Shaded parts (m) are changed and

added functions from previous BWC Series.

## **Cross-Beam Area Sensor**

### Features

• Minimized blind zone with 3-point cross-beam netting method

Long sensing distance: 1 to 7m

- 14 types of model
  - : wide range of choice in the number of optical axis (4 to 20), pitch of optical axis (40, 80mm), and sensing width (120 to 1,040mm)
- Easy installation with installation mode
- Built-in interference protection, self-diagnosis function
- Self-diagnosis output
  - : sensing front screen contamination and covering optical axis by itself, making easy to see the status from external equipment (patent)
- Conspicuous high luminance indicators at emitter/receiver for easy check of the status from side, front even long distance
- Suitable for KRS Korean Railway Srandard (BWC80-14HD meets KRS conditions.)
- Protection structure IP67 (IEC structure)





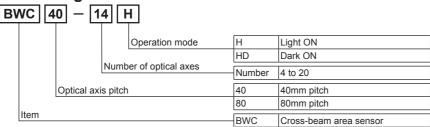
## Applications

(only for BWC80-14HD model)

Various environment:

Utilized in various environment: obstacle detecting sensor for subway platform screen door (PSD), and etc.

## Ordering Information



## Specifications

Model	BWC40-□□H	BWC40-□□HD	BWC80-14H	BWC80-14HD		
Sensing type	Through-beam type					
Sensing distance	1.0 to 7.0m					
Sensing target	Opaque material of min. Ø50mm	1	Opaque material of min. @	Opaque material of min. Ø90mm		
Optical axis pitch	40mm		80mm			
Number of optical axes	4/10/12/16/18/20		14			
Sensing height	120 to 760mm		1,040mm			
Beam pattern	3-point cross-beam netting type					
Response time	Max. 50ms					
Power supply	12-24VDC== ±10% (ripple P-P: max. 10%)					
Current consumption	Max. 100mA					
Light source	Infrared LED (850nm modulated)					
Operation mode	Light ON	Dark ON	Light ON	Dark ON		
Control output	NPN open collector output • Load voltage: max. 30VDC • Load current: max. 100mA (self-diagnosis output: max 50mA) • Residual voltage: max. 1VDC					
Protection circuit	Reverse power polarity, output short over current protection circuit					
Insulation resistance	Over 20MΩ (at 500VDC megger)					
Synchronization type	Timing method by synchronous	Timing method by synchronous cable				
Self-diagnosis	Transmitted-received light monitoring, direct light monitoring, output circuit monitoring, self-diagnosis output (checking whether there is contamination on the front screen, or any obstacle on optical axis)					
Interference protection	Interference protection by frequency changing setting					
Noise immunity	±240V the square wave noise (pulse width: 1μs) by the noise simulation					
Dielectric strength	1,000VAC 50/60Hz for 1 min					
Vibration	1.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 2 hours					

(A) Photoelectric Sensors

SENSORS

CONTROLLERS

MOTION DEVICES

SOFTWARE

(B) Fiber Optic Sensors

(C) LiDAR

### (D) Door/Area Sensors

(E) Vision Sensors

(F) Proximity Sensors

(G) Pressure Sensors

(H) Rotary Encoders

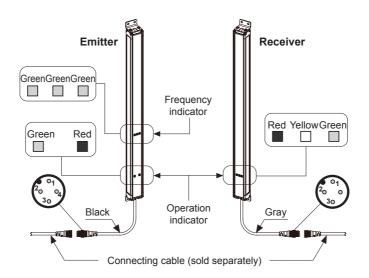
Connectors/ Connector Cables/ Sensor Distribution Boxes/ Sockets

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# **BWC Series**

Model		BWC40-□H BWC40-□HD BWC80-14HD BWC80-14HD				
Shock		500m/s² (approx. 50G) in each X, Y, Z direction for 3 times				
	Ambient illumination	Ambient light: max. 100,000lx (received light side illumination)				
Environ- ment	Ambient temperature	-10 to 55°C, storage: -20 to 60°C	10 to 55°C, storage: -20 to 60°C			
	Ambient humidity	35 to 85%RH, storage: 35 to 85%RH				
Protection	structure	IP65 (IEC standard)				
Material		Case: Aluminum, sensing part and indicator: Acrylic				
Cable		Ø5mm, 4-wire, 300mm, M12 con	Ø5mm, 4-wire, 300mm, M12 connector			
Accessory		Bracket A: 4, Bracket B: 4, Fixing bolt: 8				
Korean Rail	way Standards	— KRS SG 0068				
Approval		C€, ╚				
Weight**1		Approx. 2.1kg (approx. 1.7kg) (based on BWC80-14H)				

## Structure



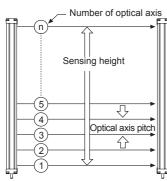
### < Operation indicator>

LED color	Emitter	Receiver
Green	Power	Stable light ON
Yellow	_	Unstable area
Red	Installation mode	Stable light OFF

<Wiring connection>

Pin No	Cable color	Emitter	Receiver
1	Brown	12-24VDC	12-24VDC
2	White	Sync	Sync
3	Blue	0V	0V
4	Black	Mode	OUT
	1	1 Brown 2 White 3 Blue	1 Brown 12-24VDC 2 White Sync 3 Blue 0V

## ■ Optical Axis Pitch/Number Of Optical Axis/Sensing Height

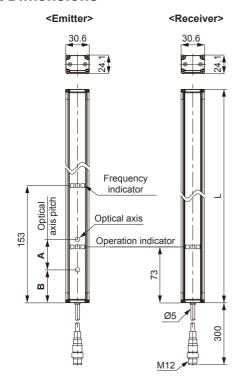


Model	Number of optical axis	Sensing height	Optical axis pitch
BWC40-04H/HD	4	120mm	
BWC40-10H/HD	10	360mm	
BWC40-12H/HD	12	440mm	40mm
BWC40-16H/HD	16	600mm	4011111
BWC40-18H/HD	18	680mm	
BWC40-20H/HD	20	760mm	
BWC80-14H/HD	14	1,040mm	80mm

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 $<sup>\</sup>times$ 1: The weight includes packaging. The weight in parenthesis is for unit only.  $\times$ The temperature or humidity mentioned in Environment indicates a non freezing or condensation environment.

## Dimensions



Model	L	A, B
BWC40-04H/HD	160	
BWC40-10H/HD	400	
BWC40-12H/HD	480	40
BWC40-16H/HD	640	40
BWC40-18H/HD	720	
BWC40-20H/HD	800	
BWC80-14H/HD	1120	80

# SENSORS

CONTROLLERS

MOTION DEVICES

SOFTWARE

(A) Photoelectric Sensors

(B) Fiber Optic Sensors

(C) LiDAR

### (D) Door/Area Sensors

(E) Vision Sensors

(F) Proximity Sensors

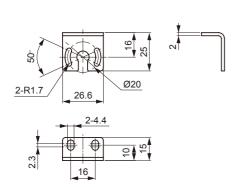
(G) Pressure Sensors

Sensors

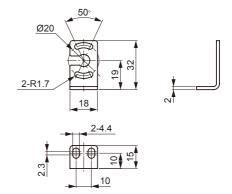
(H) Rotary Encoders

(I) Connectors/ Connector Cables/ Sensor Distribution Boxes/ Sockets

### Bracket A



### Bracket B



## ■ Bracket Mounting

• Mounting the bracket A

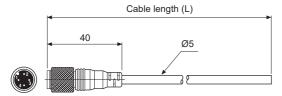


## • Mounting the bracket B



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## **■** Connection Cable (sold separately)



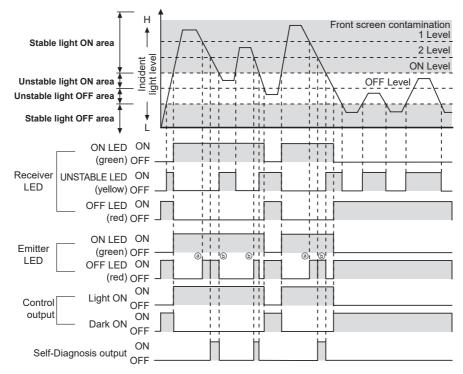
XConnection cable is sold separately as one set; each of emitter's and receiver's

Туре	Model	L	Cable color
	CID4-3T	3m	
	CID4-5T	5m	
Emitter	CID4-7T	7m	Black
	CID4-10T	10m	
	CID4-15T	15m	
	CID4-3R	3m	
	CID4-5R	5m	
Receiver	CID4-7R	7m	Gray
	CID4-10R	10m	
	CID4-15R	15m	

## Operation Mode

Operation mode	Light ON	Dark ON	
Receiver	Received light Interrupted light	Received light Interrupted light	
Operation indicator (green LED)	ON OFF	ON OFF	
Transistor output	ON OFF	ON OFF	

## Operation Timing Diagram

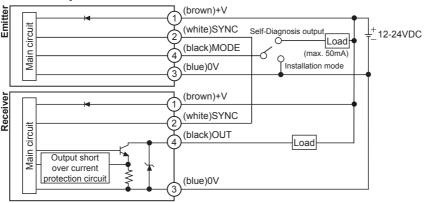


 $\fint \fi \fi$  @: [Self-diagnosis output] Front screen contamination level 1 / flashing at 1 sec interval

(b): [Self-diagnosis output] Front screen contamination level 2, covering optical axis / flashing at 0.25 sec interval

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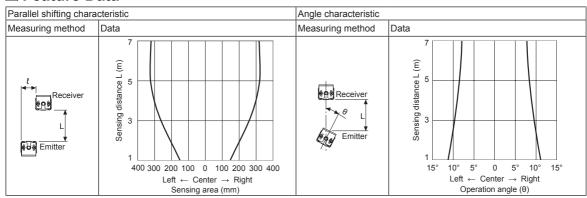
## **■** Control Output Circuit



# CONTROLLERS MOTION DEVICES

SOFTWARE

### ■ Feature Data



### (A) Photoelectric Sensors

(B) Fiber Optic Sensors

(C) LiDAR

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(I) Connectors/ Connector Cables/ Sensor Distributior Boxes/ Sockets

## Functions

### Interference protection

You can change transmitted light frequency to prevent interference from several units.

To change transmitted light frequency, input 0V for over 1 second to 4th terminal, (black) MODE, in installation mode.

Frequency type is displayed by frequency indicator.

### Installation mode

This function is for stable installation.

Inputting 0V to 4th terminal of emitter which is (black) MODE, supply power to the product to enter to the installation mode.

## Self-Diagnosis Output

This function outputs self-diagnosis signal, when front screen is contaminated with dust, optical axis is misaligned due to vibration, emitter is damaged due to the long-term usage, or light t is not received due to obstacle such as leaves and trash on the product. It operates in the operation mode, and you can check the status through an external device which is connected to 4th terminal of emitter, (black) MODE.

Item	Emitter operation indicator	Control output		Self-diagnosis
litem	Emilier operation indicator	Light ON	Dark ON	output
Front screen contamination level 1	Red, flashing at 1 sec interval	ON	OFF	OFF
Front screen contamination level 2, covering optical axis	Red, flashing at 0.25 sec interval	ON	OFF	ON

## Self-diagnosis

If there is checked malfunction during normal operation by regular self-diagnosis, control output turns OFF and operation indicator displays the state.

### Diagnosis item

Break of light emitting element

- ② Break of emitter
- 3 Break of adjacent emitting element more than 2.
- ④ Break of receiver⑥ Receiver failure

- ⑤ Emitter failure
- Malfunction of synchronous cable
- ※For more information about operation indication display, refer to "■ Operation Indicator"

Autonics D-41

☼: ON, ●: OFF

light frequency

Transmitted

Frequency A

Frequency B

Frequency C

Frequency D

Frequency E

Frequency indicator

Φ

•

•

Φ

✡

Green 1 Green 2 Green 3

Ф

•

•

✡

Ø

 $\Diamond$ 

Ф

# Operation Indicator

		Emitter		Receive	er			
Item		Indicator		Indicato	Indicator		Control output	
		Green	Red	Green	Yellow	Red	Light ON	Dark ON
Power supp	ply	≎	•	<u> </u>	<u> </u>	<u> </u>	T—	_
Break of er	nitter	<b>D</b>	<b>(4)</b>	<b> </b>			<b>—</b>	_
Break of lig	ht emitting element	<b>•</b>	•	<b>•</b>	<b>(</b>	<b>•</b>	OFF	OFF
Break of adjacent emitting element more than 2.		•	•	<b>▶</b>	•	<b>(b)</b>	OFF	OFF
Installation mode	Normal installation	≎	•	≎	•	•	OFF	OFF
	Hysterisis section	•	0	•	≎	•		
	Abnormal installation	•	•	•	•	•		
Stable light	ON	≎	•	≎	•	•	ON	OFF
Unstable lig	ght ON	≎	•	≎	≎	•	ON	OFF
Unstable lig	ght OFF	•	≎	•	≎	≎	OFF	ON
Stable light	OFF	•	≎	•	•	≎	OFF	ON
Break of receiver		_		<b>P</b>		<b>(1)</b>	OFF	OFF
Control output over current		_		<b>•</b>	•	≎	OFF	OFF
Synchronous line malfunction		_	<u> </u>	•	•	•	OFF	OFF
Emitter fail	ure (time out)	<u> </u>	1—	•	•	•	OFF	OFF
Receiver failure (time out)		•	•	1—		<u>                                     </u>	OFF	OFF

Indicator	Indicators				
¢	Lighting				
•	Light out				
	Flashing				
0	at 0.5 sec interval				
or	Flashing simultaneously				
	at 0.5 sec interval				
00	Cross-flashing				
⋑●	at 0.5 sec interval				
000	Sequence-flashing				
	at 0.5 sec interval				

# **■** Troubleshooting

Malfunction	Cause	Troubleshooting
	Power supply	Supply the rated power.
Non-operation	Cable incorrect connection, or isconnection	Check the wiring connection
	Out of rated sensing distance	Use it within rated sensing distance.
Non-operation in sometimes	Pollution by dirt of sensor cover	Remove dirt by soft brush or cloth.
TVOIT-OPERATION IN SOMETIMES	Connector connection failure	Check the assembled part of the connector
	Out of the rated sensing distance	Use it within the rated sensing distance.
Control output is OFF even though there is not a target	There is an obstacle to cut off the emitted light between emitter and receiver.	Remove the obstacle.
object.	There is strong electric wave or noise generator such as motor, electric generator, or high voltage line, etc.	Put away the strong electric wave or noise generator.
Operation indicator displays break of emitter	Break of emitter	
Operation indicator displays break of receiver	Break of receiver	Contact our company.
Operation indicator displays break of light emitting element	Break of light emitting element	
Operation indicator displays	Emitter or Receiver failure	
emitter/receiver failure	Bad wiring connection of synchronous cable in emitter and receiver	Check the wiring connection in emitter and receiver.
Check the wiring connection in	Control output line is shorted out.	Check the wiring connection.
emitter and receiver.	Over load	Check the rated load capacity.

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## **Cross-Beam Area Sensor**

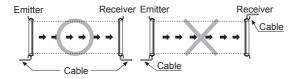
## Installation

For the first installation, enter installation mode.

- ① Entry method for installation mode: Supply the power with inputting 0V to terminal 4 (black) MODE of Emitter.
- ② After entering installation mode, install the unit at the position where green LED of receiver operation indicator turns ON.
- 3 After installation, re-supply the power to the unit.

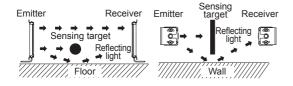
### For direction of installation

Emitter Receiver should be installed in same up/down direction.



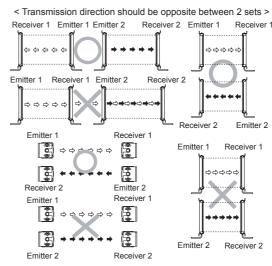
### For reflection from the surface of wall/flat

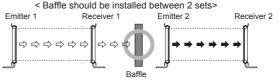
When installing it as below, the light reflected from the surface of wall and flat is not shaded. Please check whether it operates normally or not with a sensing target before using. (interval distance: min. 0.5m)



### For protection of interference

It may cause interference when installing more than 2 sets of the sensor. In order to avoid the interference of the sensor, please install as following figures and use interference protection function





<It should be installed out of the interference distance>



XIt may be different by installation environment.

«Avoid using the unit in the place where the sensor is exposed directly to the fluorescent light with high speed start or high frequency. CONTROLLERS

SENSORS

MOTION DEVICES

SOFTWARE

(A) Photoelectric Sensors

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(I) Connectors/ Connector Cables/ Sensor Distributior Boxes/ Sockets

## ■ Proper Usage

- 1. Follow instructions in 'Proper Usage'.
  - Otherwise, It may cause unexpected accidents.
- 2. 12-24VDC power supply should be insulated and limited voltage/current or Class 2, SELV power supply device.
- 3. Use the product, 1 sec after supplying power.
  - When using separate power supply for the sensor and load, supply power to sensor first.
- 4. When using switching mode power supply to supply the power, ground F.G. terminal and connect a condenser between 0V and F.G. terminal to remove noise.
- 5. When connecting a DC relay or other inductive load, remove surge by using diodes or varistors.
- 6. Wire as short as possible and keep away from high voltage lines or power lines, to prevent surge and inductive noise.
- 7. This unit may be used in the following environments.
  - ①Indoors (in the environment condition rated in 'Specifications')
  - ②Altitude max. 2,000m
  - ③Pollution degree 2
  - 4 Installation category II

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