

# RM-1000



## User's Manual

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# General Operation

## INSTALLATION

### Mounting

1. Tape or temporarily glue the mounting template on the panel in the desired location.
2. Drill four screw holes with a #23 bit (5/32").
3. Drill or punch a 2" round or 0.6" x 1.5" rectangular hole for the terminal connections.
4. Attach the RM-1000 to the panel using 4 #6 x 1/2" screws. Tighten the screws to no more than 10 in-lbs.
5. Attach the wires to the terminal block and plug into the connector. (See the Wiring section.)

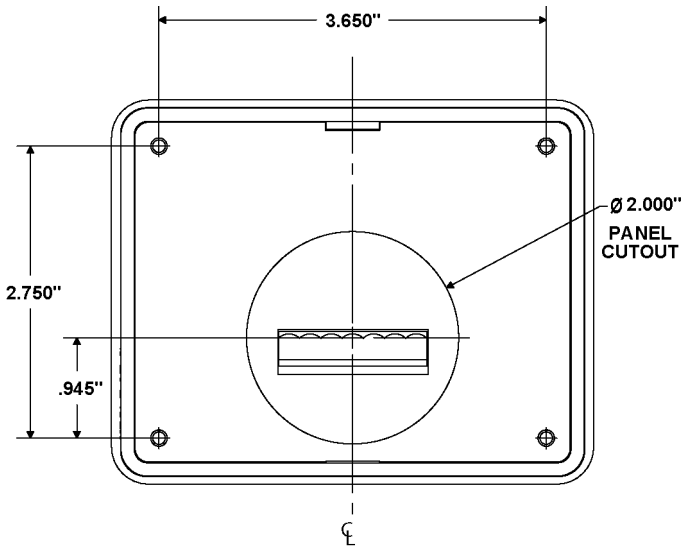
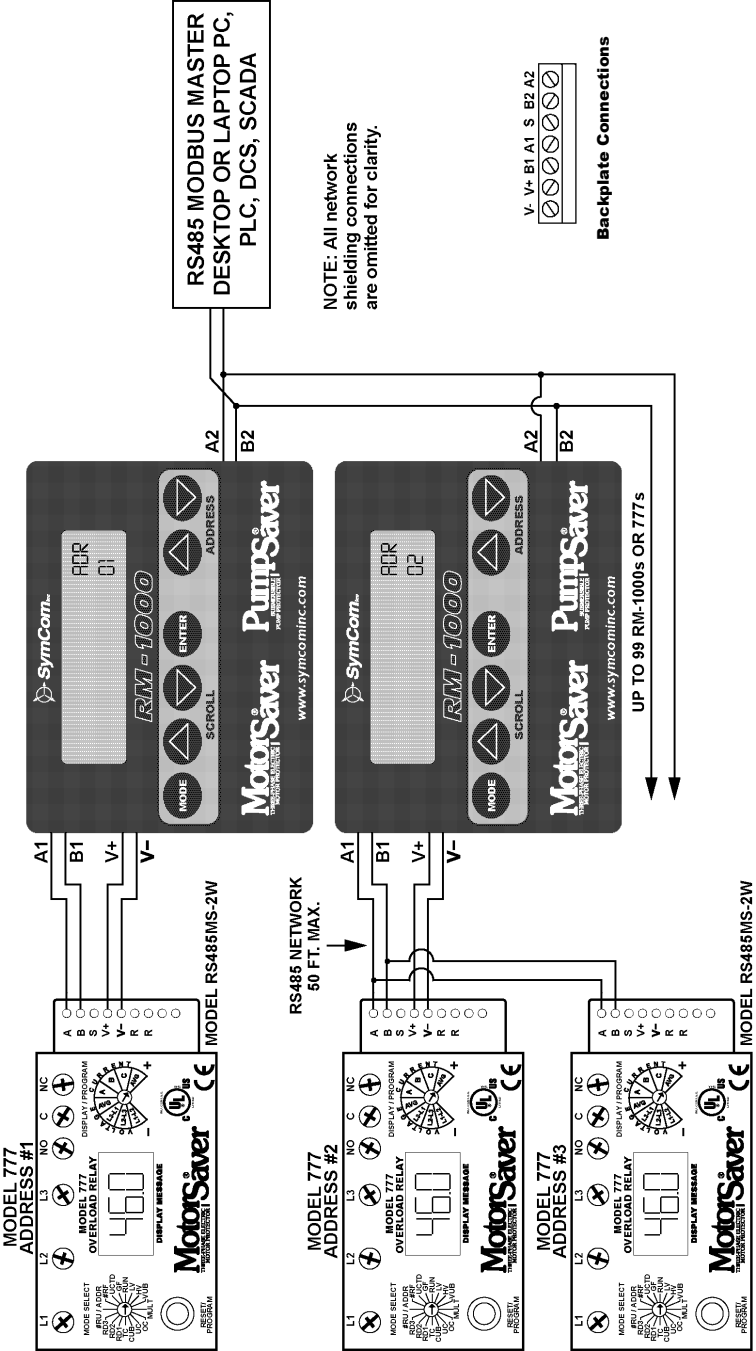


Figure 1. Mounting Diagram

# Wiring



## Quick Start

Setup of a new or existing RM-1000 can be achieved very quickly by using the **Learn Nodes** and the **Delete All Nodes** features. The **Learn Nodes** feature can be used to scan all 99 addresses to find all existing addresses. The **Delete All Nodes** feature is helpful when many or all of the addresses have changed, or the installer is not sure which address(es) no longer exist.

## New RM-1000 Installation

1. Apply power to all MotorSaver<sup>®</sup> and/or PumpSaver<sup>®</sup> relays to be monitored.
2. Set a different address into each MotorSaver<sup>®</sup> or PumpSaver<sup>®</sup> to be monitored by the RM-1000.
3. Enter **Learn Mode**.
  - 3.1. Press ENTER at the **45\_Learn Network** submenu.
  - 3.2. Scroll to answer yes (451\_Confirm ?Yes) and press ENTER.
  - 3.3. Allow the RM-1000 to scan all 99 addresses. The RM-1000 will display the found nodes as they are located and will display the number of found nodes when complete.
  - 3.4. Press ENTER to leave this screen.
4. Go to **Real Time** mode.
  - 4.1. Press MODE to get to the **Main Menu**.
  - 4.2. Press scroll down to get to the **1\_REAL TIME** submenu selection.
  - 4.3. Press ENTER.
5. Scroll through the addresses, by pressing the up or down address key, to verify the RM-1000 found all the installed devices.
6. If all the installed devices were found you are ready for normal operations. If some devices are missing, manually set up the addresses in question and/or check the wiring and power to the device(s) in question.

## Keypad Buttons



**MODE Button** – switches to the previous mode or menu. It can be thought of as a *previous*, *escape*, or *back* button.



**ENTER Button** – moves to the selected mode, chooses the selected option, or saves a setup parameter



**SCROLL**

**SCROLL Up/down** – moves up or down through a set of menu options or to increment or decrement a programmable setpoint.



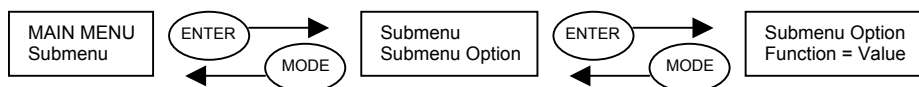
**ADDRESS**

**ADDRESS Up/down** – moves up or down through the addresses on the network.

## Keypad Programming

### **Fundamentals**

The programming structure is a series of menus and submenus followed by a series of programming options. The menus, submenus, and options are navigated by using a four-button interface as shown in Figure 2.



**Figure 2. Menu Navigation**

### **Changing Values**

The function parameters or setpoints are changed using the SCROLL up/down buttons. When the current value of a parameter is shown an "=" sign is used. When the value is changed, the "=" changes to "?." When the new value is saved by pressing ENTER, the "?" changes to "=."

### **Enable Network Programming**

The overload relay can have network programming disabled from a PC, PLC, or other device. If the network programming is disabled, the setpoints cannot be changed until the overload relay has the network programming enabled. This can be done from the RM-1000. To enable network programming, go to 3\_CNTRL MENU, press and hold the MODE button, then press both the SCROLL up and down buttons. The screen should display "Network Unlock Command Sent." Network programming cannot be disabled from the RM-1000.

# Main Menu Options / Modes

The main menu has four options: **1\_REAL TIME**, **2\_SET POINTS**, **3\_CNTRL MENU** and **4\_SETUP MENU**. A new RM-1000 will startup locked into the **MAIN MENU** at the **4\_SETUP MENU**. The RM-1000 will not leave the setup menu/mode until at least one node is programmed.

After a node has been programmed, the RM-1000 will start up in the **1\_REAL TIME** menu/mode. To access the other menus press the MODE button.

## 1\_REAL TIME Mode

### Run Information

In the REAL TIME mode, the user can scroll through a list of run information. The SCROLL down button moves the operator down through the list of real time data. The SCROLL up button moves the operator up through the list.

### Fault Information

The Fault Status screen is used to display both pending and existing faults. Faults that are in the process of timing down a trip delay will be described as “pending.” Faults that have caused the relay to trip and are in the process of timing down the restart delay are described as “tripped.” The Fault Status screen is a two-line screen. The Fault History screens, Flt1-Flt4, are one-line screens showing the last four trip faults (see Table 5).

Model 777	Model 777-KW/HP	Model 601
Vavg= 456 Axx Iavg = 10.00 I1 = 10.00 I2 = 10.00 I3 = 10.00 Iub = 0% Vab = 456 Vbc = 456 Vac = 456 Vub = 0% GF = 0.00 Hours = 33 PwrFr = 1 RD1 = 0s RD2 = 0m RD3 = 0m Flt1 [UndCur] Flt2 [OvrCur] Flt3 [Clear] Flt4 [Clear] Fault Status	Vavg = 456 Axx Iavg = 10.00 I1 = 10.00 I2 = 10.00 I3 = 10.00 Iub = 0% Vab = 456 Vbc = 456 Vac = 456 Vub = 0% GF = 0.00 Hours = 33 PwrFr = 1 KW = 100 RD1 = 0s RD2 = 0m RD3 = 0m Flt1 [Low kW] Flt2 [OvrCur] Flt3 [Clear] Flt4 [Clear] Fault Status	Vavg = 456 Axx Vab = 456 Vbc = 456 Vac = 456 Vub = 0% Freq = 60.0 RD1 = 0s RD2 = 0m Flt1 [Hi Vlt] Flt2 [Lo Frq] Flt3 [Clear] Flt4 [Clear]
		Model 77C
		V = 456 Axx I = 10.00 Hours = 33 RD1 = 0s RD2 = 0m RD3 = 0m Flt1 [UndCur] Flt2 [OvrCur] Flt3 [Clear] Flt4 [Clear]

Table 1. REAL TIME Mode Screens



<b>Abbr.</b>	<b>Description</b>	<b>Abbr.</b>	<b>Description</b>
Vavg	Average Voltage	GF	Ground Fault
Iavg	Average Current	Hours	Run Hours
I1	Phase 1 Current	PwrFr	Power Factor
I2	Phase 2 Current	kW	Power
I3	Phase 3 Current	Freq	Frequency
Iub	Current Unbalance	RD1	Rapid-Cycle Timer
Vab	Voltage A-B	RD2	Cool Down Timer
Vbc	Voltage B-C	RD3	Dry-Well Recovery Timer
Vac	Voltage A-C	Flt#	Last Faults
Vub	Voltage unbalance		

**Table 2. REAL TIME Mode Abbreviations**

<b>Abbr.</b>	<b>Description</b>	<b>Abbr.</b>	<b>Description</b>
OC	Overcurrent	VUB	Voltage Unbalance
ISP	Current Single Phase	HV	High Voltage
VSP	Voltage Single Phase	LV	Low Voltage
CUB	Current Unbalance	GF	Ground Fault
RP	Reverse Phase	HF	High Frequency
UC	Undercurrent	LF	Low Frequency
LPr	Low Power		

**Table 3. Pending Fault Abbreviations**

<b>Abbr.</b>	<b>Description</b>	<b>Abbr.</b>	<b>Description</b>
HV	High Voltage	CUB	Current Unbalance
LV	Low Voltage	OC	Overcurrent
CF	Contactora Failure	UC	Undercurrent
RP	Reverse Phase	HF	High Frequency
SP	Single Phase	LF	Low Frequency
GF	Ground Fault	LPr	Low Power
Hot	High Motor Temp.		

**Table 4. Tripped Fault Abbreviations**

<b>Abbr.</b>	<b>Description</b>	<b>Abbr.</b>	<b>Description</b>
Hi Vlt	High Voltage	C Unbl	Current Unbalance
Lo Vlt	Low Voltage	OvrCur	Overcurrent
Cnt Fl	Contactora Failure	UndCur	Undercurrent
Rev Ph	Reverse Phase	Hi Frq	High Frequency
Sng Ph	Single Phase	Lo Frq	Low Frequency
Grnd F	Ground Fault	Low Pr	Low Power
Hot	High Motor Temp.		

**Table 5. Last Fault Abbreviations**

## 2\_SET POINTS

In the SET POINTS mode, the user can scroll through a list of setpoints for each installed device. The SCROLL up/down buttons are used to move through the list. The ADDRESS up/down buttons are used to change devices. If change setpoints is enabled in the Setup menu, the user can change the setpoint by pressing ENTER. Then, the SCROLL button is used to change the value and ENTER is used to accept the value.

777	777-KW/HP	77C
2a LV	2a LV	2a LV
2b HV	2b HV	2b HV
2c VUB	2c VUB	2d MULT
2d MULT	2d MULT	2e OC
2e OC	2e OC	2f UC
2f UC	2g IUB	2h TC
2g IUB	2h TC	2i RD1
2h TC	2i RD1	2j RD2
2i RD1	2j RD2	2k RD3
2j RD2	2k RD3	2l #RU
2k RD3	2l #RU	2m #RO
2l #RU	2m #RF	2n UCTD
2m #RF	2n * UCTD	
2n UCTD	2o GF	
2o GF	2p LKW	

\* UCTD can only be changed from the network. KWS does not apply to the RM-1000.

601
2a LV
2b HV
2c VUB
2i RD1
2j RD2
2m #RF

Table 6. Setpoint Screens

<b>Abbr.</b>	<b>Description</b>	<b>Abbr.</b>	<b>Description</b>
LV	Low Voltage	RD1	Rapid-Cycle Timer
HV	High Voltage	RD2	Cool-Down Timer
VUB	Voltage Unbalance	RD3	Dry-Well Recovery Timer
MULT	Current Multiplier	#RU	Number of Restarts after UC Faults
OC	Overcurrent	#RF	Number of Restarts after Faults
UC	Undercurrent	UCTD	Undercurrent Trip Delay
IUB	Current Unbalance	LKW	Low Power
TC	Trip Class	GF	Ground Fault
HF	High Frequency	TD1	Trip Delay for Voltage/Frequency Faults
LF	Low Frequency	TD2	Trip Delay for Single-Phasing Faults

**Table 7. Setpoint Screen Abbreviations**

### **3\_CNTRL MENU**

The CONTROL submenus are used to reset a tripped relay, send an OFF command to a relay, clear the last fault memory and to clear the run-hour counter.

After pressing ENTER to select a control option, the RM-1000 will ask for confirmation before executing the command. Press the SCROLL up or down button to change the response to yes and press ENTER to confirm the request.

#### **31\_Set OFF**

Press ENTER at this menu option to send an OFF command to a relay. After confirming the request an OFF command will be sent. The MotorSaver<sup>®</sup> or PumpSaver<sup>®</sup> will remain in the off state (relay de-energized) until the reset button is pressed, or a RESET command is sent from the RM-1000 or the host network.

#### **32\_Reset**

Press ENTER at this menu option to send a RESET command. The relay will be reset after confirming the request.

#### **33\_Clear LF (Clear Last Fault)**

Press ENTER at this menu option to clear the last fault memory location in the relay, provided the relay supports the clear last fault function. Placing a CLEAR in the last fault memory location can be a helpful tool in system troubleshooting, ending any uncertainty about whether the last fault is new or very old.

#### **34\_Clear Hrs (Clear Run Hours)**

Press ENTER at this menu option to clear the accumulated run hours, provided the relay supports the run hour feature. The run hour counter will be cleared when the command is confirmed.

## 4\_SETUP MENU

### 41\_Gen Options

#### 411\_Unl Set point

The unlock setpoint option allows enabling or disabling network programming of the setpoints of the relays on the network. If disabled, the operator can only view the setpoints of the relay, not change them.

#### 412\_A/S Rate

The Auto Scroll feature allows the RM-1000 REAL TIME mode screens to automatically scroll from one screen to the next at a desired interval. The intervals range from 0.5-127.5 seconds at 0.5-second intervals. Setting the delay to OFF disables the Auto Scroll feature.

#### 413\_A/S KeyDelay

If the Auto Scroll feature is enabled and one of the buttons on the keypad are pressed, the Auto Scroll feature is temporarily disabled for the amount of time set in the Auto Scroll Key Delay. The delay range is 0.5-127.5 seconds at 0.5 second intervals. Setting the delay to OFF disables the Auto Scroll feature.

#### 414\_Reference

This menu option displays the firmware version number.

### 42\_Edit Nodes

#### 4212\_Model

Options: 777, 777-KW/HP, 77C, 601

777- All Model 777 relays except Model 777-KW/HP

777-KW/HP- All Model 777-KW/HP relays

77C- All single-phase relays, Model 77C and 777-HVR-SP

601- all Model 601 voltage monitors

This menu option is only needed for older model 601 relays. The RM-1000 is able to recognize the model of all compatible relays except older model 601s. This setting will automatically be overridden by the RM-1000 if it is programmed incorrectly.

#### 4213\_UC Alarm

Treat undercurrent as alarm if enabled.

## 43\_Comm Settings

The communication settings can be set to standard or custom. Standard is the default setting. The custom slave communication settings are included for forward compatibility. The existing product line only supports the standard communication settings of 9600 baud, even parity and one stop bit (9600,E,1).

### 431\_Slave Comm

Selecting "Cst" (Custom) allows the individual setup of baud rate, parity and stop bits for the slave port.

#### 4311\_Slave Baud

Slave port baud rate. 9600 is the default.

Options: 1200, 2400, 9600, 14400, 19200

#### 4312\_Slave Prty

Slave port parity. Even is the default.

Options: E (Even), O (Odd), N (None)

#### 4313\_Slave Stop

Number of Stop bits for the slave port. One is the default.

Options: 0, 1, 2

### 432\_Host Comm

The communication settings can be set to standard or custom. Standard is the default setting which sets the communication parameters to 9600 baud, even parity and one stop bit (9600,E,1).

#### 4321\_Host Baud

Host port baud rate - 9600 is the default.

Options: 1200, 2400, 9600, 14400, 19200, 28800

#### 4322\_Host Parity

Host port parity - even is the default.

Options: E (Even), O (Odd), N (None)

#### 4323\_Host Stop

Number of Stop bits for the host port - One is the default.

Options: 0, 1, 2

#### 44\_Del All Nodes

This function deletes all programmed nodes from the RM-1000 memory. This feature is useful when moving an RM-1000 or making many changes to the system.

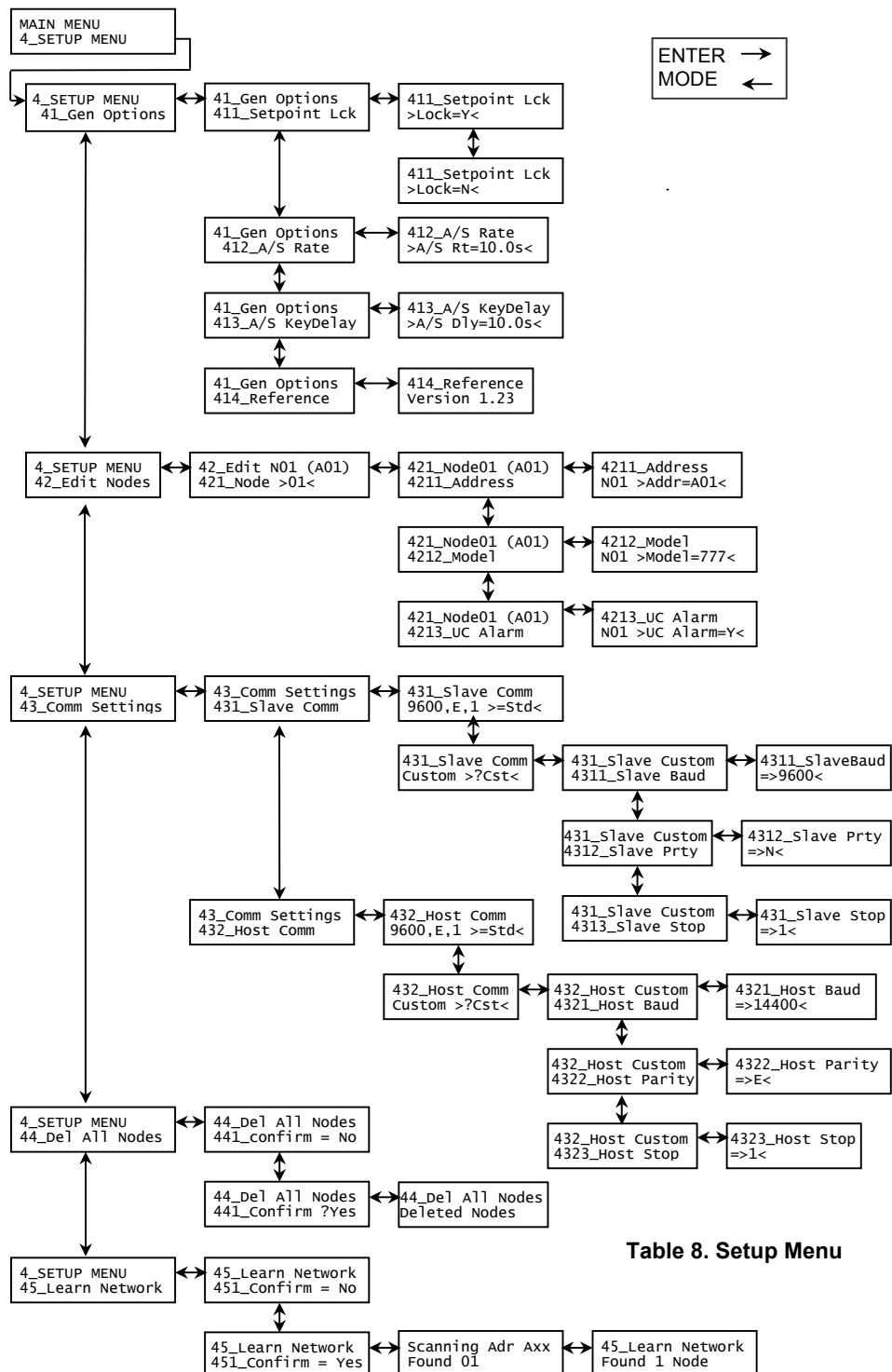
**NOTE:** If all nodes are deleted, the RM-1000 will remain in the 4\_SETUP MENU until at least one node is programmed.

#### 45\_Learn Network

This function scans all network addresses from 1-99 in search of installed equipment. Any device that is found is programmed into the next available node. Devices already programmed into the RM-1000 will not be lost.

This function can be aborted at any time by pressing the MODE or ENTER buttons. The found nodes will be programmed. This allows the scan to be stopped as soon as all existing nodes have been found.

If the model can be read, no further programming is necessary. Only older Model 601 voltage monitors need to have the model programmed in submenu 4212.



**Table 8. Setup Menu**

## RM-1000 SPECIFICATIONS

<b>Power</b>	
Nominal Power Supply Voltage Rating	12-24VAC or VDC (isolated power source with maximum 4A overcurrent protection)
Max Current	100mA
<b>Environment</b>	
Protection Class	NEMA 3R, IP44
Operating Temperature	-20° to 70°C
Storage Temperature	-40° to 80°C
Humidity	85% Non-condensing
<b>Enclosure</b>	
Dimensions	4.5" L x 3.2" W X 0.9" D
Weight	6 oz.
Material	Black Polycarbonate
UV Exposure w/o degradation	2000 hrs
Keypad Mechanical Lifetime	200,000 cycles
Keypad Material	Polyester
Panel Thickness	.03" min.
Terminal	Depluggable, Max Torque 3 in.-lbs.
<b>Electrical Noise Immunity</b>	
Electrostatic discharge	IEC 61000-4-2, Level 3 (6kV contact, 8kV air discharge)
Electromagnetic field	IEC 61000-4-3, Level 3 (10 V/m)
Fast transient burst	IEC 61000-4-4, Level 4+ (4kV on cable clamp)
Surge	IEC 61000-4-5, 24V supply, Level 1 (±500V) RS-485 & Reset Lines, Level 2 (±1kV)
Conducted RF	IEC 61000-4-6, Level 3+ (30 V <sub>rms</sub> )
Voltage dips & interruptions	SEMI F47
<b>Agency Approvals</b>	
UL	UL 508
CE	IEC 60947-1, IEC 1131-2
<b>Communications</b>	
Baud Rate	1200 - 19200
Protocol	Modbus RTU
Serial Interface	RS-485
Range	50 ft., 4000 ft. with separate supply