RECTILINEAR DISPLACEMENT TRANSDUCER WITH



PC

#### **Principal characteristics**

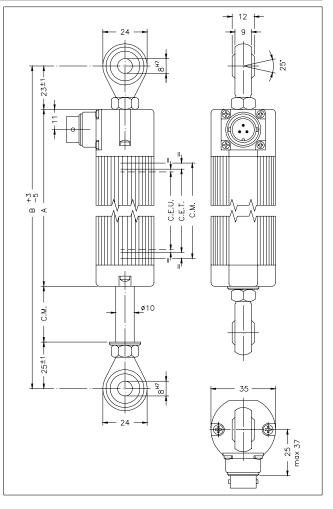
- The transducer is designed to satisfy extreme applicative demands in terms of mechanical strength.
- The 10 mm diameter rod, large steel joints, and reinforced structure make this series mechanically ideal for metalworking, woodworking, and ceramics.
- Installation is simplified by the lack of electrical signal variation at output outside theoretical electrical stroke.
- The structure based on self-aligning and weight-bearing ball joints permits assembly with free movement of the transducer axle.

### **TECHNICAL DATA**

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Useful electrical stroke (C.E.U.)	50/100/130/150/175/200/225/275/300/360/ 375/400/450/500/600/750
Independent linearity (within C.E.U.)	± 0,05%
Resolution	Infinite
Repeatability	0.01 mm
Protection	IP65
Displacement speed	≤ 5 m/s
Displacement force	≤ 15 N
Life	> 25x10° m strokes,or > 100x10° operations, whichever is less (within C.E.U.)
Vibrations	52000Hz, Amax =0.75 mm amax. = 20 g
Shock	50 g, 11ms.
Tolerance on resistance	± 20%
Recommended cursor current	< 0.1 µA
Maximum cursor current	10mA
Max. applicable voltage	60V
Electrical isolation	>100MΩ at 500V=, 1bar, 2s
Dielectric strength	< 100µA at 500V~, 50Hz, 2s, 1bar
Dissipation at 40°C (0W at 120°C)	зw
Actual Temperature Coefficient of the output voltage	≤ 1.5 ppm/°C
Working temperature	-30+100°C
Storage temperature	-50+120°C
Case material	Anodised aluminium Nylon 66 G
Control rod material	Stainless steel AISI 303
Fixing	2 selfloading and selfaligning ball-joints

### **MECHANICAL DIMENSIONS**

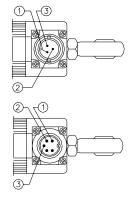


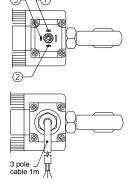
Important: all the data reported in the catalogue linearity, lifetime, temperature coefficient are valid for a sensor utilization as a ratiometric device with a max current across the cursor Ic  $\leq$  0.1  $\mu$ A.

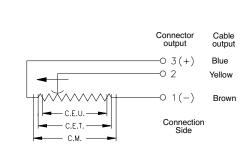
## **MECHANICAL / ELECTRICAL DATA**

MODEL		50	100	130	150	175	200	225	275	300	360	375	400	450	500	600	750
Useful electrical stroke (C.E.U.) +3/-0	mm	50	100	130	150	175	200	225	275	300	360	375	400	450	500	600	750
Theoretical electrical stroke (C.E.T.) ± 1	mm	C.E.U. + 3				C.E.U. + 4				364	380	406	457	508	609	762	
Resistance (C.E.T.)	kΩ	5				5			5	5	5	5	5	5	10		
Mechanical stroke (C.M.)	mm	C.E.U. + 9				C.E.U. + 10			370	386	412	463	518	619	772		
Case length (A)	mm	C.E.U. + 130.5				C.E.U. + 131.5			497.5	513.5	539.5	590.5	665.5	766.5	919.5		
Min. distance between ball-joints (B)	mm	C.E.U. + 177				C.E.U. + 178			544	560	586	637	712	813	966		

## **ELECTRICAL CONNECTIONS**



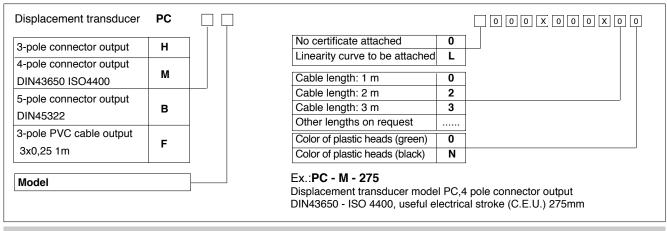




#### INSTALLATION INSTRUCTIONS

- · Respect the indicated electrical connections (DO NOT use the transducer as a variable resistance)
- When calibrating the transducer, be careful to set the stroke so that the output does not drop below 1% or rise beyond 99% of the supply voltage.

### **ORDER CODE**



# **OPTIONAL ACCESSORIES**

4-pin 90° radial female PCM connector INDUSTRIAL STANDARD EN175301 spacing 9,4 mm IP65 PG7 for cable ø4 - ø6 mm	CON008
3-pin axial female PCH connector IP40 clamp for wire ø4 - ø6 mm	CON002
5-pin axial female PCB connector DIN43322 IP40 clamp for wire ø4 - ø6 mm	CON011
5-pin axial female PCB connector DIN43322 IP65 clamp PG7 for wire ø4 - ø6 mm	CON012
5-pin 90° radial female PCB connector DIN43322 IP40 clamp for wire ø4 - ø6 mm	CON013

GEFRAN spa reserves the right to make any kind of design or functional modification at any moment without prior notice

