## PWL400-15

# 1Q PWM Chassis Adjustable Speed Drive for PMDC or Field Wound Brushed Motors

The PWL Series adds to the versatility of our PWM offering by adding field voltage outputs for shunt-wound motors. With on-board selector switches, this series can easily be setup to accept 115 VAC or 230 VAC power. This full featured series comes with on-board fusing and cage clamp terminals to make installation simple and quick. The almost pure DC output of the PWL Series allows motors to run more efficiently and at lower speeds while achieving full torque than with the use of SCR type drives. With a wide selection of models that can run motors from 1/20 HP all the way up to 3 HP, you're sure to find a drive that will satisfy your needs.



ROHS COMPLIANT

Model Number	Enclosure	Maximum Current (ADC)	Input Voltage (VAC)	Output Voltage (VDC)	Power Range		Field/Shunt	Reversing	Isolation
					HP	kW	Supply		
PWL400-15	Chassis	15	115	0 - 90 /130	1/4 - 1 1/2	.20 - 1.1	50/100	No	No
			230	0 - 90 /130	1/4 - 1 1/2	20 - 1.1	100/200		
				0 - 180 /240	1/2 - 3	.40 - 2.3			

### **SPECIFICATIONS**

AC Line Voltage115 / 230 VAC, ± 10%, 50/60 Hz, 1Ø
Maximum Field Current1 amp
Acceleration Time Range
with 90/130 VDC motor1 - 9 seconds
with 180/240 VDC motor1 - 15 seconds
Deceleration Time Range
with 90/130 VDC motorcoast to stop - 10 seconds
with 180/240 VDC motorcoast to stop - 18 seconds
Form Factor1.05
Speed Range
Load Regulation0.5% of base speed or better
Input Impedance50K $\Omega$
Isolated Analog Signal Range @ 115 VAC input0 - 2.5 VDC
@ 230 VAC Input0 - 5 VDC
Ambient Temperature Range10°C - 40°C

**FEATURES** 

used for rapid starting and stopping

On-board Fusing: Drives include on-board fusing Jog Mode: Dedicated circuitry for a jog setup Diagnostic LEDs: Power, Current Limit

KTP-0001: Potentiometer kit

**ACCESSORIES** 

**KTW-0001:** 2-pin plug for Inhibit, Power, +15, or Curr headers with 18" leads

Stopping Modes: Inhibit (N.O.) for coasting to a stop. Can be

### TRIM POTS

Acceleration
Current Limit
Deceleration
IR Compensation
Jog
Maximum Speed
Minimum Speed