## **Autonics**

# **ROTARY ENCODER(INCREMENTAL TYPE)** E30S4 SERIES

#### INSTRUCTION MANUAL





Thank you for choosing our Autonics product. Please read the following safety considerations before use.

## Safety Considerations

\*\*Please observe all safety considerations for safe and proper product operation to avoid hazards. 

▲ Warning Failure to follow these instructions may result in serious injury or death.
 ▲ Caution Failure to follow these instructions may result in personal injury or product damage.

# **△ Warning**

- 1. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment, ships. vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.)
- Failure to follow this instruction may result in fire, personal injury, or economic loss.
- 2. Install on a device panel to use. Failure to follow this instruction may result in fire.
- 3. Do not connect, repair, or inspect the unit while connected to a power source
- Failure to follow this instruction may result in fire.
- 4. Check 'Connections' before wiring.
- Failure to follow this instruction may result in fire.
- 5. Do not disassemble or modify the unit. Failure to follow this instruction may result in fire

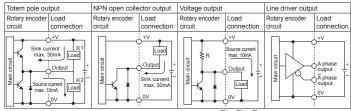
#### **△** Caution

- 1. Use the unit within the rated specifications.
- Failure to follow this instruction may result in fire or product damage 2. Do not short the load.
- Failure to follow this instruction may result in product damage by fire.
- 3. Do not use the unit in the place where flammable/explosive/corrosive gas, humidity, direct sunlight, radiant heat, vibration, impact, or salinity may be present. Failure to follow this instruction may result in fire or explosion
- 4. Do not use the unit near the place where there is the equipment which generates strong magnetic force or high frequency noise and strong alkaline, strong acidic exists. Failure to follow this instruction may result in product damage

## Ordering Information

E30S	4	3000	3	- N	24	
Series		Pulses/ revolution	Output phase	Control output	Power supply	Cable
Ø30mm, shaft type	Ø4mm	100, 200, 360, 500, 1000, 1024, 3000			5: 5VDC ±5% 24: 12-24VDC ±5%	No mark : axial cable type C: axial cable connector type
*The power of Line driver is only for 5VDC						

## Control Output Diagram



- The output circuit of A. B. Z phase are the same. (line driver output is A. A. B. B. Z. Z)
- Totem pole output type can be used for NPN open collector type (X1) or voltage output type (X2).
- stThe above specifications are subject to change and some models may be discontinued without notice. \*Be sure to follow cautions written in the instruction manual, and the technical descriptions (catalog, homepage).

### Specifications

_							
Item				Shaft type Ø30mm Incremental Rotary Encoder			
Resolution (PPR) <sup>×1</sup>				100, 200, 360, 500, 1000, 1024, 3000			
	Outp	Output phase		A, B, Z phase (line driver: A, $\overline{A}$ , B, $\overline{B}$ , Z, $\overline{Z}$ phase)			
	Phase difference of output			Phase difference between A and B: $\frac{T}{4} \pm \frac{T}{8}$ (T=1 cycle of A phase)			
	output	Totem pole output		[Low] - Load current: max. 30mA, residual voltage: max. 0.4VDC     [High] - Load current: max. 10mA,     Output voltage (power voltage 5VDC ): min. (power voltage-2.0)VDC ,     Output voltage (power voltage 12-24VDC ): min. (power voltage-3.0)VDC			
	[ [	NPN o	pen collector output	Load current: max. 30mA, residual voltage: max. 0.4VDC			
ou	Control	Voltage	e output	Load current: max. 10mA, residual voltage: max. 0.4VDC			
Electrical specification			iver output	[Low] - Load current: max. 20mA, residual voltage: max. 0.5VDC     [High] - Load current: max20mA, output voltage: min. 2.5VDC			
	e	Totem pole output		Max. 1μs (cable length: 2m, I sink = 20mA)			
			pen collector output				
	sponse (rise/fa	Voltage	pole output pen collector output e output	Max. 1 $\mu$ s (5VDC: output resistance 820 $\Omega$ ), Max. 2 $\mu$ s (12-24VDC: output resistance 4.7k $\Omega$ ) (cable length: 2 $m$ , 1 sink = 20 $m$ A)			
ш	w	Line dr	iver output	Max. 0.5µs (cable length: 2m, I sink = 20mA)			
	Max. response frequency		se frequency	300kHz			
	Power supply		у	• 5VDC ±5% (ripple P-P: max. 5%) • 12-24VDC ±5% (ripple P-P: max. 5%)			
	Current consumption			Max. 80mA (disconnection of the load), line driver output: max. 50mA (disconnection of the load)			
	Insul	ation re	sistance	Over 100MΩ (at 500VDC megger between all terminals and case)			
	Diele	ctric str	ength	750VAC 50/60Hz for 1 minute (between all terminals and case)			
	Conr	nection		Axial cable type, axial cable connector type			
al	Start	ing torq	ue	Max. 20gf cm (0.002N m)			
ati izi	Mom	ent of ir	nertia	Max. 20g cm² (2×10 <sup>-6</sup> kg m²)			
cha	Shaft	t loading	1	Radial: max. 2kgf, Thrust: max. 1kgf			
Me	Starting torque  Moment of inertia  Shaft loading  Max. allowable revolution <sup>×2</sup>		ole revolution <sup>×2</sup>	5.000rpm			
l	Vibration			1.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 2 hours			
Shock	k			Approx. max. 50G			
			Ambient temp.	-10 to 70°C, storage: -25 to 85°C			
		Ambient humidity	35 to 85%RH, storage: 35 to 90%RH				
Protection structure			e	IP50 (IEC standard)			
Cable				Ø5mm, 5-wire (line driver: 8-wire), 2m, Shield cable (AWG24, core diameter: 0.08mm, number of cores: 40, insulator out diameter: Ø1mm			
Acces	Accessory			Ø4mm coupling			
Approval				€ (except line driver output)			
Unit v		ř		Approx. 80g			
			resolutions are custo				

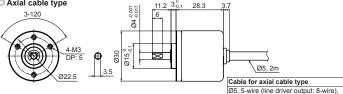
×1: Not indicated resolutions are customizable. 

×Environment resistance is rated at no freezing or condensation. ※2: Make sure that max. response revolution should be lower than or equal to max. allowable revolution when selecting the resolution.

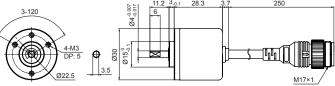
Max. response frequency × 60 sec] [Max. response revolution (rpm)= Resolution

#### Dimensions

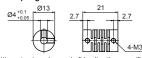
Axial cable type



Axial cable connector type



Coupling



250mm, Shield cable

Parallel misalignment=Max. 0.25mm

Angular misalignment=Max. 5

Cable for axial cable connector type

Ø5. 5-wire (line driver output: 8-wire).

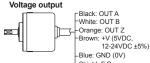
2m. Shield cable

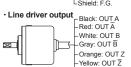
End-play=Max. 0.5mm XIt must not use larger shaft loading than specification.

- XDo not put strong impact when insert a coupling into shaft.
- Failure to follow this instruction may result in product damage \*Fix the unit or a coupling by a wrench under 0.15 N·m of torque.
- \*When you install this unit, if eccentricity and deflection angle are larger, it may shorten the life cycle of this unit

#### Connections

- O Axial cable type
- · Totem pole output / NPN open collector output /





- Axial cable connector type
- Totem pole output /
- NPN open collector output / Voltage output



· Line driver output

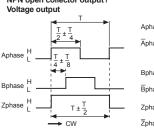
-Blue: GND (0V) -Shield: F.G.	Totem pole output / NPN open collector output / Voltage output			Line driver output		
Black: OUT A	Pin No	Function	Cable color	Pin No	Function	Cable color
-Red: OUT A -White: OUT B	1	OUTA	Black	1	OUTA	Black
Gray: OUT B	2	OUT B	White	2	OUTĀ	Red
-Orange: OUT Z	3	OUT Z	Orange	3	+V	Brown
-Yellow: OUT Z	4	+V	Brown	4	GND	Blue
-Brown: +V (5VDC ±5%)	(5)	GND	Blue	(5)	OUT B	White
-Blue: GND (0V)	6	F.G.	Shield	6	OUT B	Gray
-Snield: F.G.				7	OUT Z	Orange
				8	OUT Z	Yellow
!				9	F.G.	Shield

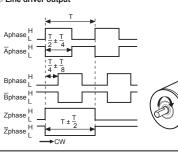
\*The metal case and shield wire of encoder should be grounded (F.G.).

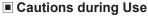
XDo not apply tensile strength over 30N to the cable.

## Output Waveform

O Totem pole output / Cline driver output NPN open collector output /







- 1. Follow instructions in 'Cautions during Use'. Otherwise, it may cause unexpected accidents.
- 2. 5VDC, 12-24VDC power supply should be insulated and limited voltage/current or Class 2, SELV power supply device.
- 3. For using the unit with the equipment which generates noise (switching regulator, inverter, servo motor, etc.), ground the shield wire to the F.G. terminal.
- 4. Ground the shield wire to the F.G. terminal.
- 5. When using switching mode power supply, frame ground (F.G.) terminal of power supply should be grounded.
- 6. Wire as short as possible and keep away from high voltage lines or power lines, to prevent inductive noise. 7. For Line driver unit, use the twisted pair wire which is attached seal and use the receiver for RS-422A
- 8. Check the wire type and response frequency when extending wire because of distortion of waveform or residual voltage increment etc by line resistance or capacity between lines.
- 9. This unit may be used in the following environments.
- ①Indoors (in the environment condition rated in 'Specifications') ③Pollution degree 2

SSRs/Power Controllers

■ Tachometer/Pulse (Rate) Meters

■ Counters

Panel Meters

■ Timers

②Altitude max. 2.000m 4 Installation category II

## Major Products

- Photoelectric Sensors Temperature Controllers
- Fiber Optic Sensors Temperature/Humidity Transducers
- Door Sensors ■ Door Side Sensors

(unit: mm)

- Area Sensors
- Proximity Sensors
- Pressuré Sensors
- Rotary Encoders

- Display Units
- Connector/Sockets
- Sensor Controllers ■ Switching Mode Power Supplies
- Control Switches/Lamps/Buzzers ■ I/O Terminal Blocks & Cables
- Stepper Motors/Drivers/Motion Controllers ■ Graphic/Logic Panels
- Field Network Devices
- Laser Marking System (Fiber, CO₂, Nd: YAG)
- Laser Welding/Cutting System

DRW171366AB