## Product data sheet Characteristics

## ATV320U22M2C

variable speed drive ATV320 - 2.2kW -200...240V - 1 phase - compact



#### Main

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Main		
Range of product	Altivar Machine ATV320	
Product or component type	Variable speed drive	
Product specific application	Complex machines	
Device short name	ATV320	
Format of the drive	Compact	
Product destination	Asynchronous motors Synchronous motors	
EMC filter	Class C2 EMC filter integrated	
IP degree of protection	IP20 conforming to EN/IEC 61800-5-1	
Degree of protection	UL type 1 with UL type 1 conformity kit	
Type of cooling	Fan	
Network number of phases	1 phase	
[Us] rated supply voltage	200240 V (- 1510 %)	
Supply frequency	5060 Hz (- 55 %)	
Motor power kW	2.2 kW for heavy duty	
Motor power hp	3 hp for heavy duty	
Line current	23.9 A at 200 V for heavy duty 20.1 A at 240 V for heavy duty	
Prospective line Isc	<= 1 kA	
Apparent power	4.8 kVA at 240 V for heavy duty	
Continuous output current	11 A at 4 kHz for heavy duty	
Maximum transient current	16.5 A during 60 s for heavy duty	
Asynchronous motor control profile	Voltage/Frequency ratio, 2 points Voltage/Frequency ratio, 5 points Flux vector control without sensor, standard Voltage/Frequency ratio - Energy Saving, quadratic U/f Flux vector control without sensor - Energy Saving	
Synchronous motor control profile	Vector control without sensor	
Speed drive output frequency	0.1599 Hz	



Nominal switching frequency	4 kHz	
Switching frequency	416 kHz with current derating 216 kHz adjustable	
Safety function	STO (safe torque off) SIL 3 SS1 (safe stop 1) SMS (safe maximum speed) SLS (safe limited speed) GDL (guard door locking)	
Communication port protocol	CANopen Modbus	
Option card	Communication module: CANopen daisy chain RJ45 Communication module: CANopen SUB-D 9 Communication module: CANopen open style terminal block Communication module: EtherCAT RJ45 Communication module: DeviceNet Communication module: Ethernet/IP Communication module: Profibus DP V1 Communication module: Profinet Communication module: Ethernet Powerlink	

#### Complementary

Complementary		
Output voltage	<= power supply voltage	
Permissible temporary current boost	1.5 x In during 60 s for heavy duty	
Speed range	1100 with asynchronous motor in open-loop mode	
Speed accuracy	+/- 10 % of nominal slip 0.2 Tn to Tn	
Torque accuracy	+/- 15 %	
Transient overtorque	170200 % of nominal motor torque	
Braking torque	< 170 % with braking resistor during 60 s	
Regulation loop	Adjustable PID regulator	
Motor slip compensation	Automatic whatever the load Not available in voltage/frequency ratio (2 or 5 points) Adjustable 0300 %	
Acceleration and deceleration ramps	S U CUS Deceleration ramp automatic stop DC injection Deceleration ramp adaptation Linear Ramp switching	
Braking to standstill	By DC injection	
Protection type	Drive: thermal protection Drive: overcurrent between output phases and earth Drive: input phase breaks Drive: overheating protection Drive: short-circuit between motor phases	
Frequency resolution	Display unit: 0.1 Hz Analog input: 0.012/50 Hz	
Electrical connection	Control, screw terminal: 0.51.5 mm² AWG 20AWG 16 Motor/Braking resistor, screw terminal: 6 mm² AWG 10 Power supply, screw terminal: 6 mm² AWG 10	
Type of connector	1 RJ45 for Modbus/CANopen on control terminal	
Physical interface	2-wire RS 485 for Modbus	
Transmission frame	RTU for Modbus	
Transmission rate	4.8, 9.6, 19.2, 38.4 kbit/s for Modbus 50 kbps, 125 kbps, 250 kbps, 500 kbps, 1 Mbps for CANopen	
Data format	8 bits, configurable odd, even or no parity for Modbus	
Type of polarization	No impedance for Modbus	
Number of addresses	1247 for Modbus 1127 for CANopen	
Method of access	Slave for CANopen	
Supply	Internal supply for reference potentiometer (1 to 10 kOhm): 10.5 V DC (+/- 5 %) current <= 10 mA (overload and short-circuit protection)	

Local signalling	1 LED green for CANopen run 1 LED red for CANopen error 1 LED red for drive fault	
Width	105 mm	
Height	142 mm 188 mm with EMC plate	
Depth	158 mm	
Product weight	1.6 kg	
Analogue input number	3	
Analogue input type	Voltage (AI1): 010 V DC, impedance 30000 Ohm, resolution 10 bits Bipolar differential voltage (AI2): +/- 10 V DC, impedance 30000 Ohm, resolution 10 bits Current (AI3): 020 mA (or 4-20 mA, x-20 mA, 20-x mA or other patterns by configuration), impedance 250 Ohm, resolution 10 bits	
Discrete input number	7	
Discrete input type	Programmable (sink/source) (DI1DI4): 2430 V DC: level 1 PLC Programmable as pulse input 20 kpps (DI5): 2430 V DC: level 1 PLC Switch-configurable PTC probe (DI6): 2430 V DC Safe torque off (STO): 2430 V DC, impedance 1500 Ohm	
Discrete input logic	Negative logic (sink): : DI1DI6, > 19 V (state 0) < 13 V (state 1) Positive logic (source): : DI1DI6, < 5 V (state 0) > 11 V (state 1)	
Analogue output number	1	
Analogue output type	Software-configurable current (AQ1): 020 mA, impedance 800 Ohm, resolution 10 bits Software-configurable voltage (AQ1): 010 V, impedance 470 Ohm, resolution 10 bits	
Sampling duration	Analog input (Al1, Al2, Al3): 2 ms Analog output (AQ1): 2 ms	
Accuracy	Analog input AI1, AI2, AI3: +/- 0.2 % for a temperature of -1060 °C Analog input AI1, AI2, AI3: +/- 0.5 % for a temperature of 25 °C Analog output AQ1: +/- 1 % for a temperature of 25 °C Analog output AQ1: +/- 2 % for a temperature of -1060 °C	
Linearity error	Analog input (AI1, AI2, AI3): +/- 0.20.5 % of maximum value Analog output (AQ1): +/- 0.3 %	
Discrete output number	3	
Discrete output type	Configurable relay logic NO/NC (R1A, R1B, R1C): electrical durability 100000 cycles Configurable relay logic NO (R2A, R2B): electrical durability 100000 cycles Logic (LO)	
Refresh time	Logic input (DI1DI6): 8 ms (+/- 0.7 ms) Relay output (R1A, R1B, R1C): 2 ms Relay output (R2A, R2C): 2 ms	
Minimum switching current	Relay output (R1, R2): 5 mA at 24 V DC	
Maximum switching current	Relay output (R1) on resistive load (cos phi = 1: 3 A at 250 V AC Relay output (R1) on resistive load (cos phi = 1: 4 A at 30 V DC Relay output (R1, R2) on inductive load (cos phi = 0.4: 2 A at 250 V AC Relay output (R1, R2) on inductive load (cos phi = 0.4: 2 A at 30 V DC Relay output (R2) on resistive load (cos phi = 1: 5 A at 250 V AC Relay output (R2) on resistive load (cos phi = 1: 5 A at 30 V DC	
Specific application	Machinery	

### Environment

Isolation	Between power and control terminals	
Insulation resistance	> 1 mOhm at 500 V DC for 1 minute to earth	
Noise level	48 dB conforming to 86/188/EEC	
Power dissipation in W	109.6 W (fan) at 200 V, 4 kHz	
Volume of cooling air	16 m3/h	
Operating position	Vertical +/- 10 degree	
Electromagnetic compatibility	Conducted radio-frequency immunity test conforming to IEC 61000-4-6 level 3 Electrical fast transient/burst immunity test conforming to IEC 61000-4-4 level 4 Electrostatic discharge immunity test conforming to IEC 61000-4-2 level 3 Radiated radio-frequency electromagnetic field immunity test conforming to IEC 61000-4-3 level 3 Voltage dips and interruptions immunity test conforming to IEC 61000-4-11 1.2/50 µs - 8/20 µs surge immunity test conforming to IEC 61000-4-5 level 3	
Pollution degree	2 conforming to EN/IEC 61800-5-1	
Vibration resistance	1.5 mm peak to peak (f = 213 Hz) conforming to EN/IEC 60068-2-6	

	1 gn (f = 13200 Hz) conforming to EN/IEC 60068-2-6
Shock resistance	15 gn during 11 ms conforming to EN/IEC 60068-2-27
Relative humidity	595 % without condensation conforming to IEC 60068-2-3 595 % without dripping water conforming to IEC 60068-2-3
Ambient air temperature for operation	-1050 °C without derating 5060 °C with derating factor
Ambient air temperature for storage	-2570 °C
Operating altitude	<= 1000 m without derating 10003000 m with current derating 1 % per 100 m
Standards	EN/IEC 61800-3 EN/IEC 61800-3 environment 1 category C2 EN/IEC 61800-5-1 IEC 60721-3 IEC 61508 IEC 13849-1
Product certifications	CSA NOM 117 UL RCM EAC
Marking	CE

### Offer Sustainability

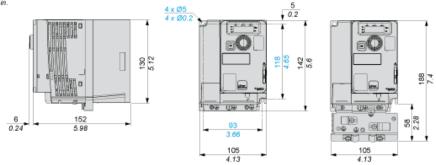
Sustainable offer status	Not Green Premium product	
RoHS (date code: YYWW)	Compliant - since 1610 - Schneider Electric declaration of conformity	
	🚰 Schneider Electric declaration of conformity	
REACh	Reference not containing SVHC above the threshold	
	Reference not containing SVHC above the threshold	

## Product data sheet **Dimensions Drawings**

# ATV320U22M2C

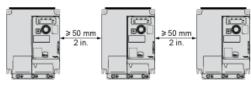
### Dimensions

Views: Right - Front - Front with EMC Plate mm in.



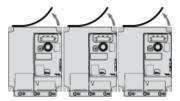
## Mounting Types

### Mounting Type A: Individual with Ventilation Cover



Only Possible at Ambient Temperature Less or Equal to 50 °C (122 °F)

### Mounting Type B: Side by Side, Ventilation Cover Removed



## Mounting Type C: Individual, Ventilation Cover Removed



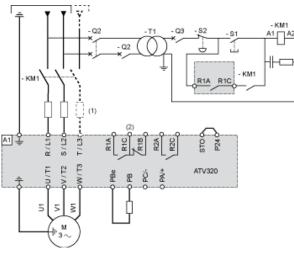
For Operation at Ambient Temperature Above 50 °C (122 °F)

#### Connections and Schem

#### **Connection Diagrams**

#### Diagram with Line Contactor

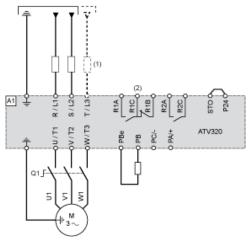
Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1.



- (1) Line choke (if used)
- (2) Fault relay contacts, for remote signaling of drive status

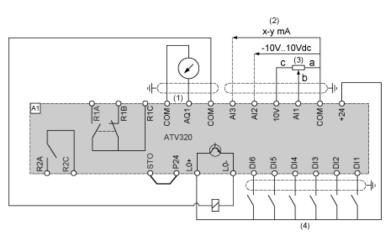
#### **Diagram with Switch Disconnect**

Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1.



- (1) Line choke (if used)
- (2) Fault relay contacts, for remote signaling of drive status

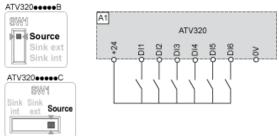
## Control Connection Diagram in Source Mode



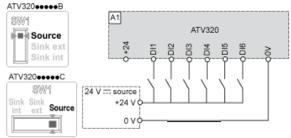
- Analog output Analog inputs (1)
- (2) (3) (4)
- Reference potentiometer (10 kOhm maxi)
- Digital inputs

### **Digital Inputs Wiring**

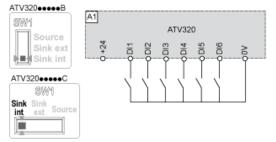
The logic input switch (SW1) is used to adapt the operation of the logic inputs to the technology of the programmable controller outputs. Switch SW1 set to "Source" position and use of the output power supply for the DIs.



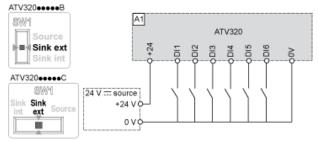
Switch SW1 set to "Source" position and use of an external power supply for the DIs.



Switch SW1 set to "Sink Int" position and use of the output power supply for the DIs.



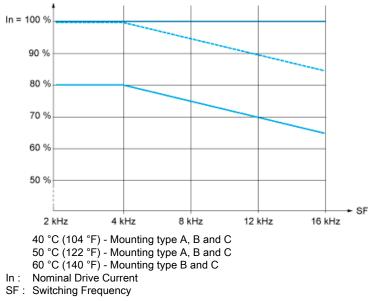
Switch SW1 set to "Sink Ext" position and use of an external power supply for the DIs.



Product data sheet Performance Curves

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## **Derating Curves**



Derating curve for the nominal drive current (In) as a function of temperature and switching frequency (SF).