

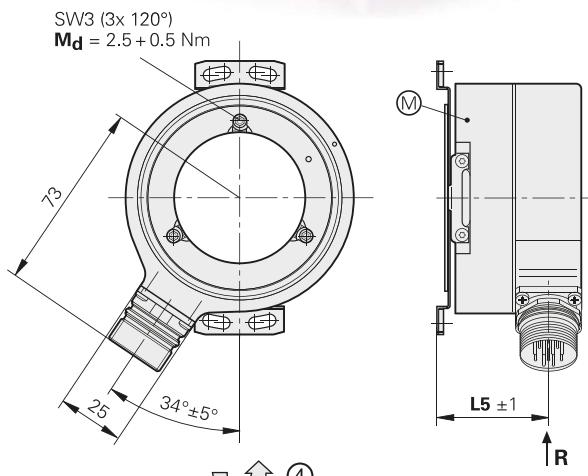
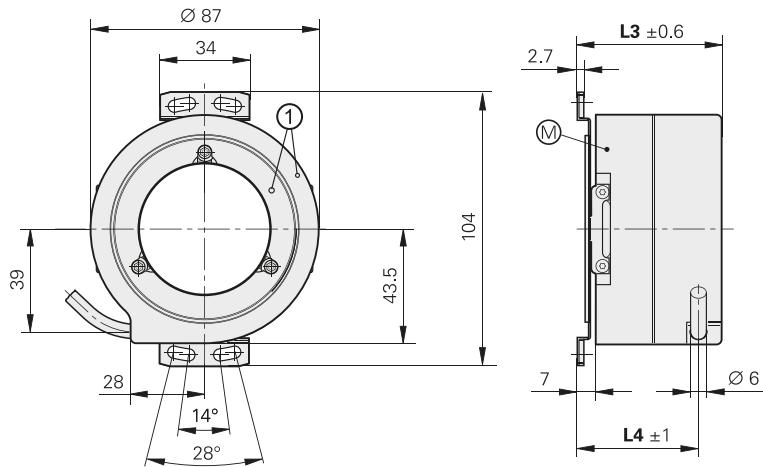
ECN/ERN 100 series

Absolute and incremental rotary encoders

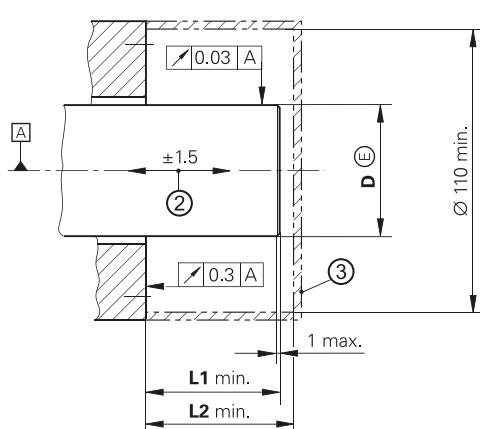
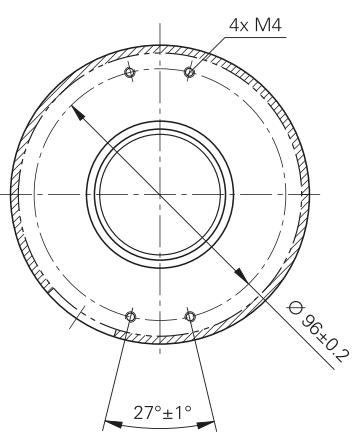
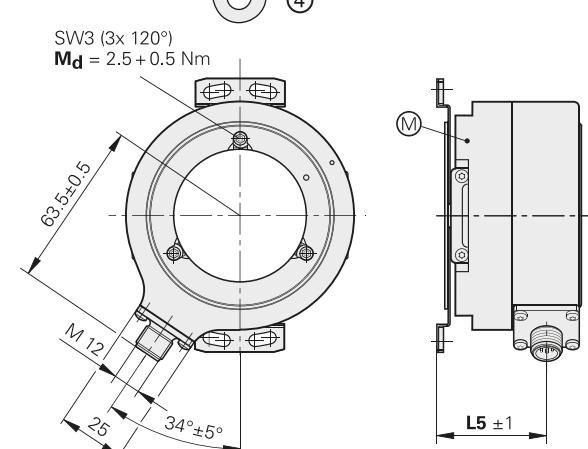
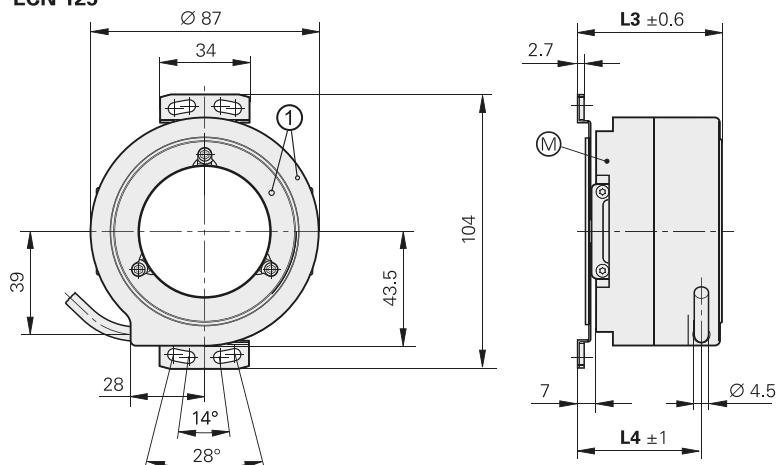
- Stator coupling for plane surface
- Hollow through shaft



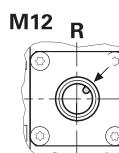
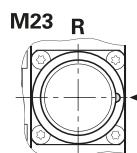
ERN 1x0/ECN 113



ECN 125



Connector coding
R = Radial



D	L1	L2	L3	L4	L5
Ø 20h7	41	43.5	40	32	26.5
Ø 25h7	41	43.5	40	32	26.5
Ø 38h7	56	58.5	55	47	41.5
Ø 50h7	56	58.5	55	47	41.5



Tolerancing ISO 8015
ISO 2768 - m H
< 6 mm: ±0.2 mm

Cable radial, also usable axially

Ⓐ = Bearing

Ⓜ = Measuring point for operating temperature

1 = ERN: reference mark position ±15°; ECN: Zero position ±15°

2 = Compensation of mounting tolerances and thermal expansion; no dynamic motion permitted

3 = Ensure protection against contact (EN 60 529)

4 = Direction of shaft rotation for output signals as per the interface description

	Absolute		Incremental		
	Singleturn				
	ECN 125	ECN 113	ERN 120	ERN 130	ERN 180
Interface	EnDat 2.2	EnDat 2.2	□ TTL	□ HTL	~ 1 V _{PP} ²⁾
Ordering designation	EnDat22	EnDat01	–		
Positions per revolution	33 554 432 (25 bits)	8192 (13 bits)	–		
Code	Pure binary		–		
Elec. permissible speed Deviation ¹⁾	n _{max} for continuous position value	≤ 600 rpm/n _{max} ±1 LSB/±50 LSB	–		
Calculation time t _{cal} Clock frequency	≤ 7 µs ≤ 16 MHz	≤ 9 µs ≤ 2 MHz	–		
Incremental signals	Without	~ 1 V _{PP} ²⁾	□ TTL	□ HTL	~ 1 V _{PP} ²⁾
Line counts*	–	2048	1000 1024 2048 2500 3600 5000		
Reference mark	–	–	One		
Cutoff frequency –3 dB Output frequency Edge separation a	– – –	≥ 400 kHz typical – –	– ≤ 300 kHz ≥ 0.39 µs	– – –	≥ 180 kHz typical – –
System accuracy	±20"		1/20 of grating period		
Electrical connection*	• Flange socket M12, radial • Cable 1 m/5 m, with M12 coupling	• Flange socket M23, radial • Cable 1 m/5 m, with or without M23 coupling	• Flange socket M23, radial • Cable 1 m/5 m, with or without M23 coupling		
Voltage supply	DC 3.6 V to 14 V		DC 5 V ± 0.5 V	DC 10 V to 30 V	DC 5 V ± 0.5 V
Power consumption (max.)	3.6 V: ≤ 620 mW/14 V: ≤ 720 mW		–		
Current consumption (without load)	5 V: ≤ 85 mA (typical)		≤ 120 mA	≤ 150 mA	≤ 120 mA
Shaft*	Hollow through shaft D = 20 mm, 25 mm , 38 mm, 50 mm				
Mech. permissible speed n ³⁾	D > 30 mm: ≤ 4000 rpm; D ≤ 30 mm: ≤ 6000 rpm				
Starting torque At 20 °C	D > 30 mm: ≤ 0.2 Nm D ≤ 30 mm: ≤ 0.15 Nm				
Moment of inertia of rotor/ angle acceleration ⁴⁾	D = 50 mm 220 × 10 ⁻⁶ kgm ² /≤ 5 × 10 ⁴ rad/s ² ; D = 38 mm 350 × 10 ⁻⁶ kgm ² /≤ 2 × 10 ⁴ rad/s ² D = 25 mm 96 × 10 ⁻⁶ kgm ² /≤ 3 × 10 ⁴ rad/s ² ; D = 20 mm 100 × 10 ⁻⁶ kgm ² /≤ 3 × 10 ⁴ rad/s ²				
Permissible axial motion of measured shaft	±1.5 mm				
Vibration 55 Hz to 2000 Hz Shock 6 ms	≤ 200 m/s ² ; flange socket version: ≤ 100 m/s ² (EN 60068-2-6) ≤ 1000 m/s ² (EN 60068-2-27)				
Max. operating temp. ³⁾	100 °C (85 °C for ERN 130)				
Min. operating temp.	Flange socket or fixed cable: –40 °C; moving cable: –10 °C				
Protection ³⁾ EN 60529	IP64				
Mass	0.6 kg to 0.9 kg depending on the hollow-shaft version				
Valid for ID	810801-xx	810800-xx	589611-xx	589612-xx	589614-xx

Bold: This preferred version is available on short notice. * Please select when ordering

¹⁾ Velocity-dependent deviations between the absolute value and incremental signals ²⁾ Restricted tolerances: signal amplitude 0.8 V_{PP} to 1.2 V_{PP}

³⁾ For the correlation between degree of protection, shaft speed and operating temperature, see *General mechanical information*

⁴⁾ At room temperature, determined mathematically; material of mating shaft: 1.4104