameter),00
{1}{2}Par.1.7	Motor current		{1}{2}Par.1.7	Motor	Send to monitor),00
{1}{2}Par.1.10	Motor torque %		{1}{2}Par.1.10	Motor 1		0,0
{1}{2}Par.1.11	DC voltage		{1}{2}Par.1.11	DC vol	Reset to default),00
{1}{2}Par.1.13	Output voltage		{1}{2}Par.1.13	Output	Change drive	0
{1}{2}Par.1.14	Output power		{1}{2}Par.1.14	Output		1,00
{1}{2}Par.1.18	Inverter GWh counter		{1}{2}Par.1.18	Inverte	Refresh the parameter	0

Figure 79. Change drive button

Adding parameters to a custom parameter window

The following example shows how to:

- create a new custom parameter window
- add parameters to a custom parameter window
- modify the Offline value column in the custom parameter window
- copy/download parameters to a drive.

1. Click File -> New -> Custom parameter set.

	Drive composer entry v.1.0.7.1 RC	1					
File	Edit View Help!						
	New	•	С	ustom par	ameter set	Ctrl	+N
	Open	•	V	V		Ø	ACTIV
	Save workspace	Ctrl+S	et fault	Start	Stop	Coast stop	Refe
	Save workspace as default	Ctrl+D					
	Exit	Alt+F4					

Figure 80. Custom parameter set

2. Name the custom paramet	er window.
----------------------------	------------

*	X
Name of window	
Ok	Use default

Figure 81. Name of window

3. Click **Add** button to add parameters/signals to the new custom parameter window or copy paste from other parameter window.

rive 🖳 Enter keyword	🔻 🔲 Filter
Name	Value

Figure 82. Add parameter button

76 Parameter window

rive : ACS880 {2}{1}				
rive parameters			Selected parameters	
30 Limits	*		{2}{1}Par.30.11 Minimum speed {2}{1}Par.30.12 Maximum speed	
1 Limit word 1				
2 Torque limit status				
11 Minimum speed	E			
12 Maximum speed		Add		
13 Minimum frequency		Demons		
14 Maximum frequency		Remove		
17 Maximum current				
18 Minimum torque sel				
19 Minimum torque	*			
(III.	•			

Figure 83. Add minimum and maximum values

- Change the values in the Offline value column to be the same as the online values.
 Note: The values in the Offline value column do not have to be the same as the online values.
- 6. Save the custom parameter window by clicking the **Save parameters to file** icon.

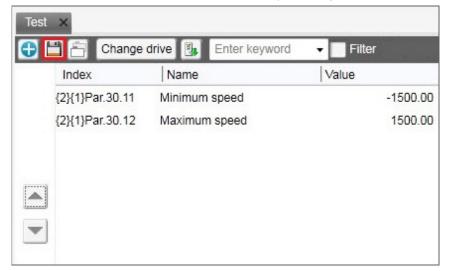
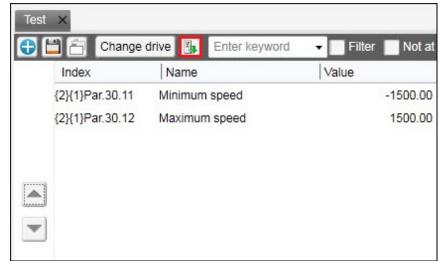


Figure 84. Save parameter to file icon

7. When connecting the next drive open the created custom parameter window by clicking File -> Open -> Custom parameter file.

You can now see the online values of the new drive.



8. Copy the offline parameter values to a new drive by clicking **Download to device**.

Figure 85. Download to device

Working with parameter files

Saving/Downloading parameter files

The following example shows how to:

- save parameters to a file
- copy/download parameters to a drive.
- 1. Start up the drive.
- 2. Click Save parameters to file icon in the parameter window.

ZCU1	2_1 {2}{1} ×				
	1 torque	✓ Filter	Not at default	Select columns:	Ŧ
Index	Save parameters to f	ile	Value	Unit	Min
•	1. Actual va	lues			

Figure 86. Save parameters to file icon

3. Select a folder, enter a name for the dcparamsbak file and click Save.

Save in	: 🚺 MultiBackup	8Dodes	- 🗧 🕂 📰 -	
Ca	Name			Date
Recent Places	1_8_09.03.2	012.dcparamsbak		9.3.2
Recent Places	1_7_09.03.2	012.dcparamsbak		9.3.2
	1_6_09.03.2	012.dcparamsbak		9.3.2
Desktop	1_5_09.03.2	012.dcparamsbak		9.3.2
(All and a	1_4_09.03.2	012.dcparamsbak		9.3.2
6778	1_3_09.03.2	012.dcparamsbak		9.3.2
Libraries	1_2_09.03.2	012.dcparamsbak		9.3.2
	1_1_09.03.2	012.dcparamsbak		9.3.2
Computer				
Network				
	•	III		Þ
	File name:	ACS880_parameterbackup	•	Save
	Save as type:	Export parameters (*.dcpara	msbak)	Cancel

Figure 87. Saving the dcparamsbak file

- To restore parameters to a drive, go to File -> Open -> Parameter file.... A separate tab opens.
- 5. Copy the parameter values to a new drive by clicking the **Download to device** icon.

You are asked to confirm the action.

1_8_0	1_8_09.03.2012.dcparamsbak					
🗊 🖽	Change drive	4	Enter keyword	-		
Index	Name	Do	wnload to device	Value		
•	1. Actual v	alue	S			

Figure 88. Download to device icon

6. If you get a message indicating that the upload of parameter values is going on, click **OK**.

At the end of the restore operation you get a report of the operation.

7. Check the parameters that have failed during the restore operation.

Note: If you use Drive composer entry you cannot modify parameter files in the offline mode. With Drive composer pro parameter values can be modified offline.

Drive composer displays the open parameter file in a tree structure.

Di Di	rive cor	mposer	pro v.1.5	.0.4 RC4
File	Edit	View	Tools	Help
C	×.	AC S8	BO {2}{1	}
All	drives	_	_	∢ ►
	drives Drives			∢ ►
	Drives	30 {2}{1}		

Figure 89. Parameter file in a drive tree

Note: Drive composer does not check the drive type and software version when copying parameters from a custom parameter window or a parameter file to a drive. Only visible parameters and ID run results are copied to a drive when the download command is used.

Use the backup/restore operation, for example, for the application program (Control Builder Plus program), panel home view configurations and different user settings. With the restore function you can also define how different parts are handled during the restore operation, for example, ID run results can be restored or cleared during the restore operation.

Note: The backup/restore function is available only with Drive composer pro.

80 Parameter window

Comparing drive data (pro)

Note: Both versions of Drive composer have **Not at default** function for listing userchanged parameters. The **Compare drive data** function compares parameter values.

With Drive composer pro you can compare parameters between

- two drives
- two parameter files
- drive and parameter file.
- 1. Go to Tools -> Compare drive data (Alt+C).

ZCU12_1 {2}{	1} ZCU12	2_1 {2}{1}.dcparamsbak	Compare driv	e data 🛛 🗙			
Open	Export	Show differences	Compare all				
Drive A			Dri	ve B			
ZCU12_1 {2	2){1}		• Z(CU12_1 {2}{1}.	dcparamsbak		•
							Start compare
Group i Nam	e	Value	Unit	Value	Unit	Name	

Figure 90. Comparing drive parameters

- 2. In a PC tool network, select drives from **Drive A** and **Drive B** drop-down menus.
- 3. To open a parameter file for comparison, click Open.
- 4. To see the parameter list without differences, deactivate **Show differences** check box.
- 5. Click Start compare.

Note: The operation may take a some time to compare two different parameter structures.

ZCU12_1	{2}{1} ZCU12_1 {2}{1}.	dcparamsbak Com	pare drive	data ×			
Open	Export O Sh	iow differences 🔘 Compa	are all				
Drive A			Driv	e B			_
ZCU12	_1 {2}{1}	•	ZC	U12_1 {2}{1}.dcp	aramsbak		
						Start con	npare
Group i	Name	Value	Unit	Value	Unit	Name	
🔊 50. Fi	eldbus adapter (FBA)						
50.1	FBA A enable	Disable	NoUnit	Option slot 1	NoUnit	FBA A enable	
50.3 ⁻	FBA B enable	Option slot 2	NoUnit	Disable	NoUnit	FBA B enable	
▲ 53. FE	BA A data out						
53.1	FBA data out1	None	NoUnit	CW 16bit	NoUnit	FBA data out1	
▲ 54. FE	BA B settings						
54.1	FBA B type	Ethernet	NoUnit	None	NoUnit	FBA B type	
54.4	IP configuration	Dyn IP DHCP	NoUnit	0	NoUnit	FBA B Par4	
54.1	T16 scale	99	NoUnit	0	NoUnit	FBA B Par19	
54.20	Timeout time	20	NoUnit	0	NoUnit	FBA B Par20	
54.2	Timeout mode	Control RW	NoUnit	0	NoUnit	FBA B Par21	
54.2	Word order	HILO	NoUnit	0	NoUnit	FBA B Par22	
54.2:	FBA B Par23	128	NoUnit	0	NoUnit	FBA B Par23	
54.24	FBA B Par24	128	NoUnit	0	NoUnit	FBA B Par24	

The following figure shows an example of the result.

Figure 91. Result of a comparison

6. To export the result to a text (*.txt) file, click the **Export**.

Note: Click the >> << buttons to copy parameter values from Drive A to Drive B.

82 Parameter window



Monitor window

Contents of this chapter

This chapter describes the monitor window and its use.

Monitor window

In Drive composer you can monitor the operation of connected drives. In the online mode, the monitor window shows signal values in graphical or numerical format. The monitor data can be saved to a file for later use.

With Drive composer entry you can monitor 2 signals using 1-second time stamping.

With Drive composer pro you can monitor 32 signals. 8 signals can be monitored with fast time stamping. If Drive composer pro is used with an ACS880 drive, it is possible to monitor 1 signal per 1-ms time interval.

The monitor window is always a tabbed window, in other words, there is only one monitor window available.

User-made monitoring settings (selected signals, y-scalings for signals, pen colors, number of grids etc.) are saved by default. In other words, when you open the tool, there are always the latest settings available.

Resizing the monitor window

When you start Drive composer the monitor window is in the minimized position and you have to lift it in the following way before you can start monitoring.

• You can resize the monitor window by clicking the title bar with the primary mouse button and dragging it upwards.

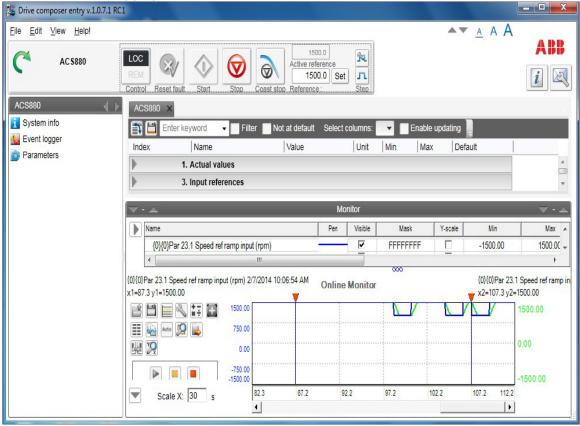


Figure 92. Monitor window

- You can resize the monitor window with the Minimize, Maximize and Split monitor buttons included in the Monitor menu bar.
- You can lift the monitor window by clicking the arrow buttons in the title bar.

Adding parameters/signals for monitoring

There are two ways to add parameters/signals to the monitor window:

• Right-click a parameter/signal in the parameter window and select Send to monitor.

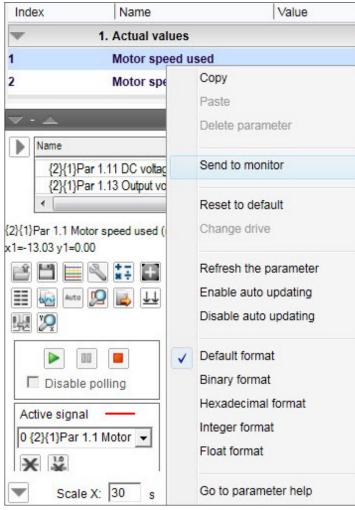


Figure 93. Send to monitor command

• Click the **Add signal** icon on the configurations and control area in the monitor window.

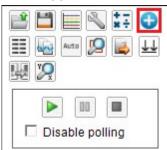


Figure 94. Icons on the configuration and control area in the monitor window

Select parameters from the Drive parameters list by double-clicking them or select a parameter and click Add button. You can add maximum of 26 parameters in Drive Composer pro and 8 parameters in Drive Composer entry.

Note: With Drive composer pro you can select signals/parameters from many different drives. Change the drive from the Drive list as shown in the following figure.

86 Monitor window

Note: In the PC tool network via Ethernet or with a panelbus, it is recommend that you select **Disable polling** to enable the best sampling result for monitoring. The status of the drive(s) cannot be read before you have unselected **Disable polling**.

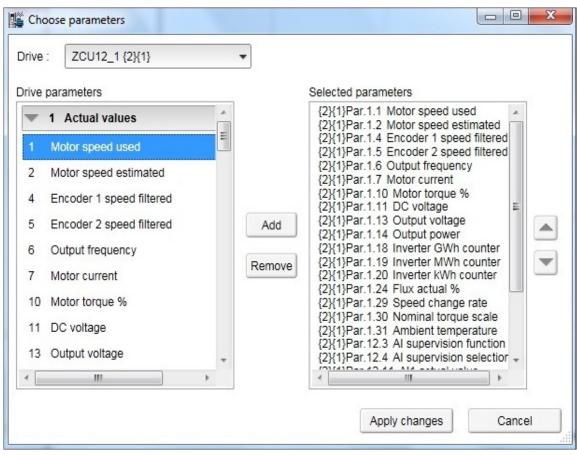


Figure 95. Drive list

The selected signals appear in the legend area.

To change the scalings of the y-axis of selected parameters/signals, click the Min or Max column in the legend area.

Active signals can be changed from the pull-down menu on the left side of the graph area.

All the other signal scalings are performed on the right side of the legend area. The right side y-scalings can be hidden by removing the check mark from the Y-scale column check box.



Figure 96. Changing the pen color and style in the legend area

You can change the color and thickness of the pen only after you have minimized, that is hidden, the legend area with the **Arrow** button on the left (see the figure above).

To change the scalings of the y-axis for selected parameters/signals, click the Min or Max column in the legend area.

Monitor window components

The monitor window consists of the following parts:

- Configuration and control settings
- Graph area
- Y-axis
- X-axis
- Legend area
- Limit, color settings.

Configuration and control settings

lcon	Description
Ď	Opens the saved monitored file to the graph area, which can be done only after monitoring has been stopped. File extension is *.dcemon or *.dcpmon.
	Note: If you have an online connection and want to start a new monitoring session after viewing opened monitored data, you can click the Monitor configuration icon.
	Saves the accumulated monitor data to a monitored data file. File extension is *.dcemon for the entry version and *.dcpmon for the pro version.
	Chart configuration can be used to set the colors for grids, number of grids, background color, color of alarm pen etc.
Se la construcción de la constru	Opens the Monitor settings window where you can modify the monitor settings and the select the sample interval time for monitoring. You can also set the method for starting and/or stopping monitoring (by hand/time). You have to select the HD where the saved data is stored.
	Note: The monitored data is saved cyclically to the selected file. Created monitoring configuration can be saved and restored from Monitor settings window.
2 2 2	Allows you to create an arithmetic signal for monitoring by using two signals used in monitoring. Available operations are ADD, SUB, MUL and DIV. Note: Remember to save settings in a workspace.
•	Opens a dialog where you can add or remove one signal or several signals from the monitor configuration.
	Note: You can use the Add signal function only when monitoring has been stopped.
	Shows the signal values in text format. Only the values seen in graph area are included in the numeric signal value list.
2	Copies the monitoring graph to a clipboard.
	Scales the y-axis automatically.
Auto	Note: Zooming is not possible in the Autoscaling mode.
	Resets both x- and y-axis zooming to original 100%.
	You can export the monitored data in csv format to a PC. Exported data can analyzed with other tools. Use the Tab key for delimiting the columns.File extension is *.dcexp.
11	Aligns signals.
	Selects or changes the drive.
¥ Q	Zooms in the x- and/or y-axis up to 1000%.

Monitor controls

lcon	Description
	Starts recording data in the selected drives and displaying it on the screen.
	Pauses monitoring on the screen but monitoring continues on the background. When you click the Pause icon again, all values are seen and monitoring continues normally.
	Stops recording data in the selected drives. The graph or numerical values remain on the screen. The graph can be saved for later purposes.

Active signal

The Active signal area consists of functions that can be done with the selected active signal. The signal can be changed from the pull-down menu.

Active signal	
¥ 10	•
Search	< >
0	
Above	-

Figure 97. Active signal area

The main functions are the following:

lcon	Description
*	Allows you to see the numeric values of the measuring points for the active signal. See figure <i>Measuring points for the active signal</i> . Note: This functionality works only if you have zoomed in enough in the graph area.
*	Allows you to see the measuring points of the active signal. See figure <i>Measuring points for the active signal</i> . Note: This functionality works only if you have zoomed in enough in the graph area, that is, if the length of the x-axis is short enough.
<	Searches to the left. The following search conditions can be selected from the pull-down menu: Above, Below or Either. See figure <i>Search functionality</i> .
>	Searches to the right. The following search conditions can be selected from the pull-down menu: Above, Below or Either. See figure <i>Search functionality</i> .

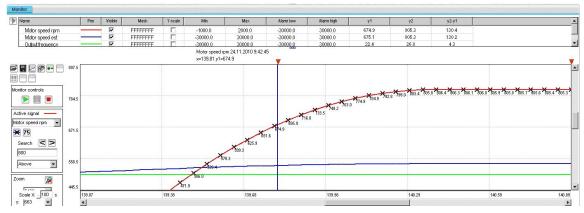


Figure 98. Measuring points for the active signal

Name	Pen	Visible	Mask	Y-scale	Min	Max	Alarm low	Alarm high	y1	y2	y2.y1		
Motor speed rpm	_	~	FFFFFFFF		-1000.0	2000.0	-30000.0	30000.0	803.4	799.9	-3.4		
Motor speed est			FFFFFFF	E	-30000.0	30000.0	-30000.0	30000.0	803.4	799.9	-3.4		
Output frequency		V	FEFFFFFF		-30000.0	30000.0	-30000.0	30000.0	26.7	26.6	-0.1		
					Motor speed x=140,32 y1:	rpm 24.11.2010 9:4. =803.4	2.46						
	0.00						ĭ	1					
ĀA													
nitor controls													
	250.0												
tive signal ——													
tor speed rpm 💌							4						
75	500.0						1						
Search < >							1						
800							_						
Above 🔻	250.0												
iom 👰													
-10	0.00												
Scale X: 100 s	100.00			116.63		133.27		149.91		166.55		183.19	199

Figure 99. Search functionality

Zooming

To enlarge the graph and take a closer look at the details, follow these steps:

- 1. To set the starting corner for the enlargement, place the mouse cursor in the graph area and press down the primary mouse button.
- Drag to the opposite desired corner, and release the button. The part of the graph that was inside the selection rectangle zooms out to fill the graph area.
- 3. To reset the zoom tool, click the **Reset zoom** icon.

You can also use the zooming tool by selecting independent values from x and y pull-down menus.

Note: Monitoring is paused during zooming. To continue monitoring, click the **Reset zoom** icon shown in the figure below.

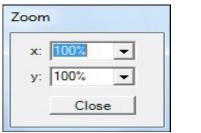




Figure 100. Zoom tool

Panning

The graph can be panned by dragging the graph with the right mouse button pressed down.

Legend area functions

The legend area shows selected signals. You can perform the following actions in the legend area:

- Change the color of the pen, thickness and style of the pen by minimizing the legend area and setting the values of each signal. See figure *Legend area functions*.
- Make signals visible or invisible by clicking the check box in the Visible column.
- Set a bit mask for monitoring. When you double-click the value in the Mask column, a new window opens allowing you to select bits for monitoring.
- Make Y-scalings visible or invisible by clicking the check box in the Y-scale column.
- Set values for y-axis scaling. You can modify the minimum and maximum values by clicking them and entering a new value. Press Enter to enforce the new value or press Esc to restore the value.

Note: If you do not see immediate changes in the graph area, check that autoscaling is not enabled.

- Set alarm limits for monitored signals. The color of a signal changes when the limit in the Alarm low or Alarm high column is reached. The color and style for the pen are selected from **Chart settings**.
- See the double cursor tool, y1 and y2 values and y2—y1 and x2—x1 differences.

Name	Pen	Visible	Mask	Y-scale	Min	Max	y1	y 2	y2-y1	x2-x1	Alarm low	Alarm high	
{2}{1}Par 1.5 Encoder 2 speed filtered (rpm)	0.001	V	FFFFFFF	V	-30000.00	30000.00	-	-		-	0.0000	30000.00	
{2}{1}Par 1.6 Output frequency (Hz)		V	FFFFFFF	V	-500.00	500.00		-	-	121	-500.00	500.00	
{2}{1}Par 1.7 Motor current (A)		V	FFFFFFF	v	0.00	30000.00	-	-	-	153	0.00	30000.00	-
						000							

Figure 101. Legend area functions

Graph area functions

The monitor window and data logger window have similar graph area facilities for displaying signal values. Their usage is described here. Before Drive composer starts monitoring online, the OnLine monitor text is seen in the graph area. When monitor files are viewed, the DataFile Viewer text is seen in the monitor window.

The graph area shows the selected signal values with different colors. The x-axis represents Time and can be set from 0 to 120s. You can change the values in online monitoring mode. Scalings of the y-axis are changed in the legend area.

For data logger files, an orange arrow-head on the x-axis indicates where triggering has occurred. Data can be combined from several files to one graph.

Double cursor tool

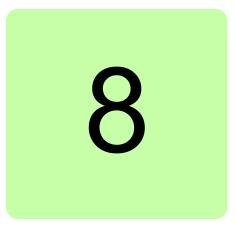
With the cursor tool, you can see the exact values of the signals at two positions in the graph area. You can move the position of cursors by clicking the primary mouse button down on the red cursor tool icon and moving it. While the mouse button is pressed down, you can move the cursor line to the left and right.

The time stamp of the cursor tool is shown in the header of the cursor tool. This is shown for the active signal. The time stamp changes if active signal is changed. The values for y1 and y2 are shown in the legend area. Signal value differences are shown in the column y2—y1. The time difference for x2—x1 is also shown in the figure below.

)	Name	Pen	Visible	Mask	Y-scale	Min	Max	y1	y2	y2-y1	x2-x1	Alarm low	Alarm high	
	{2}{1}Par 1.5 Encoder 2 speed filtered (rpm)		V	FFFFFFF	V	-30000.00	30000.00				4	0.0000	30000.00	
	{2}{1}Par 1.6 Output frequency (Hz)		V	FFFFFFF	V	-500.00	500.00	121	-	÷	-	-500.00	500.00	
	{2}{1}Par 1.7 Motor current (A)		V	FFFFFFF	V	0.00	30000.00	1.50			-	0.00	30000.00	
	2}{1}Par 1.1 Motor speed used (rpm) 1/29/2014 1:5 1=-25.05 y1=-	51:21 PM				{1}Par 1.1 Mote =-5.06 y2=-	ooo or speed used (rpm) 1/29/	2014 1:51	:41 PM				

Figure 102. Double cursor tool

94 Monitor window



Workspace handling

Contents of this chapter

This chapter describes the workspace functionality.

Overview

Workspace consists of the user interface status, such as parameter windows and custom parameter windows.

The current workspace status can be saved to a file and restored later.

Note: You cannot save/restore the following status data:

- drive control status
- If a drive has been controlled locally with Drive composer when the workspace is saved, the workspace is saved without the change in the drive control status.
- content, status and zooming levels of a stopped, paused or running monitor.

Note: Do not edit a workspace or graph file. The workspace (.dcxml) and monitored data (.dcmon) files can contain binary data. For example, if the default workspace file is corrupted, Drive composer does not open. If Drive composer does not open, delete your default (.dcxml) file from the PC and open Drive composer again.

Creating a workspace and using it as a default workspace

- 1. Make a connection to a drive.
- 2. Resize the monitor window to half a screen.
- 3. Create a new custom parameter window by clicking **File** -> **New..**-> **Custom parameter set** and name it "Own limit window".

File	Edit View Help!							
	New	•	Custom parameter set Ctrl+					
	Open	,	V	V		Ø	ACTIN	
	Save workspace	Ctrl+S	et fault	Start	Stop	Coast stop	p Refe	
	Save workspace as default	Ctrl+D						
	Exit	Alt+F4						

Figure 103. Custom parameter set

4. In the File menu, click Save workspace to save the workspace.

D 🎼	rive composer entry v.1.0.7.1 RC	1
File	Edit View Help!	
	New	•
	Open	•
	Save workspace	Ctrl+S
	Save workspace as default	Ctrl+D
	Exit	Alt+F4

Figure 104. Save workspace command

- 5. Create another custom parameter window and name it "Own reference window".
- 6. Select floating windows by clicking View -> Floating windows.
- 7. Enter keyword "Limit" in the Enter keyword field of the main parameter window.
- 8. Select parameters in the main parameter window and drag and drop or copy them to custom parameter window Limit.
- 9. Clear the search result and enter keyword "ref" in the Enter keyword field.
- 10. Select parameters in the main parameter window and drag and drop or copy them to custom parameter window Own reference window.
- 11. Close the main parameter window.
- 12. Click Event logger icon in the drive list on the left.

13. Click **File** -> **Save workspace** and name it "OwnWorkspaceFor_ACS880". See figure *Save workspace command*.

Save As		<u>? X</u>
Savejn:	C Workspace	• 🖻 🖆 📰 •
My Recent Documents Desktop My Documents My Computer: FIHEL-L-4001	 log 4_ikkunaa_cascade_auki.duxml ACS880ShortList.duxml DriveComposerEntry1011.duxml Du1008.duxml DU10014LaskennallisiaSignMukana5.duxml DU_Pro.duxml fhhfhf.duxml fhhfhf.duxml ryhmä7.duxml ttt.duxml Worksapce1005.duxml Worksapce1005_1 ikkuna.duxml Worksapce1009.duxml Worksapce1009.duxml Worksapce1009.duxml Worksapce1009.duxml Worksapce1009.duxml 	 Worksapce1009Vapaastiasetetut.duxml Worksapce1009Vertical.duxml Worksapce1009VerticalDefault.duxml Worksapce_5windows.duxml Workspace1004Beta.duxml Workspace1005.duxml Workspace1011_5_windowFloat.duxml Workspace_Tallennettu_2.duxml WorkspaceDemo.duxml WorkspaceDUPro10016Ikkunaa.duxml WorkspaceSaveDuringMonitoring.duxml WorkspaceSpanish.duxml WorkspaceWithChangedGrids.duxml WorkspaceWithCompare.duxml
My Network Places	File <u>n</u> ame: OwnWorkspaceFor_ACS88 Save as <u>type:</u> Workspace (*.duxml)	Cancel

Figure 105. Name for your own workspace

14. Close the connection to the drive and make a new connection.

98 Workspace handling

15. Click **File** -> **Open.** -> **Open workspace** and open the workplace that you have saved.

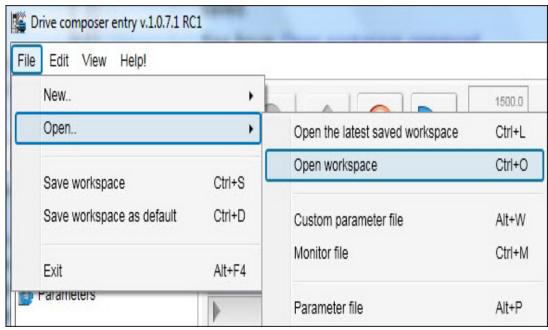


Figure 106. Open workspace command

The workspace is ready to use for commissioning and maintaining drives.

The workspace can also be saved as a default workspace which opens automatically when Drive composer is started.



Event logger

Contents of this chapter

This chapter describes the event logger view and its use.

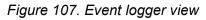
Event logger view

The event logger view displays the contents of an event logger of a connected drive. The contents of an event logger can be faults (stopping the drive), alarms or events. See the figure below.

With some drives there can be more data of a fault in the monitor window.

Note: Fault logger data can also be seen from other faults than the latest active faults.

Refresh log							
Drive	Icon	Time	Fault	Description	AUX code		
ZCU12_1 {2}{1}	8	19.02.2013 21:34:40.432	64FF	Fault reset			
ZCU12_1 {2}{1}	3	18.02.2013 19:52:36.526	64FF	Fault reset			
ZCU12_1 {2}{1}	۵	18.02.2013 19:48:01.948	6591	Backup/Restore Timeout		Par.90.1 = 0.00 rpm Par.1.7 = 0.00 A Par.6.11 = 0x0000 1233 NoUnit Par.6.1 = 0x0000 0477 NoUnit Par.1.11 = 568.38 V Par.1.10 = 0.0 %	
ZCU12_1 {2}{1}	⚠	08.02.2013 20:44:03.557	A6A6	Supply voltage unselected			
ZCU12_1 {2}{1}	Å	08.02.2013 20:41:34.876	A6A6	Supply voltage unselected			
ZCU12_1 {2}{1}	Â	08.02.2013 20:30:08.856	A6A6	Supply voltage unselected			
ZCU12_1 {2}{1}	À	08.02.2013 20:27:53.846	A6A6	Supply voltage unselected			
ZCU12_1 {2}{1}	۵	08.02.2013 20:19:45.148	64B1	Internal SSW fault	80	Par.90.1 = 0.00 rpm Par.1.7 = 0.00 A Par.6.11 = 0x0000 0000 NoUnit Par.6.1 = 0x0000 0000 NoUnit Par.1.11 = 0.00 V Par.1.10 = 0.0 %	
ZCU12_1 {2}{1}	8	08.02.2013 20:14:58.631	6581	Parameter system	10D		
ZCU12_1 {2}{1}	0	08.02.2013 20:14:58.535	64B1	Internal SSW fault	AO		
ZCU12_1 {2}{1}	0	08.02.2013 20:14:58.532	64A1	Internal file load	С	Par.90.1 = 0.00 rpm Par.1.7 = 0.00 A Par.6.11 = 0x0000 0000 NoUnit Par.6.1 = 0x0000 0000 NoUnit Par.1.11 = 0.00 V Par.1.10 = 0.0 %	



The event logger always relates to a single drive and resides in its window.

The Icon column shows the following alarm and fault icons:

- Red circle with a white cross (x) means that the drive has a fault.
- Yellow triangle with an exclamation mark means that the drive has an alarm.
- Grey circle or triangle means that the fault or alarm has disappeared from the drive.

The time stamp for faults, alarms and events comes from the drive.

Faults, alarms and events can be sorted by clicking the header of the Fault column.

Fault data logger

The **Fault data** icon in the Event logger view shows that the drive has fault data that can be seen with a monitor component. The icon is visible only if the drive sports the functionality.

I				
I				

Figure 108. Fault data icon

When you click the icon, the following message appears: "Please wait. Loading fault data appears". When the message box disappears, the data has been loaded.

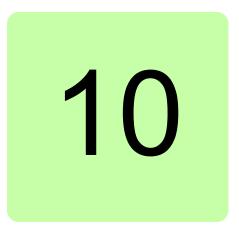
Event logger ZCU12_1 {2}{	[1] ×			
Refresh log				
Drive	Icon Time	Fault Description	AUX code	
ZCU12_1 {2}{1}	(2) 19.02.2013 21:34:40.43	32 64FF Fault reset		*
ZCU12_1 {2}{1}	(2) 18.02.2013 19:52:36.52	26 64FF Fault reset		
ZCU12_1 {2}{1}	8 18.02.2013 19:48:01.94	18 6591 Backup/Resto	e Timeou	Par.90.1 = 0.00 rpm Par.1.7 = 0.00 A Par.6.11 = 0x0000 1233 NoUnit Par.6.1 = 0x0000 0477 NoUnit Par.1.11 = 568.38 V Par.1.10 = 0.0 %
ZCU12_1 {2}{1}	₫ 08.02.2013 20:44:03.55	57 A6A6 Supply voltage	unselect	S
ZCU12_1 {2}{1}	08.02.2013 20:41:34.87	76 A6A6 Supply voltage	unselect	*
4				•
▼ - ▲		Monitor	_	▼ • ▲
{2}{1}Par 1.1 Motor s	speed used (rpm) 🚽 💻 R	Red 💌 Solid 💌 2 px	▼ Visible Min: -	30000.00 Max: 30000.00 Alarm I
{2}{1}Par 1.1 Motor s {2}{1}Par 1.1 Motor speed used x1=-25.10 y1=-			▼ Visible Min:-	30000.00 Max: 30000.00 Alarm I {2}{1}Par 1.1 Motor speed used (rpn x2=-5.03 y2=-
{2}{1}Par 1.1 Motor speed used x1=-25.10 y1=-		Red 💌 Solid 💌 2 px	▼ Visible Min:-	{2}{1}Par 1.1 Motor speed used (rpn
{2}{1}Par 1.1 Motor speed used	(rpm) 1/29/2014 1:51:21 PM	Red 💌 Solid 💌 2 px	▼ Visible Min: -	{2}{1}Par 1.1 Motor speed used (rpr x2=-5.03 y2=-
{2}{1}Par 1.1 Motor speed used x1=-25.10 y1=-	(rpm) 1/29/2014 1:51:21 PM	Red 💌 Solid 💌 2 px	Visible Min: -	{2}{1}Par 1.1 Motor speed used (rpr x2=-5.03 y2=-
{2}{1}Par 1.1 Motor speed used x1=-25.10 y1=- x1=-25.10 y1=- x1=	(rpm) 1/29/2014 1:51:21 PM	Red 💌 Solid 💌 2 px	▼ Visible Min: -	{2}{1}Par 1.1 Motor speed used (rpr x2=-5.03 y2=-
{2}{1}Par 1.1 Motor speed used x1=-25.10 y1=-	(rpm) 1/29/2014 1:51:21 PM	Red 💌 Solid 💌 2 px	▼ Visible Min: -	{2}{1}Par 1.1 Motor speed used (rpr x2=-5.03 y2=-

Figure 109. Fault data logger in the monitor window

Save the fault data.

Note: To continue the normal monitoring, click the **Monitor configuration** icon in the Monitor controls box.

102 Event logger



Diagnostics

Contents of this chapter

This chapter describes how to troubleshoot a drive with the **Support package** button of Drive composer and a data logger included in the drive.

Support package

By clicking the **Support package** button, you can collect troubleshooting data and send it to the support personnel for analysis.



Figure 110. Support package button

Drive composer creates a SupportFiles.dcsupport file to the email program installed in the PC. The file can also be saved manually. The support package includes different files depending on the drive type. All parameters, contents of the event logger and System info are always available.

To open the contents of the SupportFiles.dcsupport file with WinZip, rename the file as SupportFiles.zip.

🖳 岁 🤣 🗾 🗢 WinZip Pro - S	SupportFiles.zip				_ _ X
Home Backup	Tools Setting:	s Window He	lp		1
Add Files Encrypt Compress Se		-Click Unzip	zip and Insta zip Options izip Entire W press	•	le View
Name	Туре	Modified	Size	Ratio	Packed
💐 BackupData.dcparamsbak	DCPARAMSB	1/29/2014 2:33 PM	105,220	3%	102,029
🔮 Versions.xml	XML Docum	1/29/2014 2:33 PM	355	36%	226
🔮 FaultLog.xml	XML Docum	1/29/2014 2:33 PM	3,645	83%	606
8519681.log	Text Docume	1/29/2014 2:33 PM	30,584	99%	305
(ஊ) SystemInfo.xml	XML Docum	1/29/2014 2:33 PM	7,833	87%	995
					D
elected 0 files, 0 bytes	Т	otal 5 files, 145KB			

Figure 111. Contents of the SupportFiles.dcsupport file

The BackupData.dcparamsbak file can be opened with Drive composer. Other files can be opened with standard windows programs. In the figure below the FaultLog.xml file has been opened with Microsoft Excel.

X	🚽 🤊 • 🍽 • 🖙		В	ook2 - Mie	crosoft Excel		Table T	ools – – ×	3
F	ile Home Inser	t Page Layout	Formulas [Data Re	eview View	Acrobat PDF-XChange 2	012 Desig	yn 🛆 🕜 🗆 🗗	ж
Pa	ste booard G	• 11 • A • 🔄 • 🔗 • <u>A</u> Font		₩ - ₩-	General ▼ \$ ▼ % ・ *.00 .00 Number 5	Conditional Formatting * Format as Table * Cell Styles * Styles	Insert ▼ Delete ▼ Format ▼ Cells	Σ · A Sort & Find & C · Filter · Select · Editing	
	A1 -	fx Tir	ne						~
1	А	В	С	D	E	F	G		E
1	Time	▼ Drive ▼	FaultCode	Туре 💌	AuxCode 💌	Description	🕶 FileRef 💌	Extra	F
2	19.02.2013 21:34:40.4	32 ZCU12_1 {2}{1}	64FF	F-		Fault reset			1
3	18.02.2013 19:52:36.5	26 ZCU12_1 {2}{1}	64FF	F-		Fault reset			=
4	18.02.2013 19:48:01.9	48 ZCU12_1 {2}{1}	6591	F		Backup/Restore Timeout	8519681	Par.90.1 = 0.00 rpm	
5	08.02.2013 20:44:03.5	57 ZCU12_1 {2}{1}	A6A6	E-		Supply voltage unselected	ł		
6	08.02.2013 20:41:34.8	76 ZCU12_1 {2}{1}	A6A6	E		Supply voltage unselected	ł		
7	08.02.2013 20:30:08.8	56 ZCU12_1 {2}{1}	A6A6	E		Supply voltage unselected	t		
8	08.02.2013 20:27:53.8	46 ZCU12_1 {2}{1}	A6A6	E		Supply voltage unselected	ł		
9	08.02.2013 20:19:45.1	48 ZCU12_1 {2}{1}	64B1	F	80	Internal SSW fault		Par.90.1 = 0.00 rpm	
10	08.02.2013 20:14:58.6	31 ZCU12_1 {2}{1}	6581	F	10D	Parameter system			
	08.02.2013 20:14:58.5 Sheet1 She			F	A0	Internal SSW fault		•	-
Rea	ady						Ⅲ 100% (-	\rightarrow \neg \div)

Figure 112. FaultLog.xml file opened with Microsoft Excel

Drive application programming license

The drive application programming license N8010 is required for downloading and executing the program code on the ACS880 drive. In DriveComposerPro, select **System info** tab. Check if the appropriate license is loaded to the drive. If the required license code is not available, contact ABB representative.

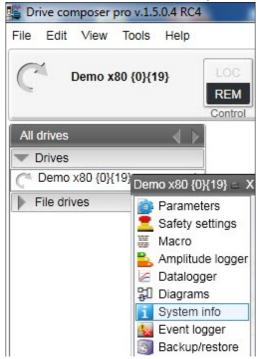


Figure 113. System info command

System info

The System info tab provides basic information about the drive and its options, for example, drive type code and firmware version.

Drive name:	ZCU12 1	Set	1/1/2013 2:38:23 AM	1/29/2014 2:39:06 PM -	Set time
Drive name:	20012_1	Sel	1/1/2015 2:58:25 AM	1/29/2014 2.39.06 PW	Settime
Products					
Drive type:		ACS880			More
Drive model:		Not selec	ted		More
Serial number:					Licenses
Firmware version	1:	AINF7 v1	.62.200.22		Livenses
Description:		Land and the second			
Drive name:		ZCU12_1			
MRP code:					5
Application					
Application name	9	Applicatio	on123		More
Application version	on	0.0.0.0			wore
Application id		C7.4D.27	.87		
Int application na					
Int application ve	rsion				
Int application id					
Option modules	6				
Embedded ethe	rnet				

Figure 114. System info

You can also set the time for the drive and name the drive.

Data logger (pro)

ABB drives have data logger(s) that can record data from various signals of a drive even if the drive is not connected to a PC. A Datalogger is operated with the Datalogger view.



Figure 115. Data logger configuration

The data collecting can be stopped with a specific stop command or automatically when a triggering condition is true in the drive. After data collection stops you can read and study the data in Drive composer pro.

The data logger view resembles the monitor window. Normally the data logger view provides data from a single drive.

Datalogger ZCU12_1	2 } {1} ×							
Refresh								
Logger Sample interval (us Post trigger count Sampling time Infinity s Stopped	0	gger	y ▼ x 1					
Trigger configuration	n Trigger :	#1	•	Signal	¢			
	Trigger : Disabler	d	•					
Apply Trigger Type Triggers	Trigger	d	•	Signal Hysteresis	Logger	Triggered		
Apply Trigger Type Triggers ID Type Trigger #1 Disabled	Trigger : Disabler	d	•		Logger User logger	Triggered		
Apply Trigger Type Triggers ID Type Trigger #1 Disabled Trigger #2 Disabled	Trigger : Disabler	d	•		Logger User logger User logger	Triggered		
Apply Trigger Type Triggers ID Type Trigger #1 Disabled	Trigger : Disabler	d	• Level		Logger User logger	Triggered		

Figure 116. Data logger view

Data logger settings

The data logger settings window contains the following functions:

- Data logger commands
- Data logger content configuration
- Data logger trigger configuration

Data logger commands

Button	Description
	Start button records data in the current Logger of the drive.
•	
	Stop button ends recording data in the drive.
	Trigger button triggers the associated Logger.
1	
	Upload button moves data from the drive and draws it to the monitor window.
Upload	
	Apply button is used for Logger and Trigger conditions.
Apply	

Data logger content configuration

With the data logger content configuration you can determine which data logger of a drive is used.

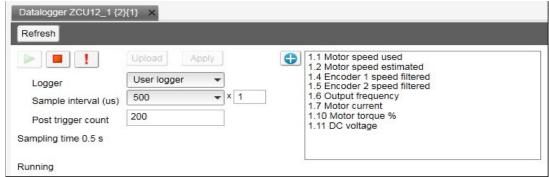


Figure 117. Data logger content configuration

- **Logger** determines which logger settings are modified. A drive has user logger(s) and factory logger(s). Factory logger settings cannot be modified.
- **Sampling interval** determines in microseconds how often the logger reads samples of the signal values. The time level shows the available lengths of the internal cycle time of the drive.
- **Post trigger count** specifies how many samples are stored after the triggering condition occurs.
- **Sampling time** shows the length of the sampling time with a selected number of signals and a selected sample interval.
- **Logger signals panel** shows a list of the signals selected to record. You can add/remove a signal by clicking the Add signal icon.

Note: The maximum number of signals that a logger can record at one time depends on the drive. Click **Apply** after making the changes.

Data logger trigger configuration

With the data logger trigger configuration you can determine trigger conditions for each trigger.

Apply	Frigger	Trigger	#1	•	Signal		
1	Гуре	Disable	d	-			
riggers							
Triggers ID	Туре	Timelevel	Variable	Level	Hysteresis	Logger	Triggered
200000.00.000	1.	Timelevel	Variable	Level	Hysteresis	Logger User logger	Triggered
ID	Disabled	Timelevel	Variable	Level -	Hysteresis	1 S. 7 7 S. 1	Triggered
ID Trigger #1	Disabled Disabled	Timelevel	Variable - -	- 1	-	User logger	Triggered

Figure 118. Data logger trigger configuration

Adding a trigger

1. To modify the conditions of a trigger, select the trigger from the **Trigger** drop-down menu.

Trigger 1 is normally used for user logger 1, Trigger 2 for user logger 2 etc.

- 2. Choose the type for the triggering condition from the **Type** drop-down menu. Following are the alternatives (however, not all of them are available at all times):
 - Bit mask stops according to the bit mask of the selected signal.
 - **Disabled** can temporarily disable a trigger condition.
 - **Falling edge level** stops according to the selected signal, triggering level and hysteresis values.
 - Fault stops when the drive reports a fault.
 - **Event** stops when the drive reports an event.
 - **Rising edge level** stops according to the selected signal, triggering level and hysteresis values.
 - **Warning** stops when the drive reports a warning.
- 3. If you use Rising edge level of Falling edge level as the type for the triggering condition, see *Using the level triggers*.
- 4. Click Apply.

Using the level triggers

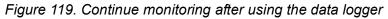
When condition Rising edge level is used, the function wakes up when the actual value of the triggering signal is below the triggering level - hysteresis. Similarly, when condition Falling edge level is used, the function wakes up when the actual value of the triggering signal is above the triggering level + hysteresis.

Rising edge	Triggering signal is below the triggering level when the data logger is started: Triggering occurs when the signal goes above the triggering level. Triggering signal is above the triggering level when the data logger is started: Triggering occurs when the signal goes above the triggering level, but before that the signal must go below the triggering level - hysteresis.
Falling edge	Triggering signal is above the triggering level when the data logger is started: Triggering occurs when the signal goes below the triggering level. Triggering signal is below the triggering level when the data logger is started: Triggering occurs when the signal goes below the triggering level, but before that the signal must go above the triggering level + hysteresis.

Uploading triggered or stopped data logger data

- 1. In the data logger view select a logger from the **Logger** drop-down menu. If the logger status is stopped or triggered, data can be uploaded.
- Click Upload to upload data to the monitor window.
 Note: If you want to continue normal monitoring after using the data logger, click Monitor configuration icon and select a sampling interval for monitoring.





3. Click **Add signal** icon to add signals for monitoring.

Datalogger ZCU12_1 {2}{1} ×				
Refresh				×
Upload Apply		tor speed used tor speed estimated		E
Logger	1.4 En	coder 1 speed filtered coder 2 speed filtered		
Sample interval (us) 500 v 1		tput frequency tor current		
Post trigger count 200		otor torque % C voltage		
Sampling time 0.5 s				
Stopped				
Stopped				-
▼ • ▲	Monitor		_	▼ - ▲
2}{1}Par 1.1 Motor speed used (rpm)	d 🔻 Solid	▼ 2 px ▼ 🗸 Visible N	1in: -30000.00 N	lax: 30000.00 Alarm I
{2}{1}Par 1.1 Motor speed used (rpm) 1/29/2014 2:59:27 PM x1=-10.79 y1=0.00	Online Mo	nitor	{2}{1}Par 1. x2=9.27 y2:	1 Motor speed used (rpn =0.00
🖻 🖹 🗮 🕄 📰 🖪 30000.00				10000-0
15000.00				177100
				Asper-
0.00				30000- 326885
Disable polling -15000.00				
Active signal				Fills
Scale X: 30 s		4.09	9.09 14.09	

Figure 120. Uploaded data logger data

Amplitude logger (pro)

ABB drives have an amplitude loggers that can record data from various signals of a drive. The results of an amplitude logger 1 (current) are displayed by the following curve. Each parameter represents an amplitude range and shows what portion of the samples fall within that range.

Note: Data loggers or amplitude loggers are not available for all ABB drives.

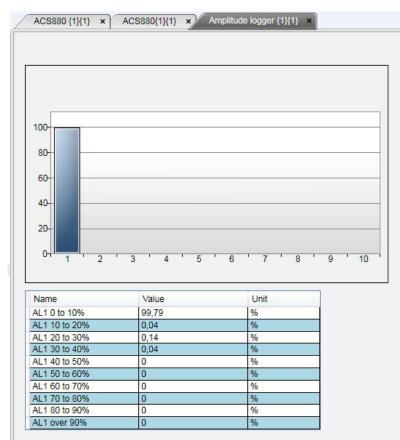


Figure 121. Amplitude logger

Macro (pro)

ABB drives have Macro functionality that can automatize a task or sequence of tasks. Macros are used for parameter value setting to multiple networked drives when custom window functionality is not sufficient. Macros may also be used for tasks which require logical or conditional parameterization of a drive.

• Right-click a drive and select Macro.

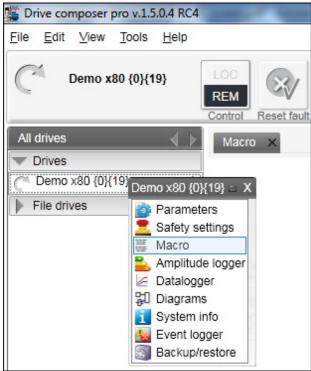


Figure 122. Macro command

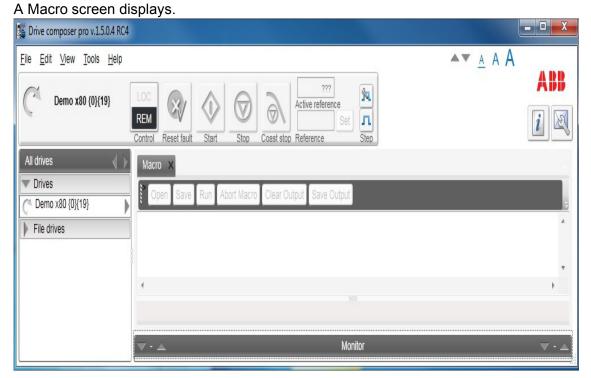


Figure 123. Macro

Macro commands

Macro language

Macro language is based on PAWN referrer to PAWN manual for general programming guides.

Note: Some PAWN features are disabled for security reasons, such as file operations and other external IO functions.

Simple example

Macro tries to read parameter 1.1 value from each target in 100 network channels.

```
main()
```

```
{
  for(new i = 0; i < 100; i++)
  {
    //note the channels are indexed ii
</pre>
```

//note the channels are indexed instead of nodes
// this should be modified according network topology

```
//change target
Target(i+1,1)
new targetName[100]
//get target name
TargetName (targetName)
```

```
//read parameter 1.1 value
new Float:val0101 = ParRead(1,1);
//output to console
printf "%s(%d,%d): %f\n", targetName, 1, 1, val0101 ;
}
```

Additional macro commands

Target

}

Changes the target of the macro commands after target command is issued.

Syntax	Returns	Example
Target (Channel, node)	0 if success, 1 if failed	Target (1, 10)

Target name

Command reads the current target name as string.

Syntax	Returns	Example
TargetName (string)	0 if success, 1 if failed	//reserve name string new name[100]
		if(TargetName(name)==0)
		{
		printf "target name is %s\n" name }

Parwrite

Command writes parameter value to current target.

Syntax	Returns	Exmaple
ParWrite (group, index, value)	0 if success, 1 if failed	//write value 1 to group 12 index 16
		ParWrite (12, 16, 1)

Parread

Command reads the parameter value to current target.

Syntax	Returns	Example
ParRead (group, index)	Parameter value or 0 if failed	//Read value of the parameter in group 10 index 5
	On error, the error message is shown in the log	new Float:val = Par- Read(10,5);
		printf "value of (%d,%d): %f\n", 10, 5, val105;

Wait

Command delays the macro execution for given time in milliseconds.

Syntax	Returns	Example
Wait (milliseconds)	0 in all cases	//wait 0.1 seconds
		Wait(100)

Endmacro

Command ends the macro execution.

Syntax	Returns	Example
EndMacro()	0 in all cases	//End execution
		EndMacro()

Gotomacro

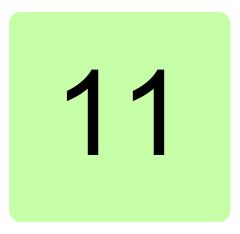
Command changes the macro execution. Currently running macro execution is terminated.

Syntax	Returns	Example
GotoMacro(string)	0 in all cases	//Change execution to macro jeejee
		new macrofilename[100]
		macrofilename = "jeejee.p"
		GotoMacro(macrofilename)

Message box

Command shows message box with ok button.

Syntax	Returns	Example
MessageBox (string)	0 in all cases	//show messagebox
		new message[100]
		message = "dingalongdangdong"
		MessageBox (message)



Control diagrams (pro)

Contents this chapter

This chapter describes the use of control diagrams helping to understand the behavior of a drive.

Control diagrams

Control diagrams provide a graphical presentation of, for example, the control chain of a drive, the speed and torque control chains and the logic of Start and Stop functions. With these diagrams it is possible to see parameter values related to certain functions. Diagrams also illustrate the position of switches according to parameter values, which helps to understand how the drive logic works. The values of parameters can be changed via control diagrams. A control diagram consists of two levels. The top level shows an overview of the diagrams and connections between them.

Note: Control Diagrams are drive-specific and they are not available for all drive types.

Note: When you connect a drive for the first time, it takes sometime to upload control diagrams from the drive. If Control Diagrams are not found in the drive, Drive composer asks to upload diagrams from the local source (PC).

118 Control diagrams (pro)

Launch Control Diagrams by clicking a drive and selecting Diagrams.

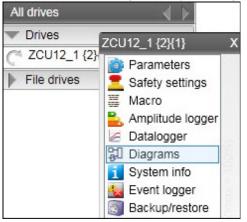


Figure 124. Selecting control diagrams from the drive tree

The top level of a diagram consists of several diagrams. To open one part of a specific diagram, click the top of a box. The figures below show an example of a top level control diagram and a lower level control diagram.

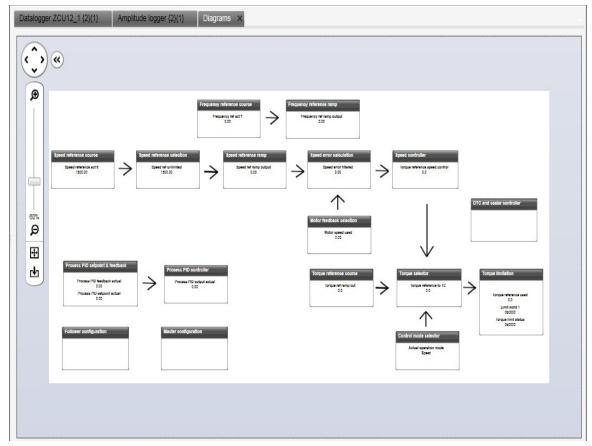


Figure 125. Top level of a control diagram

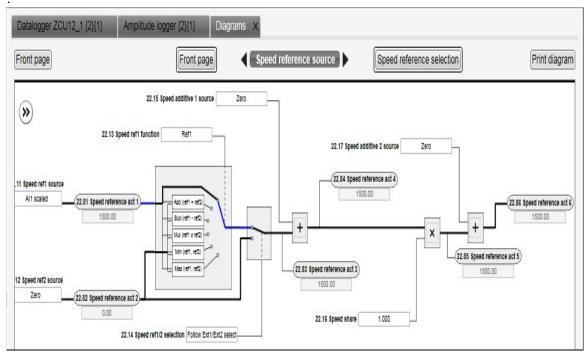


Figure 126. Lower level of a control diagram

To navigate back to the top level of a Control Diagram, click the **Diagrams top** icon. To navigate through the reference chain, click the buttons circled in the figure above.

To zoom the control diagrams, use the zooming tool in the top left-hand corner of a Control Diagram.

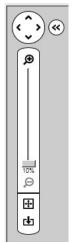


Figure 127. Zooming tool

120 Control diagrams (pro)



FSO configuration

Contents of this chapter

This chapter contains the configuration procedure of FSO-11 and FSO-12 safety functions with Drive composer pro and provides an example of how to configure these optional FSO safety functions modules.

Configuring FSO-11 and FSO-12

The safety configuration of FSO-11 and FSO-12 safety functions module is available only in Drive composer pro, DCPT-01 (code: 3AUA0000108087).

Note:

- Only trained persons are allowed to configure the safety functions.
- Stop the motor before configuring the safety functions modules. You cannot download/upload the configuration file to/from safety functions module or change the password when the motor is running.
- You need a password to copy the configuration to the safety functions.

For detailed information about FSO-11 and FSO-12, see the respective safety functions module user's manual:

- FSO-11 safety functions module user's manual (3AUA0000097054 [English]).
- FSO-12 safety functions module user's manual (3AXD50000015612 [English]).

Hardware connection

The hardware connection is common for both FSO-11 and FSO-12 safety functions module. For instructions on the hardware connections see FSO-11 safety functions module user's manual (3AUA0000097054 [English])/ FSO-12 safety functions module user's manual (3AXD50000015612 [English]).

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The following configuration description assumes that all hardware-related connections are made properly and the ID run procedure of the drive is completed.

Setting the FSO-11 safety functions with Drive composer pro

- 1. Start the drive equipped with the FSO-11 option module using the drive control panel. See *Using the drive control panel for starting the drive* on page *61*.
- 2. Right-click on drive and select **Safety settings**.

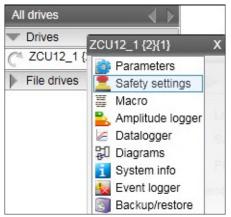


Figure 128. FSO-11: Selecting Safety settings

3. Click Upload from FSO.

Note: The motor must be stopped. Fault FSO Fault 7A8B appears on the drive.



Figure 129. FSO-11: Fault FSO Fault 7A8B

4. Type the password (8 numbers).

1 5		×
Password:	••••	••••
	Ok	Cancel

Figure 130. Typing the password

5. Double-click on the value filed and change all necessary configuration settings to match your safety configuration.

Open s	afety file	Save safety file	Upload from FSC	Download to FSO ar	nd validate	Chang	e password	J
Safety	configura	tion created 28.8.2011	10:04:50					
Group	Index	Name	V	alue	Unit	Min	Max	Default
200	1	FSO type		11		0	999	11
200	6	Stop completed outp	ut	DO X113: 7	NoUnit	0	9	0
200	7	STO IO input A		None	NoUnit	0	12	1
200	8	STO IO input B		None	NoUnit	0	12	0
200	9	STO time to zero spe	ed	4000	ms	0	3600000	3600000
200	11	STO SBC usage		None	NoUnit	0	2	0
200	12	STO SBC delay		0	ms	-1000	3600000	3600000
200	14	STO SBC speed		4.00	Hz	0.00	200.00	2.00
200	15	SSE/SS1 SBC speed	d/freq	0.00	Hz	0.00	20.00	0.00
200	16	SBC IO output		DO X113 & X114: 8	NoUnit	0	3	0

Figure 131. FSO-11: Safety settings tab

6. Click the **Download to FSO and validate** button. The password is required again.

The following Validate dialog box appears.

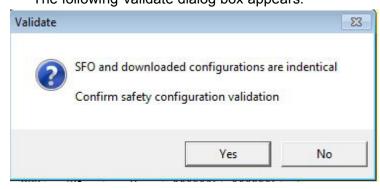


Figure 132. FSO-11 Validate dialog box

7. Click Yes.

The following dialog box appears.

	×
) Safety config	uration ok
	ОК

Figure 133. Safety configuration ok message

- 8. Click OK.
- 9. Test your safety configuration when the motor is running.

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10. Check the values of parameter group 200.

Note: If there are wrong values, right-click the parameter and select **Refresh the** parameter.

le Edit View Tools	Help!						
	REM Reset fault	Start Stop Coast stop Reference	0 Set				
All drives	Safety	settings {1}{1} × ACS880 {1}{1}	×				
USB- drives		Enter keyword 👻 🗌 Filter 🗌 No	ot at default Select co	olumns:	▼ E	nable upda	ting Download us
ACS880 {1}{1}	Index	Name	Value	Unit	Min	Max	Default
File drives	P	98. User motor parameters	**	2.5	10		10
	•	99. Motor data					
	-	200. Safety					
	1	FSO type	11	NoUnit	0	999	1
	6	Stop completed output	DO X113: 7	NoUnit			Non
	7	STO IO input A	None	NoUnit			DI X113 & X114:
	8	STO IO input B	None	NoUnit			Non
	9	STO time to zero speed	5000	ms	0	3600000	360000
	11	STO SBC usage	None	NoUnit			Non
	12	STO SBC delay	0	ms	-1000	3600000	360000
	14	STO SBC speed	4,00	Hz	0,00	200,00	2,0
	15	SSE/SS1 SBC speed/freq	0,00	Hz	0,00	20,00	0,0
	8 16	SBC IO output	DO X113 & X114: 8	NoUnit			Non
	17	SBC feedback from	Safety relay feedback	NoUnit			Safety relay feedb
	18	SBC feedback action	STO	NoUnit			STO
	19	STO ack	Automatic	NoUnit			Manua
	20	STO IO output	None	NoUnit			Non
	21	STO complete IO output	None	NoUnit			Non
	24	SSE time to zero speed w. S1	360	ms	0	3600000	360000
	25	SSE IO input A	DI X113: 1	Nol Init			Non

Figure 134. FSO-11: Parameter group 200

11. After testing save your safety settings by clicking Save safety file.

Open s	afety file	Save safety file Upload from	FSO Download to FSO a	nd validate	Chang	ge password	J
Safety	configura	tion created 28.8.2011					
Group	Index	Name	Value	Unit	Min	Max	Default
200	11	STO SBC usage	None	NoUnit	0	1	0
200	12	STO SBC delay	1500	ms	-5000	3600000	3600000
200	15	SSE/SS1 SBC speed	0	rpm	0.0	1000.0	0.0
200	16	SBC output	None	NoUnit	0	3	0
200	17	SBC feedback type	Safety relay feedback	NoUnit	0	1	0
200	18	SBC feedback action	STO	NoUnit	0	0	0
200	19	STO acknowledgement	Automatic	NoUnit	0	1	0
200	20	STO output	None	NoUnit	0	9	0
200	21	STO completed output	None	NoUnit	0	9	0
200	24	SSE time to zero speed with STO	3600000	ms	0	3600000	3600000
200	25	SSE input A	None	NoUnit	0	12	0
200	26	SSE input B	None	NoUnit	0	12	0
200	27	SSE function	Immediate STO	NoUnit	0	1	0
200	28	SSE monitoring method	Ramp	NoUnit	0	1	0

Figure 135. FSO-11: Save safety file button

If you want to change the password of the FSO safety functions module, click **Change password** button.

Note: Stop the motor when you initiate to change the password.

Setting the FSO-12 safety functions with Drive composer pro

- 1. Start the drive equipped with the FSO-12 option module using the drive control panel. See *Using the drive control panel for starting the drive* on page *61*.
- Right-click on drive and select Safety settings 2. The safety configuration that is already available in the drive is displayed. If there is no safety configuration, the view is empty.



Figure 136. FSO-12: Selecting Safety settings

3. Click **Upload from FSO**.

Note: The motor must be stopped.

When you upload the safety settings from FSO module to PC tool, the FSO goes into Configuration state and indicates a fault. You can exit the Configuration state by rebooting FSO module or by downloading the safety settings to the FSO. Step 7 below.

The Fault FSO general fault: 7A8B appears on the drive.

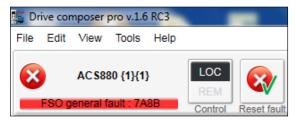


Figure 137. FSO-12: FSO general fault 7A8B

4. Type the password (8 numbers).

		×
Password:		•••••
	Ok	Cancel

Figure 138. Typing the password

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5. Double-click on the value filed and change all necessary configuration settings to match your safety configuration.

Safety set	tings 2 A	CS880 {1 }{1 } ×									
Open safe	ety file	Save safety file	Upload from FS	0	Download to FSO and	l validate	Change	password			Boot FSO
Version	2.50.14.0) Created 5/21/2014 1	10:34:59 AM by IN	IMAV	'EN1						
Group	Index	Name		Valu	e	Unit	Min	Max	Default		
Safety											
200	21	SLS1 activity and ver	rsion		Version 1		0	1	0		
200	22	SLS1 limit negative			-200.0		-35880.0	0.0	-200.0		
200	23	SLS1 limit positive			200.0		0.0	35880.0	200.0		
200	31	SLS2 activity and ver	rsion		Version 1		0	1	0	1	
200	32	SLS2 limit negative			-400.0		-35880.0	0.0	-400.0		

Figure 139. FSO-12 configuration in Safety group 200

Set the following safety function parameters:

- <u>General parameters</u>: Check that the motor parameters are correct.
- <u>I/O</u>: Check that I/O parameters are set according to the installation (wiring) plan. Remove diagnostic pulsing from any unused I/O. Check possible safety relays and cascade connections.
- <u>Safety functions</u>: Check all safety settings. You must at least check and set the STO and SSE related settings, regardless of whichever FSO safety functions you use. The FSO activates the STO and SSE functions in internal fault situations. The FSO uses the STO and SSE functions for making the system safe. All other functions are used only for monitoring the drive.

Note that only the group **Safety** is referred with group number and index numbers (see figure *FSO-12 configuration in Safety group 200*) and all other group names like **FSOGEN**, **STO** and so on have only index numbers (see figure *FSO-12 configuration with only group names*).

For examples of configuration settings and list of group names, see FSO-12 safety functions module User's manual (3AXD50000015612[English]).

Open sat	foty filo	Save safety file	Upload from FS	0	Download to ESO and	d validate	Change	password		
Jpen sa	lety life	Save salety life	Opidad Ironi PS	9	Download to FSO and	valiuate	Change	passworu		
Version	2.50.14.	0 Created 5/21/2014	10:34:59 AM by IN	NMAV	/EN1					
Group	Index	Name		Valu		Unit	Min	Мах	Default	
				valu	-	Unit				
200	223	Safety fieldbus adap	oter slot		FBAA		1	2	1	<u>^</u>
200	254	CRC of the configu	uration		36990	NoUnit	0	65535	0	
SOGE	N	1								
	1	FSO General setting	gs ver		v1	NoUnit	1	1	1	
	11	Stop completed output			None	NoUnit	0	9	0	Ξ
	21	Motor nominal speed		1500.0		rpm	1.0	35880.0	1500.0	
	22	Motor nominal frequ	iency		50.00	Hz	1.00	598.00	50.00	
	31	Trancient mute time	l.		0	ms	0	1000	0	
	41	Power-up acknowle	dgement		Automatic	NoUnit	0	3	1	
	42	Acknowledge buttor	n input		None	NoUnit	0	12	0	
	51	Zero speed without	encoder		90.0	rpm	0.0	600.0	90.0	
	61	STO indication ext r	equest		Event	NoUnit	0	3	3	
	62	STO indication safe	ty limit		Fault	NoUnit	0	3	1	
	254	CRC of the whole c	onfiguration		36990	NoUnit	0	65535	0	
STO										
	1	STO version			Version 1	NoUnit	1	1	1	
	2	STO acknowledgen	nent		Automatic	NoUnit	0	3	0	

Figure 140. FSO-12 configuration with only group names

- 6. Click **Save safety file** to save the FSO configuration to your PC.
- Click Download to FSO and validate. The password is required again. The following Validate dialog box appears.

Note: You can boot FSO without downloading to FSO using Boot FSO.

Validate		×
?	FSO and downloaded configurations a Confirm safety configuration validatio	
	Yes	No

Figure 141. Validate dialog box

8. Click Yes.

The following dialog box appears.

_					
i	Safe	ty cor	figura	tion ok	
				OK	

Figure 142. Safety configuration ok message

- 9. Click OK.
- 10. Test your safety configuration when the motor is running.
- 11. Right-click on drive and select **Parameters** to check the values in parameter group 200.

Note: If there are wrong values, right-click the parameter and select **Refresh the parameter**.

•							
Drive composer pro v.1.6 RC3				5.0		1	
File Edit View Tools Help							▲▼ <u>A</u> A
C AC 5880 {1}{1}	LOC REM Control Reset fault	Start Stop Coast sto	0.1 Active reference 0.1 Set	Step			
All drives 🔹 🗼	Safety settings 2	ACS880 {1}{1} ACS880 {	1}{1} ×				
Drives	Enter ke	yword - Filter No	at default Select co	olumns:	👻 🗌 En	able updat	ing 📮
C AC \$880 {1}{1}	Index	Name	Value	Unit	Min	Max	Default
P The drives	98 .	User motor parameters					
	▶	Motor data					
	— 200.	Safety					
	1	FSO speed ch1	0.00	rpm	-34028230 3	40282300	0.00
	2	FSO speed ch2	0.00	rpm	-34028230 3	40282300	0.00
	3	FSO DI status	0b0000	NoUnit	0b0000 0	b1111 11 [.]	060000
	4	FSO DO status	0b0000	NoUnit	0b0000 0	b1111 11 [.]	0b0000
	5	FSO control word 1	0b0001	NoUnit	0b0000 0	b1111 11 [.]	0b0000
	6	FSO control word 2	0b0000	NoUnit	0b0000 0	b1111 11 [.]	0b0000
	7	FSO status word 1	0b0010 1011	NoUnit	0b0000 0	b1111 11 [.]	0b0000
	8	FSO status word 2	0b0000	NoUnit	0b0000 0	b1111 11 [.]	0b0000
	9	Drive status word 1	0b0000	NoUnit	0b0000 0	b1111 11 [.]	0b0000
	10	Drive status word 2	0b0110 0000 0000	NoUnit	0b0000 0	b1111 11 [.]	0b0000
	254	CRC of the configuration	36990	NoUnit	0	65535	0

Figure 143. FSO-12: Parameter group 200

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12. After testing save your safety settings, click Save safety file.

Open saf	ety file	Save safety file	Upload from FSC	Download to FSO an	d validate	Change	password	
Version	2.50.12.	0 Created 5/14/2014 1	1:32:57 AM by IN	MAVEN1		_		
Group	Index	Name		Value	Unit	Min	Max	Default
Safety								
200	21	SLS1 activity and ver	sion	Version 1		0	1	0
200	22	SLS1 limit negative		-200		-35880.0	0.0	-200.0
200	23	SLS1 limit positive		200		0.0	35880.0	200.0
200	31	SLS2 activity and ver	sion	Version 1		0	1	0
200	32	SLS2 limit negative		-400		-35880.0	0.0	-400.0
200	33	SLS2 limit positive		400		0.0	35880.0	400.0
200	41	SLS3 activity and ver	sion	Version 1		0	1	0
200	42	SLS3 limit negative		-600		-35880.0	0.0	-600.0
200	43	SLS3 limit positive		600		0.0	35880.0	600.0

Figure 144. FSP-12: Save safety file button

If you want to change the password of the FSO safety functions module, click **Change password** button.

Note: Stop the motor when you initiate to change the password.



Other functions (pro)

Contents of this chapter

This chapter describes how to create a backup file of a drive and restore a drive. In addition, there are instructions on how to use the Drive parameter conversion tool.

Creating a backup of a drive (pro)

1. Right-click a drive and select **Backup/restore**.



Figure 145. Backup/restore command

2. Select a folder for the backup drive and give a name of your backup.

Drive composer pro v.1.5.0.4 RC4	
<u>F</u> ile <u>E</u> dit <u>V</u> iew <u>T</u> ools <u>H</u> elp	
C AC \$880 {2}{1}	Image: Control Reset fault Start Stop Image: Coast stop Ima
All drives 📢 🕨	ACS880 {2}{1} Backup/restore {2}{1} ×
Drives ACS880 {2}{1}	C:\Users\inmam2\Desktop\test.dcparamsbak Backup
File drives	Restore
File drives	Advanced restore

Figure 146. Selecting a folder for the backup drive

 Click **Backup** to start the backup process. The backup process takes a few minutes.

Restoring a drive (pro)

- 1. Right-click a drive and select **Backup/restore**. See figure *Backup/restore command*.
- 2. Click **Restore** to select the backup file to the drive with default settings.

All available components are restored from the backup file. All unavailable components are preserved in the drive.

Drive composer pro v.1.5.0.4 RC4	
<u>F</u> ile <u>E</u> dit <u>V</u> iew <u>T</u> ools <u>H</u> elp	
Resources	OC Image: Construction of the section of the sectio
All drives	ACS880 {2}{1} Backup/restore {2}{1} ×
Crives ACS880 {2\{1\} File drives	Image: C:\Users\inmam2\Desktop\test.dcparamsbak Backup Image: C:\Users\inmam2\Desktop\test.dcparamsbak Restore
8	Advanced restore

Figure 147. Selecting the restored backup file

3. To select a custom set of components to be restored to the drive, click **Advanced restore**.

The parameter values that are not written to the drive are listed in the restore report after the restore process. If there are grey items in the advanced list, the drive does not allow the item to restore.

Using the Drive parameter conversion tool

The parameter files of some ACS800/ACS600 ABB drive types commissioned and maintained with DriveWindow can be accessed with Drive composer via the Drive parameter conversion tool.

Note: Not all ACS800/ACS600 drives and software are supported.

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1. Go to Tools -> Drive parameter conversion tool.

Drive Parameter Conve	rter	
 Introduction Choose File Configuration Confirmation Progress Results 	 Drive Parameter Conversion Tool to convert parameters Automatic Wizard 	
	Back	t Cancel

Figure 148. Drive parameter conversion – Introduction

2. Click Next and select the appropriate ACS800/ACS600 parameter file.

Drive Parameter Converter			
 Introduction Choose File Configuration Confirmation 	Browse File Please browse file to Convert		
Progress Results	ACS800/600 Parameter File ACSX80 Parameter File Save Target	C:\Users\FIJORAK\Desktop\ACS800 Str	Browse Browse Browse
		Back Next	Cancel

Figure 149. Drive parameter conversion – Browsing the ACS800/600 file

3. Select an empty ACx80 parameter file with default values.

Drive Parameter Converter			
 Introduction Choose File Configuration Confirmation 	Browse File Please browse file to Convert		
Progress Results	ACS800/600 Parameter File ACSX80 Parameter File Save Target	C:\Users\FIJORAK\Desktop\ACS800 Str \ACS880 {1}{1}_DEFAULT.dcparamsbak	Browse
		Back Next	Cancel

Figure 150. Drive parameter conversion – Browsing the ACSX80 parameter file

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4. Select name for the drive.

Drive Parameter Converter			
 Introduction Choose File Configuration Confirmation 	Browse File Please browse file to Convert		
Progress Results	ACS800/600 Parameter File ACSX80 Parameter File Save Target	C:\Users\FIJORAK\Desktop\ACS800 Str \ACS880 {1}{1}_DEFAULT.dcparamsbak esktop\ACS880 {1}{1}_Converted.dcpara	Browse < Browse
		Back Next	Cancel

Figure 151. Drive parameter conversion – Save target **Note**: Do not overwrite the empty file.

- 5. Click Next.
- 6. Answer Yes.

The Conversion report shows the parameters which are converted successfully and failed. Read the report carefully and fix the parameter values manually for which the conversion was not successful.

Introduction	C	onvers	ion Repo	ort		Export CSV	
miroduction	Co	nversion	has been Cor	mpleted.			
Choose File	Status	800/600	Value	880	Updated Value	Message	*
Configuration	Succe	27.01	AUS	43.06	Disabled	Succesful Conversion	
	Succe	27.04	0	43.08	0	Succesful Conversion	
Confirmation	Succe	27.05	0	43.09	0	Succesful Conversion	
	Succe	30.02	FEHLER	49.05	Fault	Succesful Conversion	
Progress	Succe	30.03	NEIN	31.01	Inactive (true)	Succesful Conversion	
Results	Succe	30.04	NEIN	35.10	No action	Succesful Conversion	
Results	Succe	30.05	DTC	35.11	Estimated ter	Succesful Conversion	
	Succe	30.07	100	35.51	100	Succesful Conversion	
	Succe	30.08	74	35.52	74	Succesful Conversion	
	Succe	30.10	FEHLER	31.24	Fault	Succesful Conversion	
	Succe	30.16	NEIN	31.19	No action	Succesful Conversion	
	Succe	30.17	FEHLER	31.20	Fault	Succesful Conversion	
	Succe	31.01	0	31.14	0	Succesful Conversion	
	Succe	31.02	30	31.15	30	Succesful Conversion	
	Succe	31.03	0	31.16		Succesful Conversion	*
	4				1		

Figure 152. Drive parameter conversion – Results

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Further information

Product and service inquiries

Address any inquiries about the product to your local ABB representative, quoting the type designation and serial number of the unit in question. A listing of ABB sales, support and service contacts can be found by navigating to <u>www.abb.com/searchchannels</u>.

Product training

For information on ABB product training, navigate to <u>www.abb.com/drives</u> and select *Training courses*.

Providing feedback on ABB Drives manuals

Your comments on our manuals are welcome. Go to <u>www.abb.com/drives</u> and select *Document Library – Manuals feedback form (LV AC drives)*.

Document library on the Internet

You can find manuals and other product documents in PDF format on the Internet. Go to <u>www.abb.com/drives</u> and select *Document Library.* You can browse the library or enter selection criteria, for example a document code, in the search field.

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