# Modbus Sensor Connector Type Digital Remote I/O

# Features

- Modbus RTU standard protocol
- Saving work time for wiring with sensor connector (CNE series, sold separately)
- Compact size
- : Small size with W26×L76×H54mm to install at narrow space
- : Available DIN Rail mounting and bolt mounting method
- Low-speed (16-bit/30CPS) counter function
- Real-time monitoring by various functions
- : Communication speed auto-recognition
- : Reading number of expansion units and specifications,
- Reading model name of basic and expansion units
- : Monitoring Single byte input/output, Multi byte input/output and status Flag
- Easy expansion
- : Available to connect up to 63 basic units per 1 master unit
- : Available to connect up to 7 expansion units per 1 basic units (controllable input/output for max. 64 points)
- : Combines the desired specifications of input/output by various input/output units
- : Organizes power and communication system by only communication cable lines
- High reliability
- : Built-in surge, short, overheat, reverse power polarity and static prevention circuits
- Please read "Safety Considerations" in the instruction manual before using.

#### Ordering Information AR Μ D 80 Ν **4S** I Terminal block 4S Sensor connector type (4-pin socket) Ν NPN open collector I/O specifications Ρ PNP open collector I/O points 08 8 points type I/O type Input type 0 Output type Digital/Analog D Digital type M Basic unit (Modbus RTU) Network Х Expansion unit (DeviceNet/Modbus) Item AR Autonics Remote I/O

# Models

Models		Creation	
Basic unit	Expansion unit	specification	
ARM-DI08N-4S	ARX-DI08N-4S	10-28VDC NPN input 8-point, low-speed counter (10mA/point)	
ARM-DI08P-4S	ARX-DI08P-4S	10-28VDC PNP input 8-point, low-speed counter (10mA/point)	
ARM-DO08N-4S*	ARX-DO08N-4S*	10-28VDC NPN output 8-point, low-speed counter (0.3mA/point)	
ARM-DO08P-4S*	ARX-DO08P-4S*	10-28VDC PNP output 8-point, low-speed counter (0.3mA/point)	

%Low speed counter of digital output type is available only when using with digital input type.

# Manual

For the detail information and instructions of communication setting and Modbus mapping table, please refer to user manual for communication, and be sure to follow cautions written in the technical descriptions (catalog, website). Visit our website (www.autonics.com) to download manuals.



# Specifications

Model	Basic unit	ARM-DI08N-4S	ARM-DI08P-4S	ARM-DO08N-4S	ARM-DO08P-4S	0510000	
	Expansion unit	ARX-DI08N-4S	ARX-DI08P-4S	ARX-DO08N-4S	ARX-DO08P-4S	SENSORS	
Power sup	oply	Rated voltage: 24VDC=	, Voltage range: 12-28VD	)C==			
Power cor	nsumption	Max. 3W				CONTROLLE	
I/O points		NPN input 8-point	PNP input 8-point	NPN output 8-point	PNP output 8-point		
	Voltage	10-28VDC== input		10-28VDC output (v	oltage drop: max. 0.5VDC==)		
Control	Current	10mA/point (sensor current: 150mA/points)		0.3A/point (leakage cu	urrent: max. 0.5mA )	MOTION DEVIC	
1/0	Common	8 points, Common	. ,				
Special fu	nction (input)	Counter for 16-bit (30Cl	PS <sup>**1</sup> ) (only when using dig	ital input unit of ARM, ARX)			
Communi	cation speed **2	2400, 4800, 9600, 1920	0, 38400, 57600, 115200	ops (default: 9600bps)		SOFTWARE	
Communi	cation method	2-wire half duplex					
Communi	cation distance	Max. 800m					
Multi-drop		Max. 32 multi-drop				_	
Medium a	ccess	POLL					
Applicatio	n standard	Compliance with EIA R	S485			_	
Protocol		Modbus RTU					
Data bit		8-bit					
Stop bit		1-bit or 2-bit (default: 2-	bit)			(J) Temperature	
Parity bit None/Odd/Eve		None/Odd/Even (defaul	It: none)			Controllers	
,		I/O and inner circuit: photocoupler insulation					
Isolation n	nethod	Modbus to internal bus and inner circuit: insulation					
		Unit power: non-insulation					
Insulation resistance Over 200MΩ (at 500VDC megger)			(L)				
Noise immunity		±240V the square wave noise (pulse width: 1µs) by the noise simulator					
Dielectric	strength	1,000VAC 50/60Hz for	1 min				
Vibration		1.5mm amplitude at free	quency of 10 to 55Hz (for	1 min) in each X, Y, Z direction	on for 2 hours	(M)	
Shock		500m/s <sup>2</sup> (approx. 50G) in each X, Y, Z direction for 3 times					
Environ-	Ambient temp.	-10 to 55°C, storage: -2	5 to 75°C				
ment	Ambient humi.	35 to 85%RH, storage:	35 to 85%RH			(N)	
Protection	structure	IP20 (IEC standards)				Timers	
Protection circuit		Surge, short-circuit, overheat (over 165°C) and ESD protection, reversed polarity protection circuit					
		Overcurrent protection	circuit	Overcurrent protection	n circuit	(O) Digital	
		(operated at min. 0.17A	.)	(operated at min. 0.7A	(operated at min. 0.7A)		
Indicator		Network status (NS) LED (green, red), unit status (MS) LED (green, red)					
		I/O status LED (input: green, output: red)					
Material	-	Front case, body case:	Polycarbonate				
Mounting		DIN rail or bolt mounting type					
Approval		CE				Converters	
Weight <sup>**3</sup>	Basic	Approx. 123.3g	Approx. 123.3g	Approx. 123.3g	Approx. 123.3g	(R) Digital Display Units	
		(approx. 61.8g)	(approx. 61.8g)	(approx. 61.8g)	(approx. 61.8g)		
	Expansion	Approx. 117.5g	Approx. 118.5g	Approx. 119.5g	Approx. 120.5g		
		(approx. 56g)	(approx. 57g)	(approx. 58g)	(approx. 59g)		

%2: The communication speed is automatically set to the communication speed of the Master (PC, PLC, etc.).

When changing the communication speed during operation, the network status (NS) LED flashes in red and communication is not possible.

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X3: The weight includes packaging. The weight in parenthesis is for unit only.

※Environment resistance is rated at no freezing or condensation.

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(V) HMIs

(T) Switching Mode Power Supplies

(U) Recorders

(W) Panel PC

## Unit Descriptions

◎ Basic unit



#### 1. Network connector

No.	For	Organization
5	24VDC (+)	5: 24VDC
4	GND	4: GND
3	N·C	• ) 3: N·C
2	В	● ) 2: B
1	A	

- 2. Rotary switch for address: Rotary switch for setting the address ×10 represents tens digit and ×1 represents ones digit.
- 3. Status LED: It displays the status of unit (MS) and network (NS).
- 4. I/O status LED: It displays each I/O status.
- 5. Rail lock: It is used for mounting DIN rail or with bolts.
- 6. Connector output part: It connects an expansion unit.
- 7. Sensor connector: It is used for connecting external device I/O.
- 8. External power connector: It is used for supplying external power.

## **◎** Expansion unit



- 1. Connector input part: It connects expansion unit and is joined into the expansion connector output.
- 2. I/O status LED: It displays each I/O status.
- 3. Rail lock: It is used for mounting DIN rail or with bolts.
- 4. Connector output part: It connects an expansion unit.
- 5. Sensor connector: It is used for connecting external device I/O.
- 6. External power connector: It is used for supplying external power.

# Status LED

			( ☆: ON, -♥: Flash, ●: OFF
Itom	LED status		Description
litem	Red	Green	Description
	ų.	•	Error of expansion units
Linit status (MC) LED	×.	•	Error of MAC ID
Unit status (MS) LED		ų.	Normal operation
		•	Power is not supplied
Network status (NS) LED	Ϋ́ς-	•	Not supported communication speed (at auto baud rate)
	Э.	•	Error of packet
	•	Ϋ́ς.	Normal communication
		ù.	Communication standby

# I/O Circuit Diagram



(W) Panel PC

(X) Field Network Devices

# Connections

%When wiring the communication connector, use AWG20 cable and tighten the connector screw with a tightening torque of 0.5N·m.



# Terminating Resistance

120Ω
1% of metallic film
1/4W

\*Connect terminating resistances on the both ends of the network cables. If not connecting terminating resistances, impedance can be too high or low. It may cause network problems.

## Dimensions

XSame dimensions are applied to both basic and expansion unit.

%Tightening torque for mounting bolts: 1.8 to 2.5N m



• Rail lock position: mounting with bolt



• Rail lock position: mounting on DIN rail

a

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85.





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(unit: mm)

## Expansion connector



# Setup and Installation

## Setting node address

-Setting address is able to be done by rotary switch for address, or by in the EEPROM.

- -If the rotary switch for address' number is "00", the address is available to set by in the EEPROM.
- The others, the desired number of rotary switch is that address.
- The address of the connected unit must not be duplicated. When changing the address during operation, the unit status (MS) LED flashes in red and the unit communicates to MOTION DEVICES the address before the change.

## • By rotary switch for address

- ① Two rotary switches are used for setting address. The X10 switch represents tens digit and the X1 switch represents ones digit. The address can be set 01 to 99.
- 2 After setting the desired address, re-supply the unit power for applying the changed address.

## By in the EEPROM for address

- (During communicate status with master system (PLC or PL), set the desired address on the 41029 EEPROM MAC ID parameter.
- (2) The set address is changed after unit power is supplied. Re-supply the unit power for applying the changed address.

## O Unit Installation

### Mounting on panel

- ① Pull two Rail locks on the rear part of a unit, there is a fixing bolt hole.
- ② Place unit on a panel to be mounted.
- ③ Make a hole on a fixing bolt hole position.
- ④ Fasten the bolt to fix the unit tightly. Please set the tightening torque under 0.5N·m.

#### Mounting on DIN rail

- ①Pull two Rail locks on the rear part of a unit.
- 2 Place the unit on DIN rail to be mounted.
- ③Press Rail locks to fix the unit tightly.

### Connection of basic and expansion units

- ① Turn OFF the power of a basic unit.
- (2) Remove the cover of connector for extension with nippers.
- ③ Connect connector input part of an expansion unit and connector output part of a basic unit with the connector which is enclosed with an expansion unit box.
- ④ Connected expansion units are installed as the right figure.
- (5) Supply power to the basic unit.
- \*Re-supply power to the basic unit, and it recognizes expansion units.

## Cautions during Use

- 1. Follow instructions in 'Cautions during Use'. Otherwise, it may cause unexpected accidents.
- 2. 24VDC power supply should be insulated and limited voltage/current or Class 2, SELV power supply device.
- 3. Use only designated connector and do not apply excessive power when connecting or disconnecting the connectors.
- Mode Powe 4. Keep away from high voltage lines or power lines to prevent inductive noise. In case installing power line and input signal Supplies line closely, use line filter or varistor at power line and shielded wire at input signal line. Do not use near the equipment which generates strong magnetic force or high frequency noise. (U) Recorders
- 5. Do not connect or disconnect the expansion unit when power is being supplied.
- 6. This unit may be used in the following environments.
- ()Indoors (in the environment condition rated in 'Specifications') ②Altitude max. 2.000m ③Pollution degree 2
- ④Installation category II

(E.g.)

The X10 and X1 switches point both at "3", the address is "33"



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CONTROLLERS

SENSORS

SOFTWARE

(J) Temperature

Controllers

(K) SSRs

(L) Power Controllers

(M) Counters

(N) Timers

(0)

Digital Panel Meters

(P) Indicators

(Q) Converters

(R) Digital Display Units

(S) Sensor Controllers

(T) Switching

(V) HMIs

(W) Panel PC