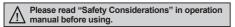
Features

- 13 kinds of various operation modes selected by DIP switches
- High speed input response
- Flip-flop mode for level control
- Multifunctional unit with timer mode
- DIN rail, Mounting to panel
- Wide range of power supply (100-240VAC 50/60Hz)







Ordering Information

PA10 — U			
Input	No mark	NPN input	
	Р	PNP input	
Function	U	High function controller	
Function	V	General purpose controller	
	W	2-channel controller	
Item	PA10	Power amplifier	

Specifications

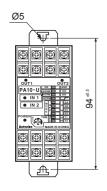
Model		PA10-U	PA10-V	PA10-VP	PA10-W	PA10-WP
Power su	ıpply	100-240VAC∼ 50/60Hz				
Allowable	operation voltage	voltage 90 to 110% of rated voltage				
Power co	onsumption	Max. 10VA (condo ion:12VDC:/200mA resistive load)				
Power fo	r external senso	12VDC== ±10% Approx. 200mA				
Input (IN1) (IN2)		Selectable NORM/INV. Selectable OR/AND operation for IN1, IN2 input. Selection function for IN2 derivative action.		1, IN2 AND.	Selectable NORN Operation for IN1	, IN2 AND.
		NPN input type		PNP input type	NPN input type	PNP input type
Input typ	 PA10-U (no-voltage input) Impedance at short-circuit: Max. 680Ω,			at open: Min. 100kΩ		
	Contact output	OUT: 250VAC \sim 3A, 30VDC	== 3A (resistive lo	ad)	OUT1, OUT2 : 250VAC~ 3A, 3	0VDC== 3A (resis ive load)
Output	Solid-state output	O.C. OUT1/O.C. OUT2 : NPN open collector output Max. 30VDC== 100mA		open collector output 30VDC== 100mA	_	
Respons	e time	Relay output: Max. 10ms, Tr	ansistor output: N	lax. 0.05ms		
Time setting function by each mode % Only for		ON Delay Mode One-Shot Delay Mode Flicker One-Shot Mode High-Speed Detection Mode	de	Flicker ILow-Sp	elay Mode Mode eed Detection Mod Delay Mode	le
PA10-I	J None	Normal Mode Flip-Flop Mode Encoder (mode 9 to 11)				
Relay	Relay Mechanical Min. 10,000,000 operations					
life cycle Electrical Min. 100,000 operations (250VAC 3A resistive load)						
Dielectric	Dielectric strength 2000VAC 50/60Hz for 1 minute					
Insulation resistance Over 100MΩ (at 500VDC megger)						
Environ-ment temperature temperature -10 to 55°C, storage: -25 to 60°C						
	Ambient humidit	,	85%RH			
Unit weig	Unit weight Approx. 150g Approx. 160g					

XIf the load is connected over 200mA at the sensor output, it may cause mechanical trouble.

X Environment resistance is rated at no freezing or condensation.

O-2 Autonics

Dimensions



+12

OUT1

PA10-U

• IN 1

● IN 2

NC СОМ NO

CONTACT OUT:

RESISTIVE LOAD

250VAC 3A, 30VDC 3A

Black

Δ

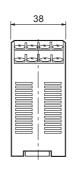
SOURCE

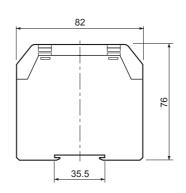
50/60Hz

100-240VAC 🤤

IN1

IN2





PA10-W/PA10-WP

+12 GND IN1

+12 GND IN2

oUT1

PA10-W

IN 1 NORM INV • IN 1

NC2

NC1

OUT2

NO2

NO1

OUT1

OM²

CONTACT OUT1, OUT2:

250VAC 3A, 30VDC 3A

RESISTIVE LOAD

(unit: mm)

(A) Photoelectric Sensors

(C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure Sensors

(F) Rotary Encoders

(G) Connectors/ Connector Cables/ Sensor Distribution Boxes/Sockets

(I) SSRs / Power Controllers

(J) Counters

(M) Tacho / Speed / Pulse Meters

(P) Switching Mode Power Supplies

(Q) Stepper Motors

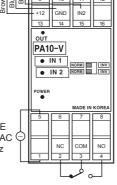
(R) Graphic/ Logic Panels

Connections



PA10-V/PA10-VP

+12 IN1 GND OUT PA10-V • IN 1 • IN 2



CONTACT OUT: 250VAC 3A, 30VDC 3A RESISTIVE LOAD

Δ SOURCE 100-240VAC © 50/60Hz

Input Connections

PA10-U

PA10-V / PA10-W

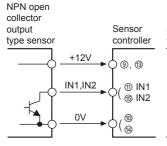
PA10-VP / PA10-WP

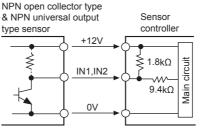
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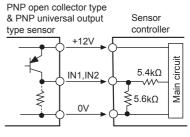
SOURCE

50/60Hz

100-240VAC ©

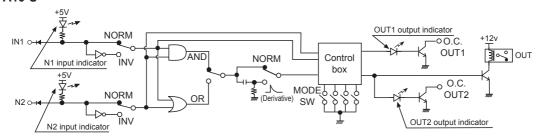




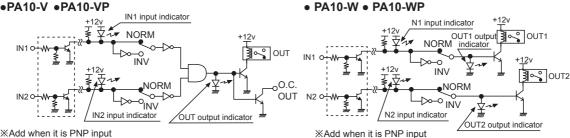


Function Diagram

●PA10-U







Unit Description

• PA10-U

- 1. Power indicator:
- LED is turned on when AC power applied
- 2. Output1 indicator:
- Indication of output 1 operation status
- 3. Output2 indicator:
- Indication of output 2 operation status 4. Sensor input indicator
- Indicates sensor input signal
 - (LED is turned on when sensor input is Low)
- 5. AND/OR selection switch:
 - Select "AND" or "OR" for IN1, IN2 Input
- 6. Selection switch of sensor input signal
 - NORM INV (Reverse function of input signal) NORM: LED is turned on when input signal is low. (¬_)
 - INV: LED is turned on when input signal is high. (」
- 7. Derivative action selection of IN2 input signal (OR/AND selection switch: AND)

NORM (When input signal is high (_ f) it is effective signal.)

- NORM: IN2 input signal is operating as reverse turn function • IN2 Derivative action of IN2 input signal. (*Refer to O-8, Application of derivative operation,)

2 OUT1 5 PA10-U 6 • IN 1 7 10

- 8. Selection switch for operation mode: See < ■ Operation mode > in next page.
- Selection switch of time range and max. input frequency: It is the switch to select time range (1 to 7 mode) or allowable input frequency (9 to 11 mode).
- Time range: Approx. 0 01 to 0.1sec Max. input frequency: 100kHz • Time range: Approx. 0.1 to 1sec
 - Max. input frequency: 10kHz • Time range: Approx. 1 to 10sec
 - Max. input frequency: 1kHz • Time range: Approx. 10 to 100sec
 - Max. input frequency: 100Hz
- 10. Timer adjuster

Adjust time as same as the range of 9.

11. Terminal block

PA10-V/PA10-VP

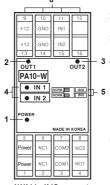
PA10-V ● IN 1 ## P## b 4 ● IN 2

1. Power indicator:

- LED is turned on when AC power applied 2. Output indicator:
 - Indicates output operation
- 3. Sensor input indicator:
 - PA10-V: Indicates sensor input signal (LED turns on when sensor input is Low) 2
 - PA10-VP: Indicates sensor input signal (LED turns on when sensor input is
- 4. Selection switch of sensor input signal
- NORM: When sensor input signal is Low, it is vaild signal.
- INV: When sensor input signal is High, it is valid signal.
- 5. Terminal block

*When IN1, IN2 input signal is AND, OUT will work.

• PA10-W/PA10-WP



XIN1, IN2 operates individually.

- 1. Power indicator:
 - LED is turned on when AC power applied
- 2. Output1 indicator:
 - Indication of output 1 operation status
- 3. Output2 indicator:

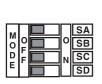
Indication of output 2 operation status

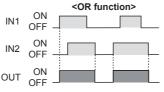
- Sensor input indicator:
 - •PA10-W: Indicates sensor input signal (LED is turned on when sensor input is
 - •PA10-WP: Indicates sensor input signal (LED is turned on when sensor input is
- 5. Selection switch of sensor input signal
 - •NORM: When sensor input signal is Low, it is valid signal.
 - •INV: When sensor input signal is High, it is vaild signal.
- 6. Terminal block

■ Operation Mode (PA10-U)

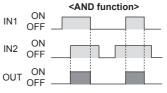
• MODE 0 Normal mode

OUT will work according to input signal regardless Timer.





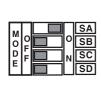
XOutput will be ON when either IN1 or IN2 is ON.

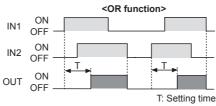


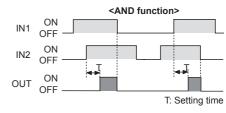
XOutput will be ON when both IN1 and IN2 are ON.

• MODE 1 ON-Delay mode

OUT will be ON after delayed as setting time according to one of IN1 and IN2 is ON. When IN1 and IN2 are OFF, OUT will be OFF.



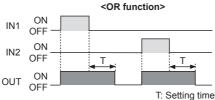


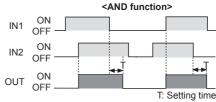


• MODE 2 OFF-Delay mode

OUT will be ON at the same time when IN1 or IN2 is ON then OUT will be OFF after delayed as setting time according to IN1 or IN2 is OFF.

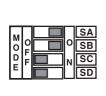


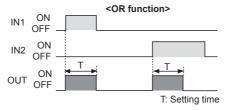


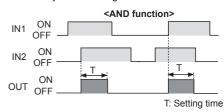


• MODE 3 ONE-Shot delay mode

OUT will be ON at the same time with IN1 or IN2 is ON then OUT will be OFF after delayed as setting time.

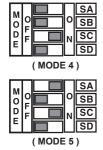


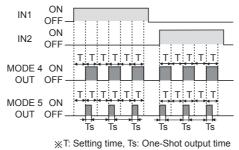




• MODE 4, 5 Flicker mode / Flicker one-shot mode

OUT will be ON after delayed as setting time for IN1 input then it is flashing and OUT will be flashing after setting time from ON. But, in case of one-shot mode, output time (Ts) will selected by NORM ITS = Approx. 10ms, NORM ITS = Approx. 100ms)





Note)ON/OFF ratio of flicker output is 1:1

Note)In case of flicker mode, it is not different between OR AND and NORM STATE OF OR STATE OF

Note)In case of one-shot mode, it is not different between OR NOD .

(A) Photoelectric Sensors

(B) Fiber Optic Sensors

> (C) Door/Area Sensors (D) Proximity Sensors

(E) Pressure Sensors

> F) totary incoders

(G) Connectors/ Connector Cables/ Sensor Distribution Boxes/Sockets

Controllers

(I) SSRs / Powe Controllers

Counters

(L) Panel Meters

(M) Tacho / Speed / Puls Meters

(N) Display Units

(O) Sensor Controllers

(P)
Switching
Mode Power
Supplies

(Q)
Stepper Motors
& Drivers
& Controllers

(R) Graphic/ Logic Panels

(S) Field Network Devices

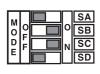
(T) Software

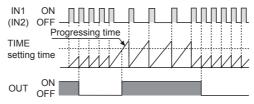
0-5

Operation Mode (PA10-U)

MODE 6 Low-speed detection mode

OUT will be ON when input signal (IN1) is longer than setting time by comparing it to the setting time by one cycle.



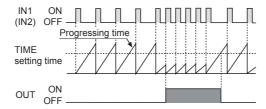


Note)Above is when input logic is OR and it will be the same by using IN2 input signal terminal instead of IN1. Note)When use MODE 6 as above, be sure that OUT will be work at the same time with power supply.

• MODE 7 High-speed detection mode

OUT will be ON when input signal (IN1) is shorter than setting time by comparing it to the setting time by one cycle.





Note) Above is when input logic is OR and it will be the same by using IN2 input signal terminal instead of IN1.

Time switches

Set the time by time switches (T1, T2) and front time adjuster (ADJ).

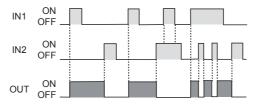
M	ODE	MODE 1 to MODE 7, MODE 12	MODE 6 to MODE 7	
TIME S/W	Item	Setting time range	Input frequency	rpm
O O T		0.01 to 0.1sec	100 to 10Hz	6,000 to 600rpm
O O T O T	_	0.1 to1sec	10 to 1Hz	600 to 60rpm
O O T F N T		1 to 10sec	1 to 0.1Hz	60 to 6rpm
O O T O T N T	Γ1 Γ2	10 to 100sec	0.1 to 0.01Hz	6 to 0.6rpm

XRange of operating rpm is 1 pulse per 1 revolution.

MODE 8 Flip-Flop mode [OUT latch operation]

When IN1 signal is input then the Flip-Flop output will be ON (SET). When the IN2 signal is input, Flip-Flop Signal will be OFF (RESET).





Note)IN2 will be prior to all input signal.

Note)Both OR AND and NORM Switches are allowed to use.

Note) There is no Timer function in Flip-Flop Mode, therefore use this unit with time switches (T1, T2) are OFF.

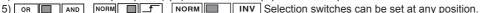
O-6 Autonics

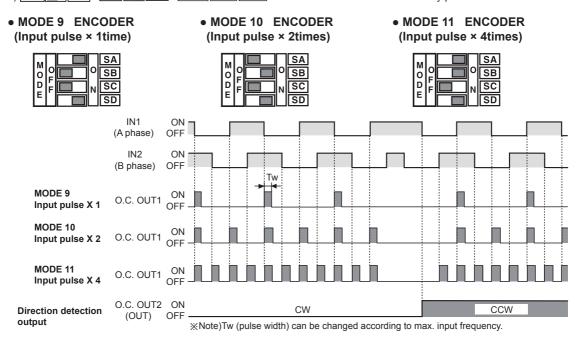
When the pulse is increasing per 1 revolution, range of operating rpm is decreasing.

■ Operation Mode (PA10-U)

© Encoder mode (MODE 9 to MODE 11)

- 1) There should be 90° phase difference between IN1 and IN2 for input terminal.
- 2) Please connect A phase output of encoder to IN1 and B phase output of encoder to IN2, when use NPN open collector or totem pole output type of encoder with PA10-U. In this case, detection signal (O.C. OUT2) output of PA10-U will be OFF when turning encoder to CW direction.
- 3) There are output function of pulse (O.C. OUT1) has been multiplied (×1, ×2, ×4 times) against input signal and Direction detection output (O.C. OUT2) function which detects direction of encoder revolution in Encoder mode.
- 4) Be cautious about input speed (cps) of connected equipment due to pulse width of O.C. OUT1 is short.





O Time switches in encoder mode

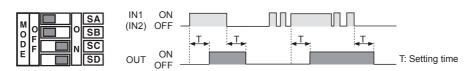
Time switch is to convert output pulse width (Tw).

Time switch	Max. input frequency	Output pulse width (Tw)	Input speed of connected equipment (cps)
O O T1 F N T2	100kHz	Approx. 0.5μs	Min. 2000kHz (2,000kcps)
O O T1 F N T2	10kHz	Approx. 5µs	Min. 200kHz (200kcps)
0 0 T1 F N T2	1kHz	Approx. 50μs	Min. 20kHz (20kcps)
O O T1 F N T2	100Hz	Approx. 500μs	Min. 2kHz (2kcps)

• MODE 12 ON/OFF-DELAY MODE

OUT will be ON after setting time when IN1 (or IN2) is ON. When IN1 (or IN2) is OFF, OUT will be OFF after setting time. (This is when input logic is OR)

XIf IN1 (or IN2) ON/OFF time is shorter than setting time, OUT does not turn.



(A) Photoelectric Sensors

(B) Fiber Optic

(C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure Sensors

(F) Rotary Encoders

(G) Connectors/ Connector Cables/ Sensor Distribution Boxes/Sockets

(H) Temperature

Controllers

(I) SSRs / Power Controllers

(J) Counters

(K) Timers

(M) Tacho / Speed / Pulse Meters

(N)

(N) Display Units

(O) Sensor Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

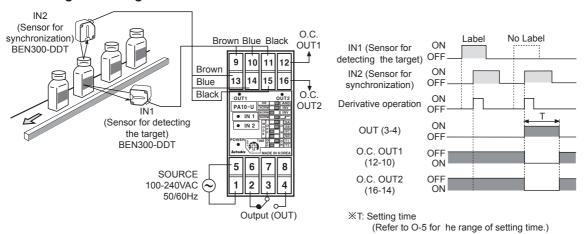
(S) Field Network Devices

> 「) oftware

Autonics O-7

Application of Derivative Operation

O Sensing labels of glass bottles



Operation

When IN2 is ON after IN1 is ON, OUT will not operate. But if there is no label on bottle, OUT will operate with IN2 is ON only. OUT will be returned after setting time.

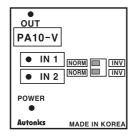
Note)Please install the sensor (IN1) to be operated first.

■ Factory Default for S/W

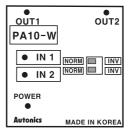
●PA10-U: MODE1 ON-DELAY



●PA10-V: NORM ●PA10-VP: NORM



- ●PA10-W: NORM
- •PA10-WP: NORM



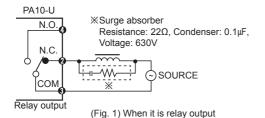
Proper Usage

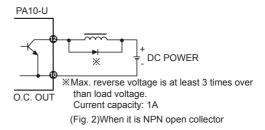
O Load connections

It is important to protect from surge or noise by installing a surge absorber across inductive loads (motor, solenoid, etc.)

In case the load is a DC relay, please install a diode across relay as shown below.

(Be careful of polarity.)



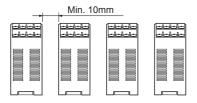


Input signal line

- Please make the cable line short from input sensor to this controller.
- Do not put input signal line with other power cable in the same conduit.
- When need to extend the input signal line, please use shielded cable.

O Precaution for installation

When it is required to install more than two PA10s, the space between two PA10s should be larger than 10mm in order for proper cooling.



Other precautions

- Installation and dismantlement should be done with power off.
- Please check connections before wiring.
- Good ventilation must be considered to protect heating from inner components.
 - (Ambient operating temperature is -10°C to 55°C.)
- Do not supply over 100-240VAC.
- Do not install this controller at place where there are dust, steam, corrosive gas, water etc.
- AC power line must be separated from O.C. output line or signal input line.
- This controller has been designed to have high speed response (5µs) for O.C. output. If using micro switch or limit switch for signal input, chattering might be occurred at O.C. output.

(A) Photoelectric Sensors

(B) Fiber Optic Sensors

> (C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure Sensors

> (F) Rotary

(G) Connectors/ Connector Cables/ Sensor Distribution Boxes/Sockets

(H) Temperatur Controllers

(I) SSRs / Power Controllers

(J) Counters

(K) Timers

(L) Panel Meters

(M) Tacho / Speed / Pulse Meters

> N) Display Jnits

(O) Sensor

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

(S) Field Network Devices

(T) Software

Autonics O-9