Autonics

5 PHASE HOLLOW SHAFT TYPE STEPPER MOTOR

INSTRUCTION MANUAL





Thank you very much for selecting Autonics products. For your safety, please read the following before using.

Safety Considerations

×Please observe all safety considerations for safe and proper product operation to avoid hazards

★▲ symbol represents caution due to special circumstances in which hazards may occur.

▲ Warning Failure to follow these instructions may result in serious injury or death

▲ Caution Failure to follow these instructions may result in personal injury or product damage.

∆Warning

Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety

equipment, crime/disaster prevention devices, etc.)
Failure to follow this instruction may result in fire, personal injury, or economic loss. 2. Fix the unit on the metal plate.

Failure to follow this instruction may result in personal injury, or product and ambient equipment damage.

3. Do not connect, repair, or inspect the unit while connected to a power source. Failure to follow this instruction may result in fire.

4. Install the unit after considering counter plan against power failure.

Failure to follow this instruction may result in personal injury, or economic loss

5. Check 'Connections' before wiring.
Failure to follow this instruction may result in fire.

6. Do not disassemble or modify the unit.

Failure to follow this instruction may result in electric shock or fire.

7. Install the motor in the housing or ground it.
Failure to follow this instruction may result in electronic shock, fire, or personal injury.

8. Make sure to install covers on motor rotating components.

Failure to follow this instruction may result in personal injury.

9. Do not touch the unit during or after operation for a while.

Failure to follow this instruction may result in burn due to high temperature of the surface.

10. Turn OFF the power directly when error occurs.

Failure to follow this instruction may result in electric shock, fire, or personal injury.

∆ Caution

 Use the unit within the rated specifications.
 Failure to follow this instruction may result in fire or product damage. 2. Use dry cloth to clean the unit, and do not use water or organic solvent.

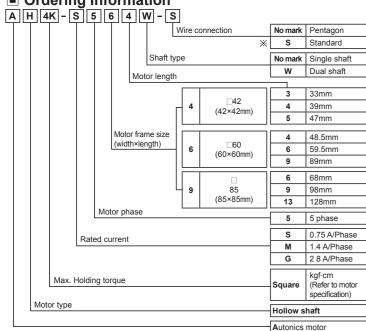
Failure to follow this instruction may result in fire.

3. Do not use the unit in the place where flammable/explosive/corrosive gas, humidity, direct sunlight, radiant heat, vibration, impact, or salinity may be present. Failure to follow this instruction may result in fire or explosion.

4. The motor may overheat depending on the environment

Install the unit at the well-ventilated environment and forced cooling with a cooling fan. Failure to follow this instruction may result in product damage and degrada ion.

Ordering Information



**Standard wiring is optional. **The above specifications are subject to change and some models may be discontinued without notice

*Be sure to follow cautions written in the instruction manual and the technical descriptions

Specifications

□42				
Model	AH1K-S543-	AH2K-S544-	AH3K-S545-	
Max. holding torque(€ 1)	1.3 kgf cm (0.13 N m)	1 8 kgf·cm (0.18 N·m)	2.4 kgf cm (0 24 N m)	
Moment of rotor inertia	35 g cm ² (35x10 ⁻⁷ kg m ²)	54 g·cm² (54x10 ⁻⁷ kg·m²)	68 g cm² (68x10 ⁻⁷ kg·m²)	
Rated current	0.75 A/Phase			
Basic step angle	0.72 / 0.36 (Full/Half)			
Unit weight	Annrox 0.25kg	Approx 0.3kg	Annrox 0.4kg	

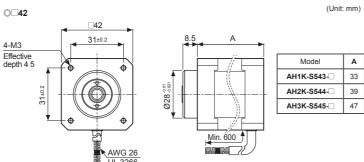
□60						
Model	AH4K- S564(W)-□	AH4K- M564(W)-□	AH8K- S566(W)-	AH8K- M566(W)-□	AH16K- M569(W)-	AH16K- G569(W)-□
Max. holding torque (*1)		gf-cm N m)		gf-cm N-m)		kgf-cm N-m)
Moment of rotor inertia	175 g·cm² (175x10 ⁻⁷ kg m²)		280 g cm ² (280x10 ⁻⁷ kg·m ²)		560 g cm ² (560x10 ⁻⁷ kg·m ²)	
Rated current	0.75 A/Phase	1.4 A/Phase	0.75 A/Phase	1.4 A/Phase	1.4 A/Phase	2.8 A/Phase
Basic step angle			0.72 /0.36	(Full/Half)		
Linit weight	Annroy	. 0.6kg	Annroy	n 8ka	Annroy	1 3kg

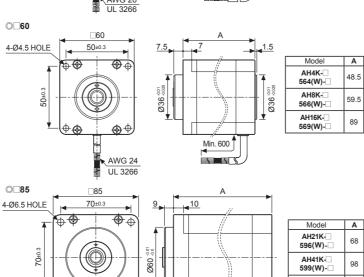
□85						
Model	AH21K- M596(W)-	AH21K- G596(W)-□	AH41K- M599(W)-□	AH41K- G599(W)-	AH63K- M5913(W)-	AH63K- G5913(W)-
Max. holding torque (※1)		gf-cm N m)		gf·cm N m)	63 kg (6 3	gf-cm N m)
Moment of rotor inertia		g·cm² 0 ^{·7} kg m²)		g·cm² 0 ⁻⁷ kg m²)	4,000 (4,000x1)	
Rated current	1.4 A/Phase	2.8 A/Phase	1.4 A/Phase	2.8 A/Phase	1.4 A/Phase	2 8 A/Phase
Basic step angle	0.72 / 0 36 (Full/Half)					
Unit weight	Approx	. 1.7kg	Approx	c. 2 8kg	Approx	. 3.8kg

1: Max. Holding torque is a retaining torque when 5 phase excitation stopped after the rated current is flowed

Common specification		
Insulation resistance	Min. 100№ (at 500VDC megger) between Motor coil-case	
Dielectric strength	1 kVAC(at 0.75 A/Phase is 0.5 kVAC) 50/60Hz for 1 minute between Motor coil-case	
Temperature rise	5-Phase excitation for rated current, below 80°C at stop status (resistance method)	
Ambient temperature	-10 to 50 °C, Storage: -25 to 85 °C	
Ambient humidity	35 to 85%RH, Storage: 35 to 85%RH	
Protection	IP30 (EC34-5 standards)	

Dimensions





Min. 600

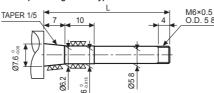
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AWG 22

Processing Example for Shaft Assembly

In order to assemble external shafts into Autonics motors, the shafts must be processed as shown in the figures below This motor is developed for direct connection to the axis of Ball-screw or TM-screw, etc. without

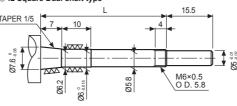
042 Square Single shaft type



Model AH1K-S543-42 5 AH2K-S544-48 5 AH3K-S545-56 5

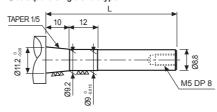
(Unit:mm)

042 Square Dual shaft type



Model AH1K- 543-42 5 AH2K-□544-□ 48 5 AH3K- 545-56 5 XLock Nut is included.

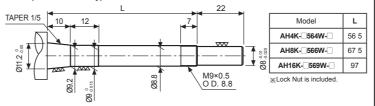
○60 Square Single shaft type



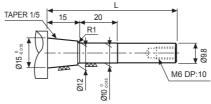
Model 46 AH4K- 564-57 AH8K- 566-AH16K- 569-86 5 «Hexagon socket bolt, Plane washer, Spring washer and Lock

Nut are included.

○60 Square Dual shaft type

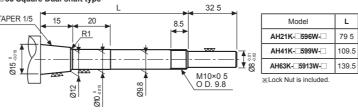


085 Square Single shaft type



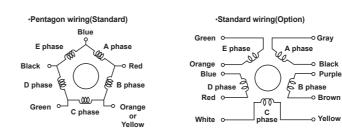
Model L 64 5 AH21K- 596-AH41K-_599-94 AH63K-□5913-□ 124.5 ※Hexagon socket screw, Plane washer, Spring washer and Lock Nut are included.

○85 Square Dual shaft type



■ Connection Diagram

Refer to the below for correlations of motor's each phase(coil) and the color of lead wire. Note that Pentagon connection type is a standard model (Standard connection type is an option model.)



In case of connecting standard connection type models to motor drivers. make sure that motor's lead wire connection must be made as specified in the

AH63K-

5913(W)-

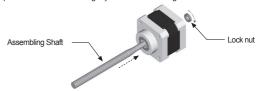
Lead wire color for Standard Lead wire color for Pentagon Gray + Red Orange + White Orange Brown + Green Green Blue + Purple Black

Shaft Assembly for Hollow Shaft with Motor

Make sure that external shaft assembly into motors must be made as sturdy as possible. If not, motor's torque might not be thoroughly transmitted to the shaft. In case no additional shaft assembly changes would be made, it is recommended to apply adhesives on screw fixing part.

TAP hole type motor

Use pliers to fasten lock nut tightly as shown in the figure below.



Through hole type motor with single shaft

Use hexagon socket screws, flat washers, spring washers and lock washers to fasten the shaft tightly as shown in the figure below

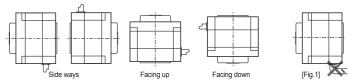
·Through hole type motor with dual shaft Use a lock nut to fasten the shaft tightly as shown in the figure below





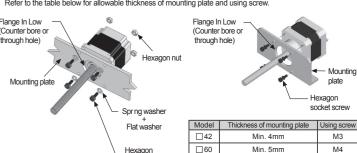
Motor Mounting

Motors can be mounted in any directions - facing up, facing down and side ways. No matter which direction motors to be mounted, be sure not to apply overhung or thrust load on the shaft. Do not apply excessive force on motor cable when mounting motors like [Fig.1]. t may cause disconnection of motor cable



With considering heat radiation and vibration isolation, mount the motor as tight as possible against a meta panel having high thermal conductivity such as iron or aluminum.

When mounting motors, use hexagon socket screw, hexagon nuts, spring washers, flat washers Refer to the table below for allowable thickness of mounting plate and using screv



Caution during Use

- . Follow instructions in 'Cautions during Use'. O herwise, It may cause unexpected accidents.
- Using motors at low temperature may cause reducing ball bearing's grease consistency
- and friction torque is increased. Start the motor in a steady manner since motor's torque is not to be influenced.
- . For using motor, it is recommended to maintenance and inspection regularly.
- ①Unwinding bolts and connection parts for the unit installa ion and load connec ion ②Strange sound from ball bearing of he unit
- 3 Damage and stress of lead cable of the unit 4 Connection error with driver
- ⑤Inconsistency between he axis of motor output and the center, concentric (eccentric, declination) of the load, etc.
- 4. This unit may be used in the following environments
- (1) Indoors (in the environment condition rated in 'Specifications')
- ②Altitude max. 2,000m
- ③Pollution degree 2 Installa ion category II

Major Products

■ Photoelectric Sensors ■ Temperature Controllers ■ Fiber Optic Sensors ■ Temperature/Humidity Transducers

- Door Side Sensors Counters
- Area Sensors
- Timers
- Proximity Sensors Panel Meters ■ Pressure Sensors ■ Tachometer/Pulse (Rate) Meters
- Rotary Encoders ■ Connectors/Sockets
 ■ Sensor Controller
- Switching Mode Power Supplies
 Control Switches/Lamps/Buzzers
- I/O Terminal Blocks & Cables
- Stepper Motors/Drivers/Motion Controller ■ Graphic/Logic Panels
- Field Network Devices
- Laser Marking System (Fiber, CO₂, Nd: YAG)
- Laser Welding/Cutting Syster

DRW171404AA

- Mountina

МЗ

M4

M6

Min 8mm